

X20DO8332-1

Data sheet
1.10 (October 2024)



Publishing information

B&R Industrial Automation GmbH

B&R Strasse 1

5142 Eggelsberg

Austria

Telephone: +43 7748 6586-0

Fax: +43 7748 6586-26

office@br-automation.com

Disclaimer

All information in this document is current as of its creation. The contents of this document are subject to change without notice. B&R Industrial Automation GmbH assumes unlimited liability in particular for technical or editorial errors in this document only (i) in the event of gross negligence or (ii) for culpably inflicted personal injury. Beyond that, liability is excluded to the extent permitted by law. Liability in cases in which the law stipulates mandatory unlimited liability (such as product liability) remains unaffected. Liability for indirect damage, consequential damage, business interruption, loss of profit or loss of information and data is excluded, in particular for damage that is directly or indirectly attributable to the delivery, performance and use of this material.

B&R Industrial Automation GmbH notes that the software and hardware designations and brand names of the respective companies used in this document are subject to general trademark, brand or patent protection.

Hardware and software from third-party suppliers referenced in this document is subject exclusively to the respective terms of use of these third-party providers. B&R Industrial Automation GmbH assumes no liability in this regard. Any recommendations made by B&R Industrial Automation GmbH are not contractual content, but merely non-binding information for which no liability is assumed. When using hardware and software from third-party suppliers, the relevant user documentation of these third-party suppliers must additionally be consulted and, in particular, the safety guidelines and technical specifications contained therein must be observed. The compatibility of the products from B&R Industrial Automation GmbH described in this document with hardware and software from third-party suppliers is not contractual content unless this has been separately agreed in individual cases; in this respect, warranty for such compatibility is excluded in any case, and it is the sole responsibility of the customer to verify this compatibility in advance.

1516132311786-1.10.1

1 General information

1.1 Other applicable documents

For additional and supplementary information, see the following documents.

Other applicable documents

Document name	Title
MAX20	X20 System user's manual

1.2 Order data


Order number	Short description	Figure
	Digital outputs	
X20DO8332-1	X20 digital output module, 8 outputs, 24 VDC, 2 A, source, supply directly on module, 1-wire connections	
	Required accessories	
	Bus modules	
X20BM11	X20 bus module, 24 VDC keyed, internal I/O power supply connected through	
X20BM15	X20 bus module, with node number switch, 24 VDC keyed, internal I/O power supply connected through	
	Terminal blocks	
X20TB12	X20 terminal block, 12-pin, 24 VDC keyed	

Table 1: X20DO8332-1 - Order data

1.3 Module description

This module is equipped with 8 outputs for 1-wire connections. The outputs are designed for a source circuit. The nominal output current is 2 A.

The output power supply is fed directly into the module. An additional power supply module is therefore not necessary. There is no connection between the module and the I/O power supply potential on the bus module.

Functions:

- [Digital outputs](#)
- [Delayed switching of outputs](#)
- [Monitoring the operating limits](#)

Delayed switching of outputs

The digital outputs can be switched with a delay using a timer.

Monitoring operating limits

The voltage of the I/O power supply is monitored for voltage overshoot or undershoot.

2 Technical description

2.1 Technical data

Order number	X20DO8332-1
Short description	
I/O module	8 digital outputs 24 VDC for 1-wire connections
General information	
B&R ID code	0xF321
Status indicators	I/O function per channel, operating state, module status
Diagnostics	
Module run/error	Yes, using LED status indicator and software
Outputs	Yes, using LED status indicator and software (output error status)
Supply voltage monitoring	Yes, using LED status indicator and software (output error status)
Power consumption	
Bus	0.26 W
Internal I/O	-
External I/O	0.81 W
Additional power dissipation caused by actuators (resistive) [W] ¹⁾	+0.336
Certifications	
CE	Yes
UKCA	Yes
UL	cULus E115267 Industrial control equipment
Digital outputs	
Variant	Current-sourcing FET
Number of output groups	2
Nominal voltage	24 VDC
Switching voltage	24 VDC -15% / +20%
Nominal output current	2 A
Total nominal current	8 A ²⁾
Connection type	1-wire connections
Output circuit	Source
Output protection	Thermal shutdown in the event of overcurrent or short circuit (see value "Short-circuit peak current") Internal freewheeling diode for switching inductive loads (see section "Switching inductive loads") Reverse polarity protection of supply voltage
Actuator power supply	
Supply	External
Fuse	Required line fuse: Max. 10 A, slow-blow
Diagnostic status	Output monitoring with 18 ms delay
Leakage current when the output is switched off	5 µA
R _{DS(on)}	21 mΩ
Peak short-circuit current	90 A for 200 µs
Switch-on in the event of overload shutdown or short-circuit shutdown	300 ms
Switching delay	
0 → 1	<300 µs
1 → 0	<300 µs
Switching frequency	
Resistive load	Max. 500 Hz
Inductive load	See section "Switching inductive loads".
Braking voltage when switching off inductive loads	Typ. 64 VDC
Insulation voltage between channel and bus	500 V _{eff}
Additional functions	Outputs can be connected in parallel to increase the output current.
Electrical properties	
Electrical isolation	Channel isolated from bus and I/O power supply
Operating conditions	
Mounting orientation	
Horizontal	Yes
Vertical	Yes
Installation elevation above sea level	
0 to 2000 m	No limitation
>2000 m	Reduction of ambient temperature by 0.5°C per 100 m
Degree of protection per EN 60529	IP20

Table 2: X20DO8332-1 - Technical data


Order number	X20DO8332-1	
Ambient conditions		
Temperature		
Operation		
Horizontal mounting orientation	-25 to 60°C	
Vertical mounting orientation	-25 to 50°C	
Derating	See section "Derating".	
Storage	-40 to 85°C	
Transport	-40 to 85°C	
Relative humidity		
Operation	5 to 95%, non-condensing	
Storage	5 to 95%, non-condensing	
Transport	5 to 95%, non-condensing	
Mechanical properties		
Note	Order 1x terminal block X20TB12 separately. Order 1x bus module X20BM11 separately.	
Pitch	12.5 ^{+0.2} mm	

Table 2: X20DO8332-1 - Technical data

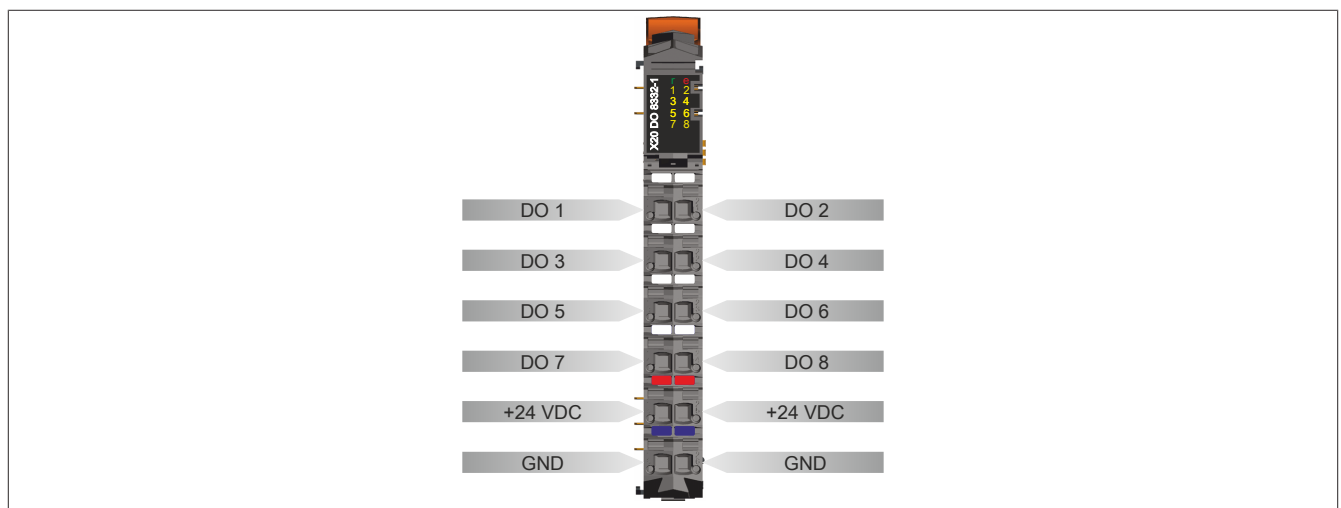
- 1) Number of outputs $\times R_{DS(on)} \times$ Nominal output current². For a calculation example, see section "Mechanical and electrical configuration" in the X20 system user's manual.
- 2) Derating must be observed for summation current starting at 6 A.

2.2 LED status indicators

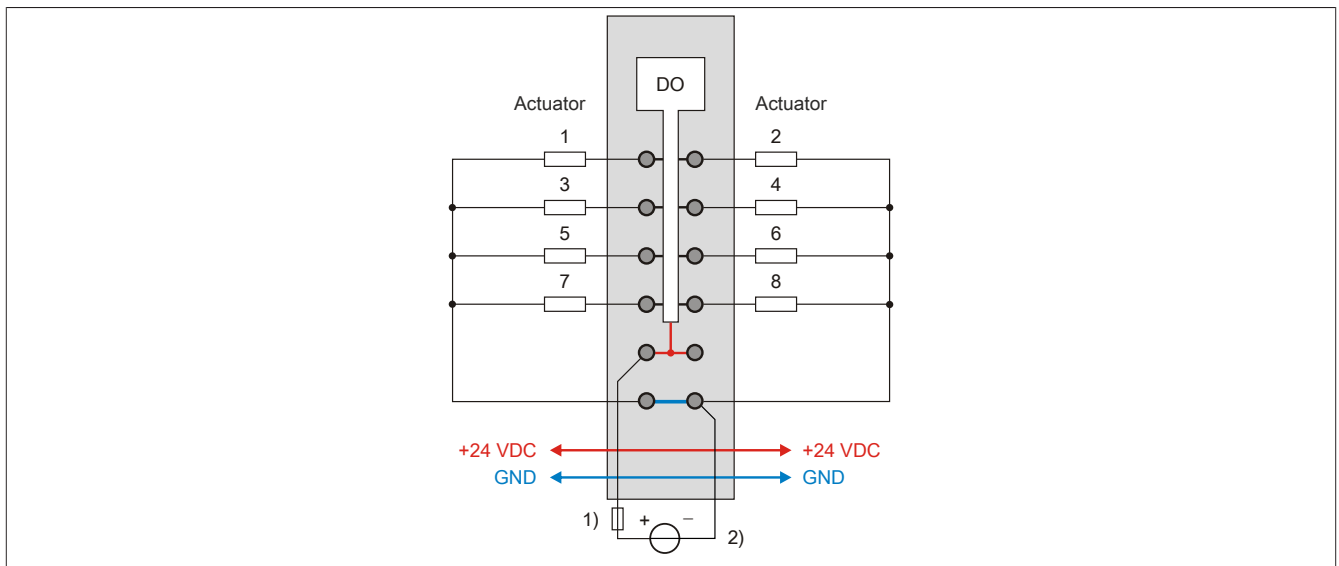
For a description of the various operating modes, see section "Additional information - Diagnostic LEDs" in the X20 System user's manual.

Figure	LED	Color	Status	Description
	r	Green	Off	No power to module
			Single flash	Mode RESET
			Blinking	Mode PREOPERATIONAL
			On	Mode RUN
	e	Red	Off	No power to module or everything OK
			Single flash	Warning/Error on an I/O channel. Level monitoring for digital outputs has been triggered.
			Double flash	I/O power supply too low
	e + r	Solid red / Single green flash		Invalid firmware
	1 - 8	Orange		Output state of the corresponding digital output

2.3 Pinout



2.4 Connection example



- 1) Fuse, 10 A slow-blow
- 2) External power supply 24 VDC

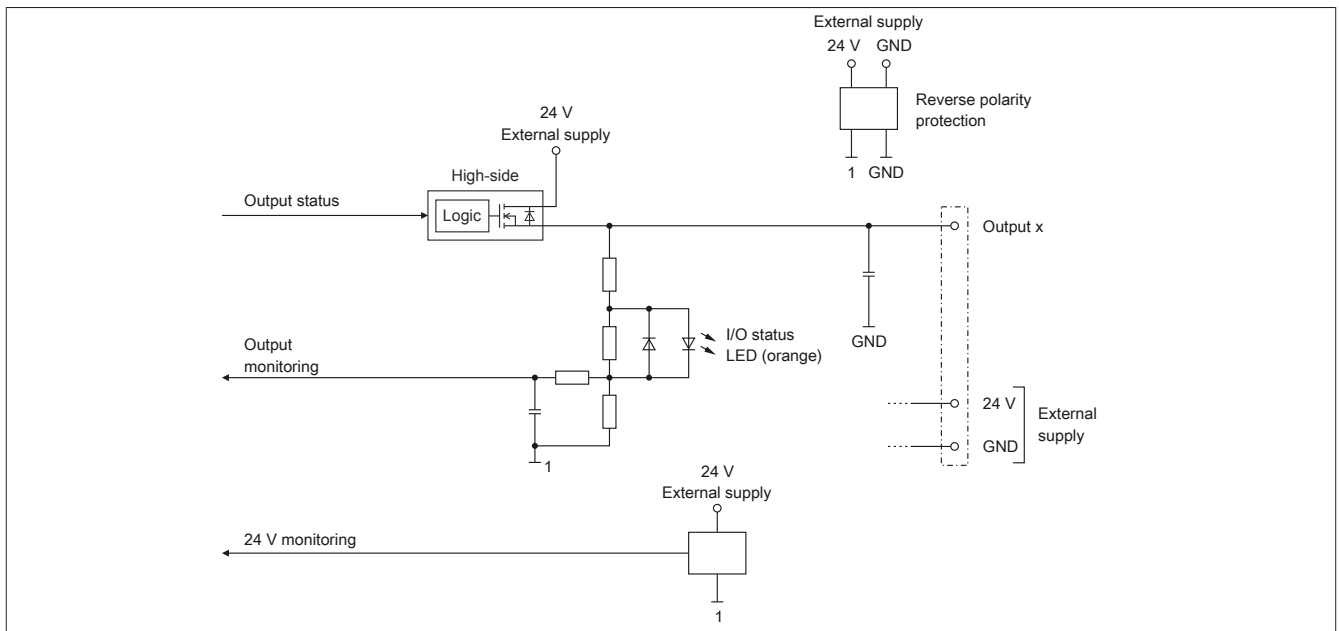


Caution!

If the module is operated outside specifications, the output current may rise above the maximum permissible nominal current. This applies both to individual channels and to the summation current of the module.

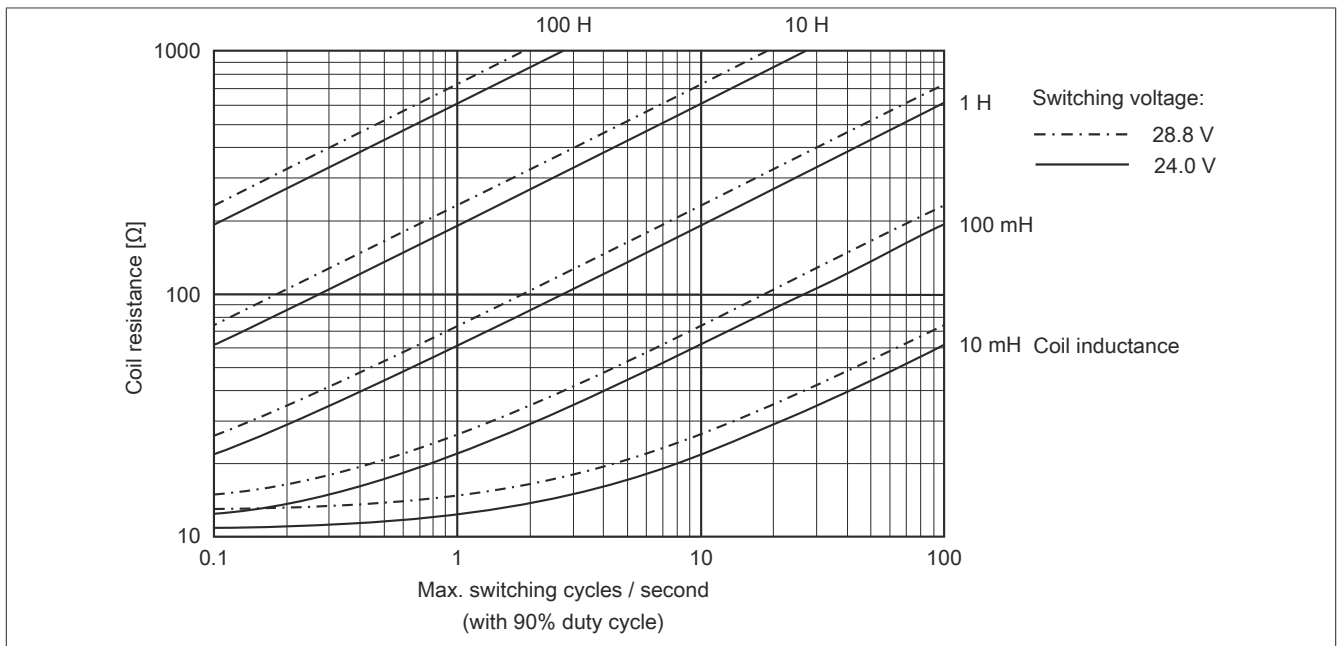
Appropriate cable cross-sections or external safety measures must therefore be provided.

2.5 Output circuit diagram

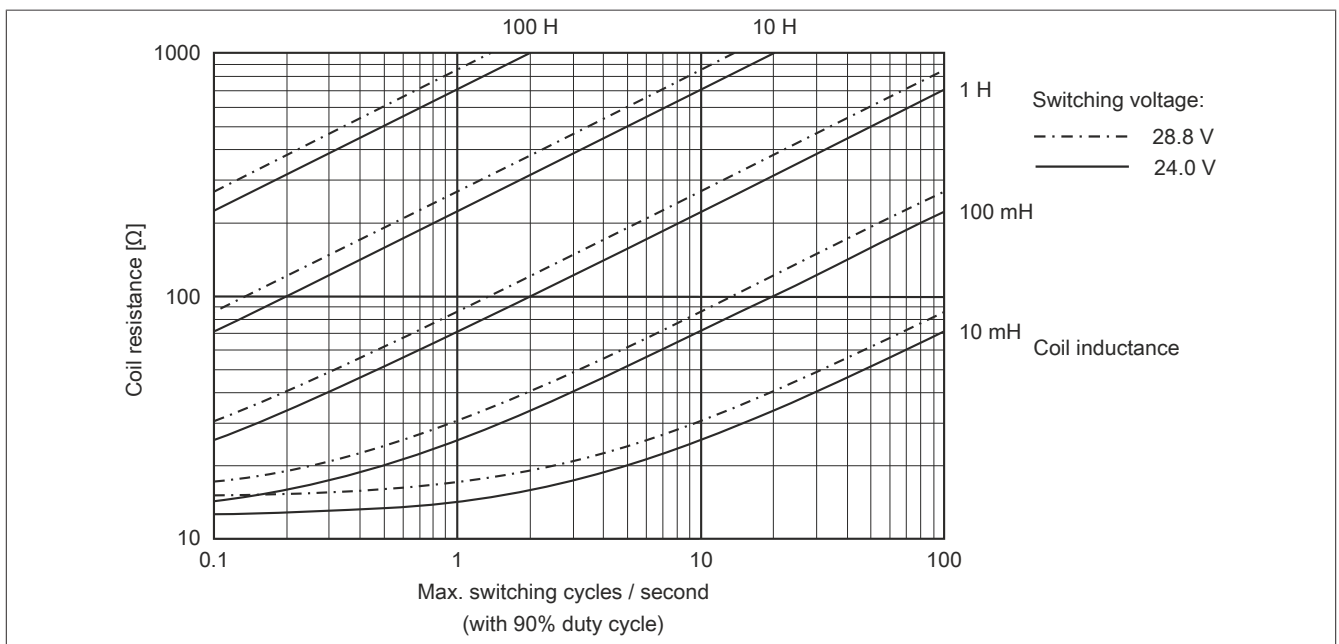


2.6 Switching inductive loads

Ambient temperature: 35°C, 4 outputs with the same load.

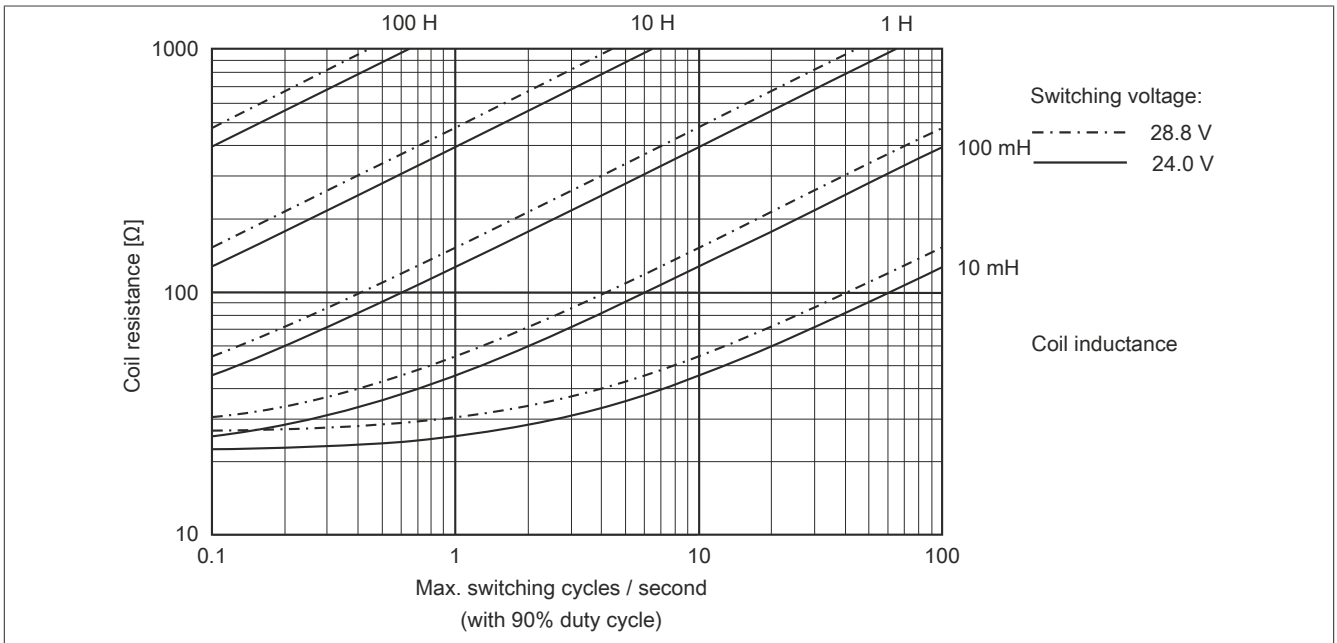


Ambient temperature: 60°C, 4 outputs with the same load.



Technical description

Ambient temperature: 60°C, all outputs with the same load.



Information:

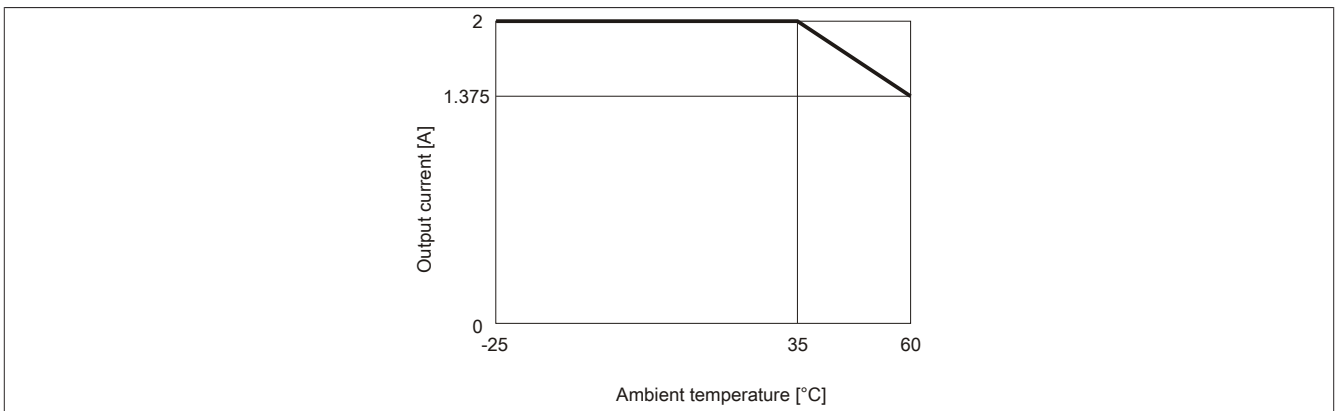
If the maximum number of operating cycles per second is exceeded, an external inverse diode must be used.

Operating conditions outside of the area in the diagram are not permitted!

2.7 Derating

The outputs of the module can handle up to 2 A. With a summation current of 8 A, no more than 4 channels are operable at full load.

Derating must be taken into account starting at 6 A.



Information:

Only modules with a maximum power consumption of 1.5 W are permitted to be operated next to the module.

For an example of calculating the power dissipation of I/O modules, see section "Mechanical and electrical configuration - Power dissipation of I/O modules" in the X20 user's manual.

3 Function description

3.1 Digital outputs

The module is equipped with 8 digital outputs.

The output state is transferred to the output channels with a fixed offset (<60 µs) in relation to the network cycle (SyncOut).

Packed outputs (only function model 0 - Standard)

Setting "Packed outputs" in the Automation Studio I/O configuration can be used to determine whether all bits of the register should be applied as individual data points in the Automation Studio I/O mapping (e.g. "DigitalOutput01 to DigitalOutputxx") or whether the register should be displayed as a single USINT data point (e.g. "DigitalOutput").



Information:

The register is described in ["Switching state of digital outputs 1 to 8" on page 13](#).

3.1.1 Monitoring status of the outputs

On the module, the output states of the outputs are compared to the target states. The control of the output driver is used for the target state.

A change in the output state resets monitoring for that output. The status of each individual channel can be read out. A change in the monitoring status is actively transmitted as an error message.

Supervision status	Description
0	Digital output channel: No error
1	Digital output channel: <ul style="list-style-type: none"> • Short circuit or overload • Channel switched on and missing I/O power supply • Channel switched off and external voltage applied to channel



Information:

The register is described in ["Status of digital outputs 1 to 8" on page 14](#).

3.2 Delayed switching of outputs

In "Function model 1 - Switching outputs", it is possible to activate the digital outputs with a delay.

The OutputDelay mask can be used to activate the delay for each channel individually. The module is controlled here using a 100 µs-based timer and the Output or OutputDelayed register.

Behavior of function model 1 - Output switching

With a timer delay of 0:

Output: DigitalOutput0x bits

When the delay is changed:

The bit string for DigitalOutput0x bits is output. The timer restarts.

Output: DigitalOutput0x bits

After delay time has expired:

The channels whose bits are set in the mask for OutputDelay are adapted to the corresponding OutputDelayed bits.

Output: DigitalOutput0x bits (if Enable bit = FALSE)
OutputDelayed bits (if Enable bit = TRUE)



Information:

Adjusting the output and restarting the timer take place immediately after transferring the new delay, even if the previous time has not yet passed.



Information:

The registers are described in "[Additional function - Delayed switching of digital outputs with switchover mask](#)" on page 15.

3.3 Monitoring the operating limits

Bit	Description
0	No error
1	

The status of the I/O supply voltage can be read out.

Bit	Description
0	I/O power supply above the warning limits of (20.4 V)
1	I/O power supply below the warning limits (20.4 V)



Information:

The register is described in "[Status of the supply voltage](#)" on page 14.

4 Commissioning

4.1 Using the module on the bus controller

Function model 254 "Bus controller" is used by default only by non-configurable bus controllers. All other bus controllers can use other registers and functions depending on the fieldbus used.

For detailed information, see section "Additional information - Using I/O modules on the bus controller" in the X20 user's manual (version 3.50 or later).

4.1.1 CAN I/O bus controller

The module occupies 1 digital logical slot on CAN I/O.

5 Register description

5.1 General data points

In addition to the registers described in the register description, the module has additional general data points. These are not module-specific but contain general information such as serial number and hardware variant.

General data points are described in section "Additional information - General data points" in the X20 System user's manual.

5.2 Function model 0 - Standard

Register	Fixed offset	Name	Data type	Read		Write	
				Cyclic	Acyclic	Cyclic	Acyclic
2	0	DigitalOutput	USINT			•	
		DigitalOutput01	Bit 0				
					
		DigitalOutput08	Bit 7				
30	1	StatusInput01	USINT		•		
		StatusDigitalOutput01	Bit 0				
					
		StatusDigitalOutput08	Bit 7				
8192	-	asy_ModulID	UINT		•		
8196	-	Status of the supply voltage	USINT		•		
		PowerSupply01	Bit 2	•			

Fixed modules require their data points to be in a specific order in the X2X frame. Cyclic access occurs according to a predefined offset, not based on the register address.

Acyclic access continues to be based on the register numbers.

5.3 Function model 1 - Output switching

Register	Fixed offset	Name	Data type	Read		Write	
				Cyclic	Acyclic	Cyclic	Acyclic
2	0	Switching state of digital outputs 1 to 8	USINT			•	
		DigitalOutput01	Bit 0				
					
		DigitalOutput08	Bit 7				
4	1	Switching state of delayed digital outputs 1 to 8	USINT			•	
		DigitalOutput01Delayed	Bit 0				
					
		DigitalOutput08Delayed	Bit 7				
6	2	Switching mask after the delay time has expired	USINT			•	
		DigitalOutput01DelayEnable	Bit 0				
					
		DigitalOutput08DelayEnable	Bit 7				
8	3	Setting the delay (OutputDelayTime)	USINT			•	
30	1	Status of digital outputs 1 to 8	USINT		•		
		StatusDigitalOutput01	Bit 0				
					
		StatusDigitalOutput08	Bit 7				
8192	-	asy_ModulID	UINT		•		
8196	-	Status of the supply voltage	USINT		•		
		PowerSupply01	Bit 2	•			

Fixed modules require their data points to be in a specific order in the X2X frame. Cyclic access occurs according to a predefined offset, not based on the register address.

Acyclic access continues to be based on the register numbers.

5.4 Function model 254 - Bus Controller

Register	Offset ¹⁾	Name	Data type	Read		Write	
				Cyclic	Acyclic	Cyclic	Acyclic
2	0	Switching state of digital outputs 1 to 8	USINT			•	
		DigitalOutput01	Bit 0				
					
		DigitalOutput08	Bit 7				
30	-	Status of digital outputs 1 to 8	USINT		•		
		StatusDigitalOutput01	Bit 0				
					
		StatusDigitalOutput08	Bit 7				
8192	-	asy_ModulID	UINT		•		
8196	-	Status of the supply voltage	USINT		•		
		Power Supply01	Bit 2		•		

1) The offset specifies where the register is within the CAN object.

5.5 Digital outputs

5.5.1 Switching state of digital outputs 1 to 8

Name:

DigitalOutput

DigitalOutput01 to DigitalOutput08

The switching state of digital outputs 1 to 8 are stored in this register.

Data type	Values	Information ¹⁾
USINT	0 to 255	Packed outputs = On Data point: "DigitalOutput"
	See the bit structure.	Packed outputs = Off or function model ≠ 0 - Standard. Data points: "DigitalOutput01" to "DigitalOutput08"

1) See "Digital outputs" on page 9.

Bit structure:

Bit	Name	Value	Information
0	DigitalOutput01	0	Digital output 01 reset
		1	Digital output 01 set
...
7	DigitalOutput08	0	Digital output 08 reset
		1	Digital output 08 set

5.6 Reading out the module ID

Name:

asy_ModulID

This register offers the possibility to read the module ID.

Data type	Values
UINT	Module ID

5.7 Monitoring status of the digital outputs

On the module, the output states of the outputs are compared to the target states.

5.7.1 Status of digital outputs 1 to 8

Name:

StatusInput01

StatusDigitalOutput01 to StatusDigitalOutput08

This register is used to indicate the status of digital outputs 1 to 8.

Data type	Values	Information ¹⁾
USINT	0 to 255	Packed outputs = On Data point: "StatusInput01"
	See the bit structure.	Packed outputs = Off or function model ≠ 0 - Standard. Data points: "StatusDigitalOutput01" to "StatusDigitalOutput0x"

1) See "Digital outputs" on page 9.

Bit structure:

Bit	Name	Value	Information
0	StatusDigitalOutput01	0	Channel 01: No error
		1	Channel 01: <ul style="list-style-type: none"> Short circuit or overload Channel switched on and missing I/O power supply Channel switched off and external voltage applied to channel
...
8	StatusDigitalOutput08	0	Channel 08: No error
		1	Channel 08: For an error description, see channel 01.

5.8 Operating limit monitoring

The output supply of the module is monitored. I/O supply voltage <19.2 V is displayed as a warning.

5.8.1 Status of the supply voltage

Name:

asy_SupplyStatus

The status of the I/O supply voltage is mapped in this register.

Data type	Values
USINT	See the bit structure.

Bit structure:

Bit	Name	Value	Information
0 - 1	Reserved	0	
2	PowerSupply01	0	I/O supply above the warning level of 20.4 V
		1	I/O supply below the warning level of 20.4 V
3 - 7	Reserved	0	

5.9 Additional function - Delayed switching of digital outputs with switchover mask

5.9.1 Switching state of delayed digital outputs 1 to 8

Name:

DigitalOutput01Delayed to DigitalOutput08Delayed

According to the corresponding bit in the OutputDelay mask, the switching state of all digital outputs 1 to 8 are stored in the OutputDelayed bits after the delay time has expired.

Data type	Values
USINT	See the bit structure.

Bit structure:

Bit	Name	Value	Information
0	DigitalOutput01Delayed	0	Digital output 01 reset
		1	Digital output 01 set
...
7	DigitalOutput08Delayed	0	Digital output 08 reset
		1	Digital output 08 set



Information:

After the delay time has elapsed, only the channels whose bit is set in the OutputDelay mask are adapted to the OutputDelayed bits.

5.9.2 Switching mask after the delay time has expired

Name:

DigitalOutput01DelayEnable to DigitalOutput08DelayEnable

These registers form the mask for OutputDelay. They specify which outputs are switched to the bit pattern of register OutputDelayed after the delay time has elapsed.

Data type	Values
USINT	See the bit structure.

Bit structure:

Bit	Name	Value	Information
0	DigitalOutput01DelayEnable	0	Digital output 01 remains unchanged
		1	Digital output 01 being switched
...
7	DigitalOutput08DelayEnable	0	Digital output 08 remains unchanged
		1	Digital output 08 being switched

5.9.3 Setting the delay

Name:

OutputDelayTime

This register can be used to set the delay in 100 µs steps.

After the delay time has expired, the digital outputs are adjusted according to the switching mask (register 6) and the delayed output pattern (register 4).

Data type	Value
USINT	0 to 255 (in 100 µs steps) ¹⁾

¹⁾ The value 0 disables processing

5.10 Minimum cycle time

The minimum cycle time specifies how far the bus cycle can be reduced without communication errors occurring. It is important to note that very fast cycles reduce the idle time available for handling monitoring, diagnostics and acyclic commands.

Minimum cycle time
150 µs

5.11 Minimum I/O update time

The minimum I/O update time specifies how far the bus cycle can be reduced so that an I/O update is performed in each cycle.

Minimum I/O update time
150 µs