# **HLC2705**

### **Encoder Detector**

#### **FEATURES**

- Side-looking plastic package TTL/LSTTL/CMOS compatible
- On-chip quadrature logic which provides tach and direction outputs
- Linear or rotary encoder applications
- Resolution to 0.018 in.(.457 mm)
- Sensitivity versus temperature compensation
- Mechanically and spectrally matched to SEP8506/8526 and SEP8706 infrared emitting diodes



#### **DESCRIPTION**

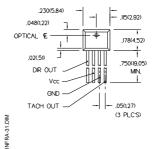
The HLC2705 detector is designed for use as an optical interrupter to sense speed and direction of mechanical motion. Applications include rotary and linear encoders; the device is especially well suited for the encoding function in an optical mouse. The detector is a monolithic IC, consisting of two narrow adjacent photodiodes, amplifier stages, and quadrature logic which provides two outputs. One is a fixed duration, low level active tachometer (counting) pulse. It is generated whenever the "A" channel illumination passes through the threshold level. The second is a direction output which is set to a logic high or a logic low depending upon which channel is illuminated first. The sensor also has sensitivity compensation circuitry for the output power versus temperature characteristic of an IRED. The IC is encapsulated in a molded, unlensed black plastic package which is transmissive to IR energy, yet provides shielding from visible light.

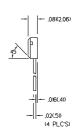
The tachometer output is an NPN collector, internally connected to  $V_{CC}$  through a 10 k $\Omega$  (nominal) resistor. The direction output is a totem-pole configuration. Both are capable of directly driving TTL loads.

The tachometer pulse is generated at both the increasing and decreasing illumination thresholds of the "A" channel, resulting in two tachometer pulses for each mechanical period of the interrupter. The HLC2705 is designed to work with a mechanical period as small as 0.036 in.(0.914 mm), providing resolution to 0.018 in.(0.457 mm).

# OUTLINE DIMENSIONS in inches (mm)

±0.005(0.12) Tolerance 3 plc decimals 2 plc decimals ±0.020(0.51)





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### **ELECTRICAL CHARACTERISTICS** (-40°C to +85°C unless otherwise noted)

PARAMETER	SYMBOL	MIN	TYP	MAX	UNITS	TEST CONDITIONS
Operating Supply Voltage	Vcc	4.5		5.5	V	
Turn-on Threshold Irradiance	E <sub>eT</sub> (+)				mW/cm <sup>2</sup>	V <sub>CC</sub> =5 V, T <sub>A</sub> =25°C
HLC2705-001		0.05		2.0		(1)
Supply Current	Icc			12.0	mA	V <sub>CC</sub> =5.25 V
Tach Output, inactive	V <sub>OH,TACH</sub>	4.5			V	$V_{CC}=5 V, I_{OH}=0$
Tach Pulse Level, active	V <sub>OL,TACH</sub>			0.4	V	$V_{CC}=5 V$ , $I_{OL}=1.6 mA$
Direction Output, B leads A	V <sub>OH,DIR</sub>	2.4			V	V <sub>CC</sub> =5 V, I <sub>OH</sub> =10 μA
Direction Output, A leads B	V <sub>OL,DIR</sub>			0.4	V	$V_{CC}=5 V$ , $I_{OL}=1.6 mA$
Tach Pulse Width	T <sub>PW</sub>	3.0		20	μs	$V_{CC}$ =5 V, $I_{OL}$ =1.6 mA
Operate Point Temperature Coefficient			-0.76		%/°C	Emitter @ Constant Temperature

- Notes
  The radiation source is an IRED with a peak wavelength of 880 nm.
  It is recommended that a bypass capacitor, 0.1 μf typical, be added between V<sub>CC</sub> and GND near the device in order to stabilize power supply line.

# **ABSOLUTE MAXIMUM RATINGS**

(25°C Free-Air Temperature unless otherwise noted)

Duration of Output Short to V<sub>CC</sub> or Ground 1.0 sec. -40°C to 85°C Operating Temperature Range Storage Temperature Range -40°C to 85°C 240°C Soldering Temperature (5 sec)

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## OUTPUT TIMING DIAGRAM

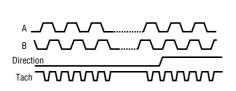
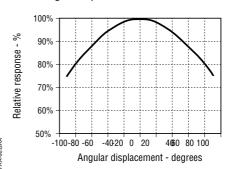
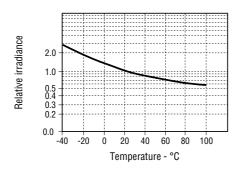


Fig. 1 Responsivity vs Angular Displacement



INFRA-12.CIR INFRA-66.GRA

Fig. 2 Threshold Irradiance vs Temperature



INFRA-60.GRA

All Performance Curves Show Typical Values