



Loadmonitors - GAMMA series

Digital setting

Multifunction

Temperature monitoring of the motor winding

Fault latch

Recognition of disconnected load

Suitable for VFI (10 to 100Hz)

Supply voltage selectable via power modules

2 change over contacts

Width 45mm

Industrial design



Technical data

1. Functions

True power monitoring for 1- or 3-phase loads with adjustable switching thresholds, adjustable start-up suppression time, separately adjustable tripping delay, selectable fault latch and temperature monitoring of the motor winding with max. 6 PTC.

OVER	Overload monitoring
OVER+I=0 ON	Overload monitoring and recognition of disconnected load (relay ON or OFF)
UNDER	Underload monitoring
UNDER+I=0 ON	Underload monitoring and recognition of disconnected load (relay ON or OFF)
2MIN	Minimum monitoring
2MIN+I=0 ON	Minimum monitoring and recognition of disconnected load (relay ON or OFF)
2MAX	Maximum monitoring
2MAX+I=0 ON	Maximum monitoring and recognition of disconnected load (relay ON or OFF)
WIN	Monitoring the window between MIN and MAX
WIN+I=0 ON	Monitoring the window between MIN and MAX and recognition of disconnected load (relay ON or OFF)
MAX/MIN	Maximum- and minimum monitoring
MAX/MIN+I=0 ON	Maximum- and minimum monitoring and recognition of disconnected load (relay ON or OFF)

2. Time ranges

	Adjustment range	
Start-up suppression time (t2):	0s	100s
Tripping delay (Del_A / Del_B):	0,1s	50s

3. Indicators

Display specifications - see supplementary sheet!

4. Mechanical design

Self-extinguishing plastic housing, IP rating IP40
Mounted on DIN-Rail TS 35 according to EN 60715
Mounting position: any
Shockproof terminal connection according to VBG 4 (PZ1 required), IP rating IP20
Tightening torque: max. 1Nm
Terminal capacity:
1 x 0.5 to 2.5mm² with/without multicore cable end
1 x 4mm² without multicore cable end
2 x 0.5 to 1.5mm² with/without multicore cable end
2 x 2.5mm² flexible without multicore cable end

5. Input circuit

Supply voltage:
12 to 500V AC
terminals A1-A2 (galvanically separated)
selectable via power module type TR3
Tolerance:
according to specification of power module
Rated frequency:
according to specification of power module
Rated consumption:
3.5VA (3W)
Duration of operation:
100%
Reset time:
500ms
Ripple and noise:
-
Drop-out voltage:
>30% of the supply voltage

Overvoltage category: III (in accordance with IEC 60664-1)
Rated surge voltage: 4kV

6. Output circuit

2 potential free change over contacts
Rated voltage: 250V AC
Switching capacity: 750VA (3A / 250V AC)
If the distance between the devices is less than 5mm!
Rated voltage: 1250VA (5A / 250V AC)
If the distance between the devices is greater than 5mm!
Fusing: 5A fast acting
Mechanical life: 20 x 10⁶ operations
Electrical life: 2 x 10⁵ operations
at 1000VA resistive load
Switching capacity: max. 60/min at 100VA resistive load
max. 6/min at 1000VA resistive load
(in accordance with IEC 60947-5-1)
Overvoltage category: III (in accordance with IEC 60664-1)
Rated surge voltage: 4kV

7. Measuring circuit

Measuring range (Range): 2.5kW and 10kW
Wave form
AC Sinus: 10 to 400Hz
Sinus weighted PWM: 10 to 100Hz
Measuring input voltage: terminals L1-L2-L3
1-phase loads: 0 to 480V AC
3-phase loads: 3~ 0 to 480/277V
Overload capacity:
1-phase loads: 550V AC
3-phase loads: 3~ 550/318V
Input resistance: 1.25MΩ
Measuring input current: terminals i-k
Measuring range 2.5kW: 0.15 to 6A
Measuring range 10kW: 0.3 to 12A (for I>8A distance >5mm)
Overload capacity: 12A permanent
Input resistance: <10mΩ
Current transformer factor (Factor): 1-100
Switching thresholds Th:
Measuring range 2.5kW: 120W to 2490W
Measuring range 10kW: 480W to 9960W
Hysteresis: fixed 5% or adjustable
Temperature monitoring 9:
Terminals: T1-T2
Initial resistance: <1.5kΩ
Response value (Relais in on-position): ≥3.6kΩ
Release value (Relais in off-position): ≤1.8kΩ
Disconnection (short circuit thermistor): no
Measuring voltage T1-T2: ≤7.5V at R ≤4.0kΩ
(in accordance with EN 60947-8)
Overvoltage category: III (in accordance with IEC 60664-1)
Rated surge voltage: 4kV

Please note:

When the temperature monitoring isn't required the jumper must be set between the terminals T1-T2!

Technical data

8. Control contact Y (equipotential with measuring circuit)

Function:	Latch
Terminals:	Jumper Y1-Y2
Loadable:	no
Line length Y1-Y2:	max. 10m (twisted pair)
Control pulse length:	-
Reset:	normally closed contact in jumper Y1-Y2

9. Accuracy

Base accuracy:	±2% of upper range value
Base accuracy left:	±2% of upper range value
Frequency response:	±0,025% / Hz
Adjustment accuracy:	-
Repetition accuracy:	±2%
Voltage influence:	-
Temperature influence:	≤0,02% / °C

10. Ambient conditions

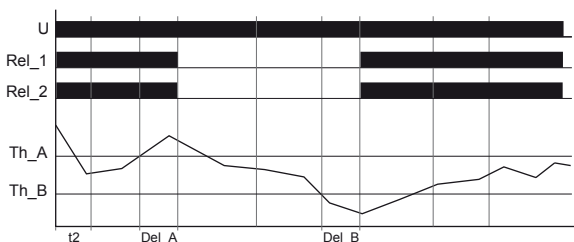
Ambient temperature:	-25 to +55°C (in accordance with IEC 60068-1) -25 to +40°C (in accordance with UL 508)
Storage temperature:	-25 to +70°C
Transport temperature:	-25 to +70°C
Relative humidity:	15% to 85% (in accordance with IEC 60721-3-3 class 3K3)
Pollution degree:	3 (in accordance with IEC 60664-1)
Vibration resistance:	10 to 55Hz 0.35mm (in accordance with IEC 60068-2-6)
Shock resistance:	15g 11ms (in accordance with IEC 60068-2-27)

Functions

When the supply voltage U is applied, the output relays Rel_1 and Rel_2 switches into on-position (state of output relay 11) and the set interval of the start-up suppression time (t₂) begins. During this period, changes of the measured true power don't affect the state of the output relays Rel_1 and Rel_2 (state of output relay 11).

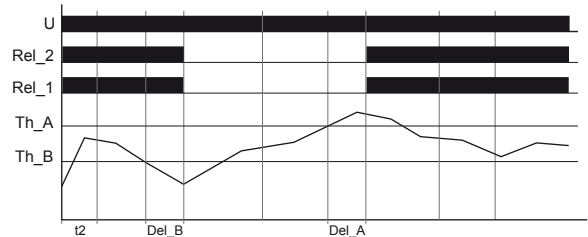
Overload monitoring (OVER)

The adjusted threshold Th_A must be greater than the adjusted threshold Th_B. When the measured true power exceeds the adjusted threshold Th_A, the set interval of the tripping delay (Del_A) begins. After the interval has expired, the output relays Rel_1 and Rel_2 switches into off-position (state of output relay 00). As soon as the measured true power falls below the adjusted threshold Th_B, the set interval of on delay (Del_B) begins. After the interval has expired, the output relays Rel_1 and Rel_2 switches into on-position again (state of output relay 11).



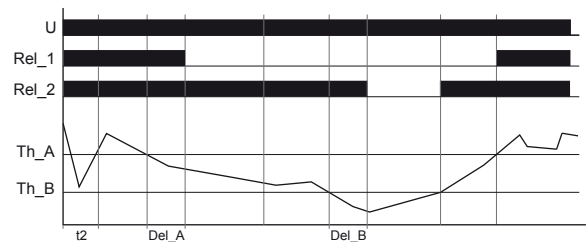
Underload monitoring (UNDER)

The adjusted threshold Th_A must be greater than the adjusted threshold Th_B. When the measured true power falls below the adjusted threshold Th_B, the set interval of the tripping delay (Del_B) begins. After the interval has expired, the output relays Rel_1 and Rel_2 switches into off-position (state of output relay 00). As soon as the measured true power exceeds the adjusted threshold Th_A, the set interval of on delay (Del_A) begins. After the interval has expired, the output relays Rel_1 and Rel_2 switches into on-position again (state of output relay 11).



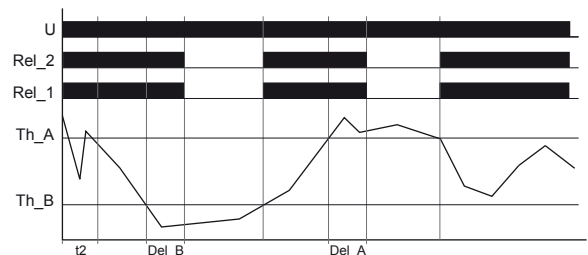
Minimum monitoring (2MIN)

The adjusted threshold Th_A must be greater than the adjusted threshold Th_B. When the measured true power falls below the adjusted threshold Th_B, the set interval of the tripping delay (Del_A) begins. After the interval has expired, the output relay Rel_1 switches into off-position (state of output relay 01). When the measured true power falls below the adjusted threshold Th_B, the set interval of the tripping delay (Del_B) begins. After the interval has expired, the output relay Rel_2 switches into off-position (state of output relay 00). As soon as the measured true power exceeds the corresponding threshold (Th_A or Th_B), the output relays Rel_1 or Rel_2 switches into on-position again (state of output relay 11).



Window function (WIN)

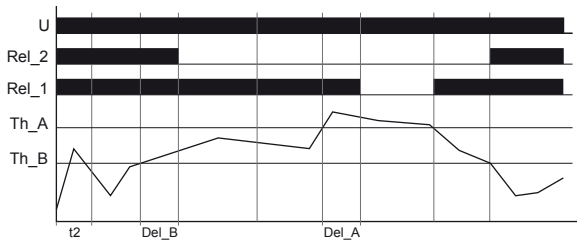
The adjusted threshold Th_A must be greater than the adjusted threshold Th_B. When the measured true power falls below the adjusted threshold Th_B, the set interval of the tripping delay (Del_B) begins. After the interval has expired, the output relays Rel_1 and Rel_2 switches into off-position (state of output relay 00). As soon as the measured true power exceeds the adjusted threshold Th_B, the output relays Rel_1 and Rel_2 switches into on-position again (state of output relay 11). When the measured true power exceeds the adjusted threshold Th_A, the set interval of the tripping delay (Del_A) begins. After the interval has expired, the output relays Rel_1 and Rel_2 switches into off-position (state of output relay 00). As soon as the measured true power falls below the adjusted threshold Th_A, the output relays Rel_1 and Rel_2 switches into on-position again (state of output relay 11).



Functions

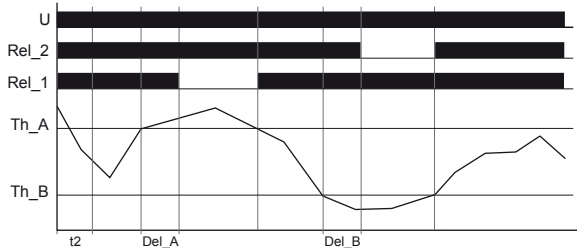
Maximum monitoring (2MAX)

The adjusted threshold Th_A must be greater than the adjusted threshold Th_B . When the measured true power exceeds the adjusted threshold Th_B , the set interval of the tripping delay (Del_B) begins. After the interval has expired, the output relay Rel_2 switches into off-position (state of output relay 10). When the measured true power exceeds the adjusted threshold Th_A , the set interval of the tripping delay (Del_A) begins. After the interval has expired, the output relay Rel_1 switches into off-position (state of output relay 00). As soon as the measured true power exceeds the corresponding threshold (Th_A or Th_B), the output relays Rel_1 or Rel_2 switches into on-position again (state of output relay 11).



Maximum- and minimum monitoring (MIN/MAX)

The adjusted threshold Th_A must be greater than the adjusted threshold Th_B . When the measured true power exceeds the adjusted threshold Th_A , the set interval of the tripping delay (Del_A) begins. After the interval has expired, the output relay Rel_1 switches into off-position (state of output relay 01). As soon as the measured true power falls below the adjusted threshold Th_A , the output relay Rel_1 switches into on-position again (state of output relay 11). When the measured true power falls below the adjusted threshold Th_B , the set interval of the tripping delay (Del_B) begins. After the interval has expired, the output relay Rel_2 switches into off-position (state of output relay 10). As soon as the measured true power exceeds the adjusted threshold Th_B , the output relay Rel_2 switches into on-position again (state of output relay 11).



Fault latch

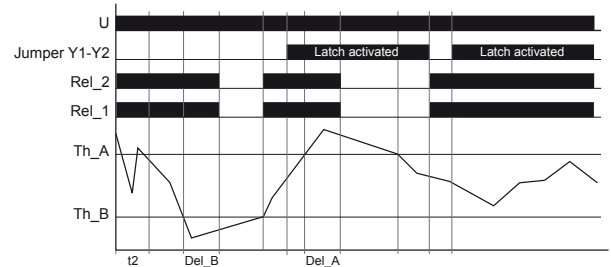
The fault latch can be activated via a jumper between the terminals Y1 and Y2 or via the display (Latch on).

If the fault latch is activated and a failure has occurred, the failure can be reset by activating the normal closed contact (Y1-Y2) or by pressing the plus- and minus-key (+ & -). After resetting the failure, the output relays Rel_1 and Rel_2 switches into on-position depending on the selected function and measured true power.

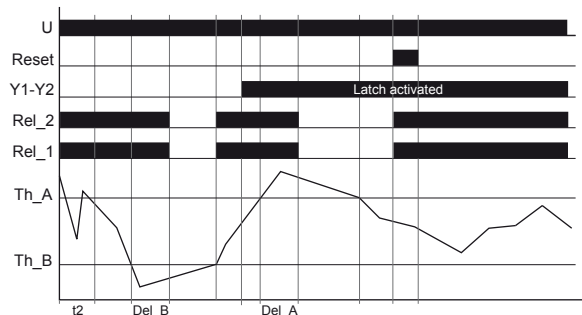
Please note:

The fault latch remains activ inspite of a I=0 recognition!

Example: Window function (WIN) - Resetting the fault latch by activating the normal closed contact (Y1-Y2)



Example: Window function (WIN) - Resetting the fault latch by pressing the plus- and minus-key (+ & -)



Temperature monitoring of the motor winding 9

If the supply voltage U is applied and the cumulative resistance of the PTC-circuit is less than $3.6k\Omega$ (standard temperature of the motor), the output relay Rel_2 switches into on-position if no other failure is applied! When the cumulative resistance of the PTC-circuit exceeds $3.6k\Omega$ (at least one of the PTCs has reached the cut-off temperature), the output relay Rel_2 switches into off-position and a temperature failure 9 will be indicated. The output relay Rel_2 switches into on-position again respectively the temperature failure 9 will be cancelled, if the cumulative resistance drops below $1.8k\Omega$ by cooling down of the PTC. If the fault latch is activated, the failure can be reset by activating the normal closed contact (Y1-Y2) or by pressing the plus- and minus-key (+ & -).

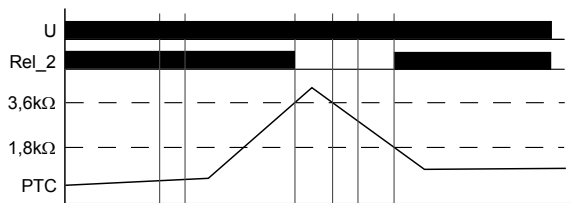
Please note:

If the output relay Rel_2 should switch into on-position again, no other failure should be applied!

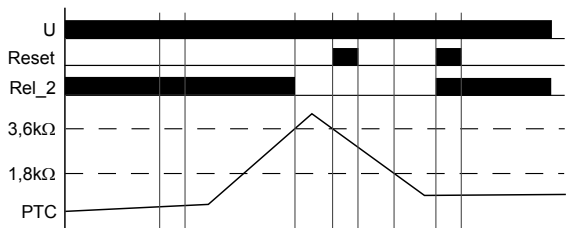
When the temperature monitoring isn't required then the jumper must be set between the terminals T1-T2!

Functions

Temperature monitoring without fault latch



Temperature monitoring with fault latch

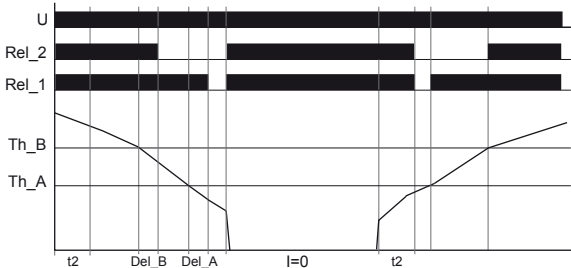


Recognition of disconnected load (I=0)

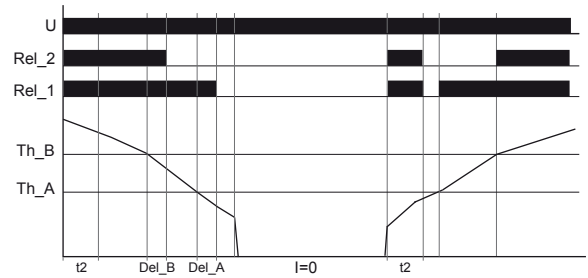
When the recognition of disconnected load (I=0) is activated, the relay state can be freely selected depending on the function.

When the current flow between i and k is interrupted, the output relays Rel_1 and Rel_2 remains into user-defined state.
When the current flow restores, the measuring cycle is restarted with the adjusted set interval of the start-up suppression time (t2).

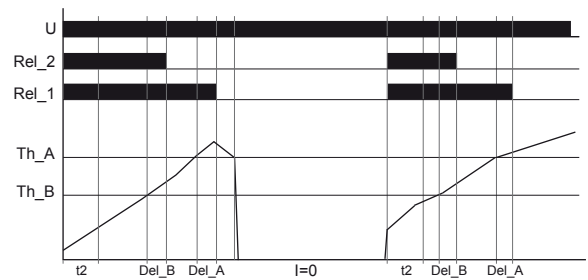
Example: I=0 with minimum monitoring (2MIN+I=0 ON)
relay state normal: Rel_1 and Rel_2 on



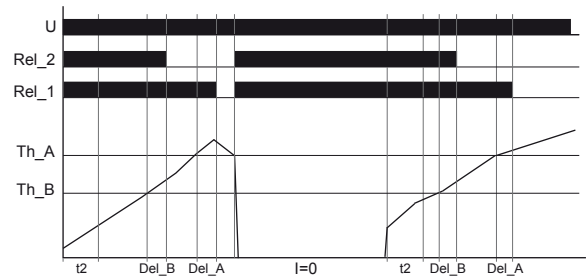
Example: I=0 Inv. with minimum monitoring (2MIN+I=0 ON)
relay state invers: Rel_1 and Rel_2 off



Example: I=0 with maximum monitoring (2MAX+I=0 ON)
relay state normal: Rel_1 and Rel_2 off

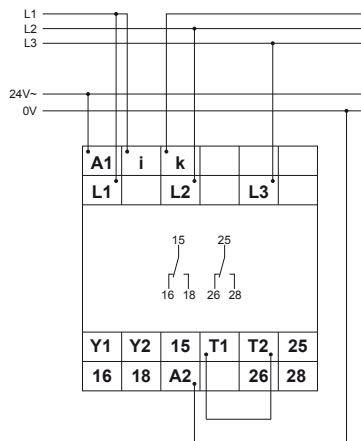


Example: I=0 Inv. with maximum monitoring (2MAX+I=0 ON)
relay state invers: Rel_1 and Rel_2 on

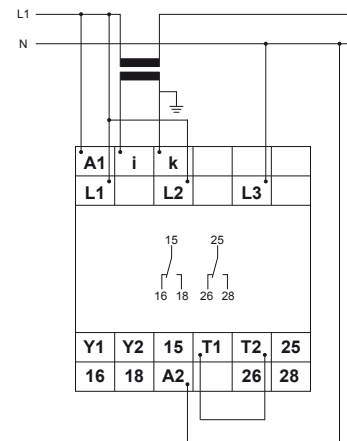


Connections

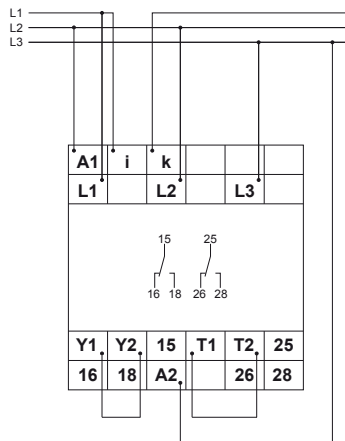
Connected 3~ 400V with power module 24V AC without fault latch $I_N < 12A$



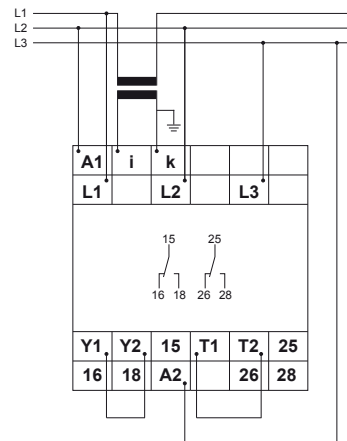
Connected 1~ 230V with power module 230V AC without fault latch but with current transformer $I_N > 12A$



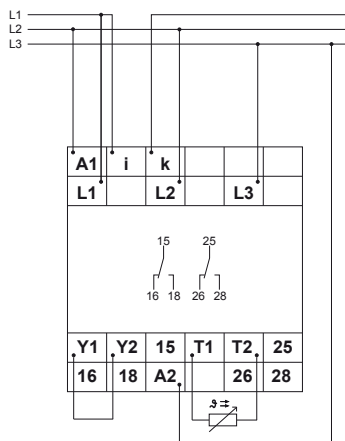
Connected 3~ 400V with power module 400V AC with fault latch $I_N < 12A$



Connected 3~ 400V with power module 400V AC with fault latch and current transformer $I_N > 12A$



Connected 3~ 400V with power module 400V AC with fault latch and temperature monitoring sensor $I_N < 12A$



Dimensions

