# Eaton 185765



Catalog Number: 185765

Eaton DC1 Variable frequency drive, 115 V AC, single-phase, 2.3 A, 0.37 kW, IP20/NEMA 0, FS1 DC1-1D2D3NN-A20CE1

# General specifications

**Product Name** 

Eaton DC1 Variable frequency drive

**EAN** 

4015081812646

**Product Height** 

184 mm

**Product Weight** 

1.2 kg

Catalog Number

185765

Product Length/Depth

124 mm

**Product Width** 

81 mm

Certifications

CE EAC

IEC/EN61800-3

Safety requirements: IEC/EN 61800-5-1

UL

**UL 508C** 

UL File No.: E172143 CSA-C22.2 No. 14

Certified by UL for use in Canada

CUL

IEC/EN61800-5

Specification for general requirements:

IEC/EN 61800-2 RoHS, ISO 9001 UkrSEPRO

RCM

IEC/EN 61800-3

UL report applies to both US and

Canada

UL Category Control No.: NMMS,

NMMS7



## Features & Functions

## **Features**

Parameterization: drivesConnect

Parameterization: drivesConnect mobile (App)

Parameterization: Fieldbus Parameterization: Keypad

#### Fitted with:

PC connection IGBT inverter

7-digital display assembly

Internal DC link
Control unit

Additional PCB protection

## General

## Cable length

100 m, screened, with motor choke, maximum permissible,

Motor feeder

50 m, screened, maximum permissible, Motor feeder75 m, unscreened, maximum permissible, Motor feeder

150 m, unscreened, with motor choke, maximum permissible,

Motor feeder

## Communication interface

CANopen®, built in OP-Bus (RS485), built in Modbus RTU, built in SmartWire-DT, optional

# Connection to SmartWire-DT

Yes

In conjunction with DX-NET-SWD3 SmartWire DT module

## Degree of protection

IP20

**NEMA Other** 

## Frame size

FS1

## Mounting position

Vertical

#### Product category

Variable frequency drives

# Protection

Finger and back-of-hand proof, Protection against direct contact (BGV A3, VBG4)

#### Protocol

Other bus systems

EtherNet/IP

MODBUS

CAN

#### Radio interference class

Optional external radio interference suppression filter for longer motor cable lengths and for use in different EMC environments

# Suitable for

Branch circuits, (UL/CSA)

# Climatic environmental conditions

## Altitude

Above 1000 m with 1 % derating per 100 m

Max. 4000 m

Ambient operating temperature - min

-10 °C

Ambient operating temperature - max

50 °C

Ambient operating temperature at 150% overload - min

-10 °C

Ambient operating temperature at 150% overload - max

50 °C

Ambient storage temperature - min

-40 °C

Ambient storage temperature - max

60 °C

## Climatic proofing

< 95 average relative humidity (RH), no condensation, no corrosion

# Main circuit

Efficiency

95 % (η)

Heat dissipation capacity Pdiss

0 W

Input current ILN at 150% overload

7.8 A

Leakage current at ground IPE - max

4.8 mA

Mains switch-on frequency

Maximum of one time every 30 seconds

Mains voltage - min

110 V

Mains voltage - max

115 V

Operating mode

Sensorless vector control (SLV)

U/f control

Speed control with slip compensation

BLDC motors

PM motors

Synchronous reluctance motors

Output frequency - min

0 Hz

Output frequency - max

500 Hz

Output voltage (U2)

230 V AC, 3-phase

Overload current IL at 150% overload

3.45 A

Rated control supply voltage

10 V DC (Us, max. 10 mA)

Rated frequency - min

48 Hz

Rated frequency - max

62 Hz

Rated operational current (le)

2.3 A at 150% overload (at an operating frequency of 16 kHz and an ambient air temperature of +50 °C)

## Rated operational voltage

115 V AC, 1-phase

#### Resolution

0.1 Hz (Frequency resolution, setpoint value)

## Short-circuit protection rating

15 A, UL (Class CC or J), Safety device (fuse or miniature circuit-breaker), Power Wiring

## Starting current - max

175 %, IH, max. starting current (High Overload), For 2.5 seconds every 600 seconds, Power section

#### Supply frequency

50/60 Hz

## Switching frequency

8 kHz, 4 - 32 kHz adjustable (audible), fPWM, Power section, Main circuit

## System configuration type

AC supply systems with earthed center point

## Voltage rating - max

120 V

# Motor rating

Assigned motor current IM at 110/120 V, 60 Hz, 150% overload 2.2 A

Assigned motor current IM at 115 V, 50 Hz, 150% overload 2 A

Assigned motor current IM at 220 - 240 V, 60 Hz, 150% overload 2.2 A

Assigned motor current IM at 230 V, 50 Hz, 150% overload 2 A

Assigned motor current IM at 400 V, 50 Hz, 150% overload 2 A

Assigned motor current IM at 440 - 480 V, 60 Hz, 150% overload 2.2 A

Assigned motor power at 115/120 V, 60 Hz, 1-phase 0.5 HP

Assigned motor power at 230/240 V, 60 Hz, 1-phase 0.5 HP

Assigned motor power at 460/480 V, 60 Hz 0.5 HP

Assigned motor power at 460/480 V, 60 Hz, 3-phase 0.5 HP

# Braking function

## Braking torque

 $\mbox{Max.}\ 100\ \%$  of rated operational current le, variable, DC - Main circuit

Max. 30 % MN, Standard - Main circuit

# Control circuit

Number of inputs (analog)

2 (parameterizable, 0 - 10 V DC, 0/4 - 20 mA)

Number of inputs (digital)

4 (parameterizable, 10 - 30 V DC)

Number of outputs (analog)

1

Number of outputs (digital)

1

Number of relay outputs

1 (parameterizable, N/O, 6 A (250 V, AC-1) / 5 A (30 V, DC-1))

## Design verification

Resources

Equipment heat dissipation, current-dependent Pvid

18.5 W

Heat dissipation capacity Pdiss

0 W

Heat dissipation per pole, current-dependent Pvid

0 W

Rated operational current for specified heat dissipation (In)

7 A

Static heat dissipation, non-current-dependent Pvs

0 W

Heat dissipation details

Operation (with 150 % overload)

10.2.2 Corrosion resistance

Meets the product standard's requirements.

10.2.3.1 Verification of thermal stability of enclosures

Meets the product standard's requirements.

10.2.3.2 Verification of resistance of insulating materials to normal heat

Meets the product standard's requirements.

10.2.3.3 Resist. of insul. mat. to abnormal heat/fire by internal elect. effects

Meets the product standard's requirements.

10.2.4 Resistance to ultra-violet (UV) radiation

Meets the product standard's requirements.

10.2.5 Lifting

Does not apply, since the entire switchgear needs to be evaluated.

10.2.6 Mechanical impact

Does not apply, since the entire switchgear needs to be evaluated.

10.2.7 Inscriptions

Meets the product standard's requirements.

10.3 Degree of protection of assemblies

Does not apply, since the entire switchgear needs to be evaluated.

10.4 Clearances and creepage distances

Meets the product standard's requirements.

10.5 Protection against electric shock

Does not apply, since the entire switchgear needs to be

Application notes

Operating Single Phase Motors

Low Temperature Applications

I/O Configuration

PI controller

Operating Permanent Magnet and Brushless DC Motors

DX-COM-STICK3\_Connection

**Conformal Coating** 

Motor data - Motor Protection - V/f curves Slip Compensation

Dependency of the output current on switching frequency and ambient

temperature

The OP System Bus - Parameterizing - Control

Fire Mode

Set Point Setting

Connecting drives to generator supplies

Update DX-COM-STICK3

Starting, Stopping and Operation

How does the internal motor protection work?

Electromagnetic compatibility (EMC)

Access to Parameter Levels 2 + 3 Parameter Lock - Load Default

**Brochures** 

eaton-powerxl-variable-frequency-drives-dc1-da1-brochure-

br040001en-en-us.pdf

DA-SW-drivesConnect

Catalogs

Product Range Catalog Drives Engineering

Declarations of conformity

DA-DC-00004555.pdf

DA-DC-00004552.pdf

DA-DC-00003964.pdf

DA-DC-00004184.pdf

Drawings

eaton-frequency-inverter-dimensions-016.eps

eaton-frequency-inverter-dimensions-017.eps

eaton-frequency-inverter-3d-drawing-003.eps

eCAD model

DA-CE-ETN.DC1-1D2D3NN-A20CE1

Installation instructions

IL04020009Z

evaluated.

## 10.6 Incorporation of switching devices and components

Does not apply, since the entire switchgear needs to be evaluated.

#### 10.7 Internal electrical circuits and connections

Is the panel builder's responsibility.

#### 10.8 Connections for external conductors

Is the panel builder's responsibility.

#### 10.9.2 Power-frequency electric strength

Is the panel builder's responsibility.

## 10.9.3 Impulse withstand voltage

Is the panel builder's responsibility.

## 10.9.4 Testing of enclosures made of insulating material

Is the panel builder's responsibility.

## 10.10 Temperature rise

The panel builder is responsible for the temperature rise calculation. Eaton will provide heat dissipation data for the devices.

## 10.11 Short-circuit rating

Is the panel builder's responsibility. The specifications for the switchgear must be observed.

## 10.12 Electromagnetic compatibility

Is the panel builder's responsibility. The specifications for the switchgear must be observed.

#### 10.13 Mechanical function

The device meets the requirements, provided the information in the instruction leaflet (IL) is observed.

#### Installation videos

PowerXL Variable Frequency Drives DC1 and DA1 - EN

Video PowerXL DA1

## Manuals and user guides

eaton-canopen-communication-manual-for-variable-frequency-drivesvariable-speed-starters-da1-db1-dc1-de11-mn040019-en-us.pdf

MN040059 EN

MN040022\_EN

MN040018\_EN

MN040003 EN

#### mCAD model

DA-CS-dc1\_fs1

DA-CD-dc1\_fs1

#### Multimedia

Looking for variable frequency drives DC1 and DA1 which can be used in harsh environments?

#### **Product notifications**

eaton-drives-ecodesign-directive-mz040046en-en.pdf



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