SKU:DFR1139 (https://www.dfrobot.com/product-2837.html)



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1. Introduction

No longer worry about insufficient memory or lack of PSRAM space when using FireBeetle 2 ESP32-E! Now, there is a version of FireBeetle 2 ESP32-E(N16R2) with 16M Flash and 2M PSRAM, offering enhanced memory capacity and operating space.

This product improves memory capacity and operating space, providing better performance when running applications such as LVGL graphics library for interface design and interaction. It is based on Espressif's ESP32-WROOM-32E-N16R2 module, featuring a 32-bit dual-core processor with a clock frequency of up to 240MHz, and supporting WiFi and Bluetooth dual-mode communication. It is highly suitable for IoT scenarios.

In terms of product design, FireBeetle 2 ESP32-E(N16R2) has the following features:

Rich peripheral interfaces

Including 17 digital pins, 11 analog pins, 3 UART interfaces, 1 SPI interface, 1 I2C interface, 1 I2S interface, and 2 DAC interfaces, it can meet various hardware connection requirements.

Dual power supply modes

Supporting USB and external 3.7V lithium battery power supply, it can automatically switch between power sources in dual power supply mode. It also supports USB and external DC charging modes.

Support for multiple programming methods

Including Arduino IDE, ESP-IDF, MicroPython, etc., catering to the programming preferences of different developers.

Compact design, easy to embed

With dimensions of only 25.4mm \times 60mm, it has onboard WiFi and Bluetooth antennas and adopts a stamp hole design, making it easy to embed or integrate into PCB prototypes.

Wide range of application scenarios

It is suitable not only for home automation renovation, IoT project prototyping, IoT remote control, remote robot control, but also for projects running LVGL graphics library for interface design or interaction.

Furthermore, this product is one of the low-power IoT development boards in the FireBeetle series. If it does not meet your requirements, you can refer to the FireBeetle Series Selection Guide (https://www.dfrobot.com/blog-13438.html) to choose a more suitable model.

2. Features

- Equipped with ESP32-WROOM-32E-N16R2 dual-core module
- Clock frequency up to 240MHz, with 16M Flash and 2M PSRAM for large memory capacity
- Low-power development board, supporting dual-mode communication of WiFi and Bluetooth
- Onboard GDI display interface for quick connection to display screens
- Onboard charging circuit and PH2.0 lithium battery interface, supporting dual-power supply and automatic switching
- Supports various programming methods such as Arduino IDE, ESP-IDF, MicroPython, etc.
- Compact design with small size, suitable for IoT projects with limited space and embedded systems

3. Specifications

Power Parameters

Input Voltage

USB-C interface: 5V DC

PH2.0 interface: 3.7V Li-ion

VCC pin: 5V DC

MCU Parameters

 Processor: Tensilica LX6 dual-core processor (one core for high-speed connectivity, one core for independent application development)

Clock Frequency: 240IVIHz

SRAM: 520KBROM: 448KB

• Flash: 16MB

PSRAM: 2MB

On-chip Clock: 40MHz crystal oscillator, 32.768KHz crystal oscillator

Wireless Parameters

• Wi-Fi Standard: FCC/CE/TELEC/KCC

- Wi-Fi Protocol: 802.11 b/g/n/d/e/i/k/r (802.11n, up to 150 Mbps), A-MPDU and A-MSDU aggregation, supports 0.4us protection interval
- Wi-Fi Frequency Range: 2.4~2.5 GHz
- Bluetooth Protocol: Compliant with Bluetooth V4.2 BR/EDR and BLE standards
- Bluetooth Audio: CVSD and SBC audio
- Bluetooth Frequency Range: 2.4~2.5GHz

Peripheral Parameters

- Digital Pins × 17: IO0, IO1, IO2, IO3, IO4, IO12, IO13, IO14, IO15, IO17, IO18, IO19, IO21, IO22, IO23, IO25, IO26
- Analog Pins × 11: IO0, IO2, IO4, IO12, IO13, IO14, IO15, IO25, IO26, I34, I35

• UART Interfaces: ×3

• SPI Interface: ×1

I2C Interface: ×1

• I2S Interface: ×1

• DAC Interface: ×2

• Touch Interfaces: ×7

• LED PWM Channels: ×16

• RGB LED: WS2812

• Display Interface: GDI

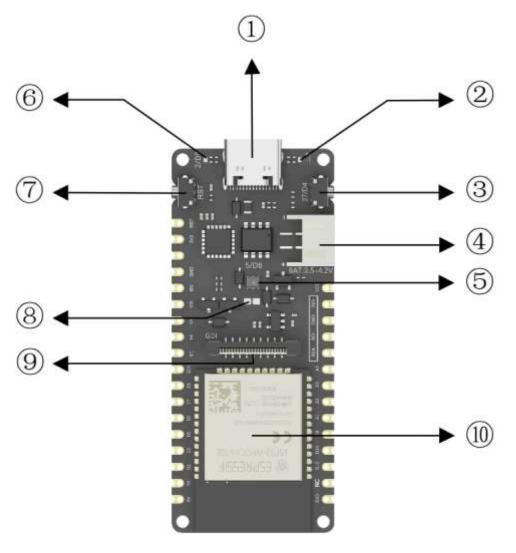
Other Parameters

Interface Compatibility: FireBeetle V2 series compatible

• Module Size: 25.4mm × 60mm

• Weight: 23.4g

4. Board Overview

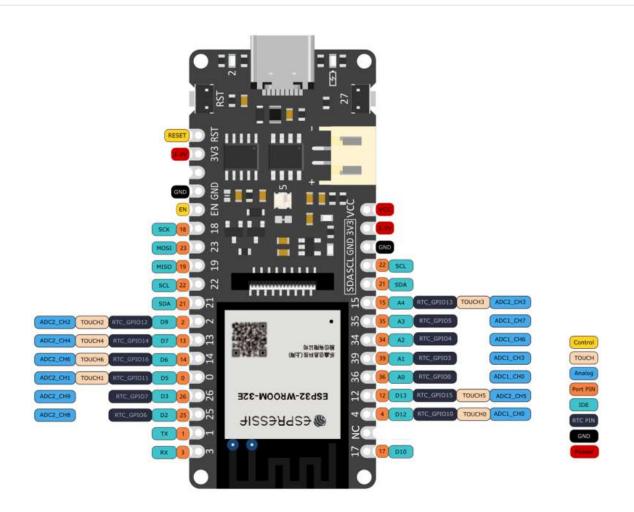


No.	Function	Description
1)	USB Interface	Program download and power supply, 4.75V-5.5V compatible
2	Charging Indicator	Red LED for indicating charging status: 1. Off when fully charged or not charged; 2. On when charging; 3. Quick flash when powered by USB, and no battery connected.
3	User Button	Controlled by pin IO27/D4
4	Li-ion Battery Port	Support 3.5V-4.2V
(5)	Onboard RGB Light	WS2812 RGB LED, controlled by pin IO5/D8
	Onboard	LED

0	LED	LED controlled by pin 102/D9
7	Reset Button	Press to reset program

No.	Function	Description				
8	Low-power Solder Jumper Pad	Designed for low power mode and default to be connected. Slightly cut off the thin wire with a knife to disconnect it. When disconnected, static power consumption can be reduced by 500 µA. The power consumption can be reduced to 13 µA after controlling the maincontroller to enter the sleep mode through the program. Note: when the pad is disconnected, you can only drive RGB LED light via the USB Power supply.				
9	GDI	DFRobot dedicated Display interface. Refer to the GDI part of this page.				
10	ESP32-E Module	ESP32-WROOM-32E-N16R2				

5. Pinout



Categro	y Desc	ription
Contro	ol .	FireBeetle enable/reset pins

Categroy	Description
Touch	Pin with capacitive touch function
Analog	Analog pin
Port PIN	Default physical pin number of the chip, which can be used to directly control the corresponding pin
Arduino IDE	In Arduino IDE, the pin numbers have been remapped by FireBeetle, and you can directly use this symbol to control the corresponding pin
RTC PIN	FireBeetle 2 ESP32-E supports low power function, and in Deep-sleep mode, only RTC pin keeps working and can be used as a wave-up source. When RTC pin is used as an output pin, it keeps outputting level value when the chip is in Deep-sleep mode, while as an input pin, it can wake up the chip from Deep-sleep.
GND	Common ground for all power supplies and logics
Power	When powered by 5V-USB, VCC outputs about 4.7V and 3V3 outputs 3.3V; When powered by 4V li-ion battery, VCC outputs about 4V and 3V3 outputs 3.3V(Actual measurement)

FireBeetle 2 ESP32-E(N16R2) has up to 21 physical GPIOs, which are mainly for connecting peripherals like sensors, actuators, etc. Meanwhile, these IO pins can be multiplexed for other functions such as UART, SPI, I2C and so on. The table below provides users with a detailed description of FireBeetle 2 ESP32-E(N16R2) GPIO.

Pin Number	Name	Function	ADC	Communication	Remark
GPIO 0	0/D5	Used as input or output	ADC2_CH1		Occupied when using USB transmission
GPIO 1	1/TXD	Used as input or output		UARTO_TX	Occupied when using USB power supply and serial printing
GPIO 2	2/D9	Used as input or	ADC2_CH2		For controlling onboard LED by outputting digital

output	, , , , , , , , , , , , , , , , , , ,	ب
output	signal	

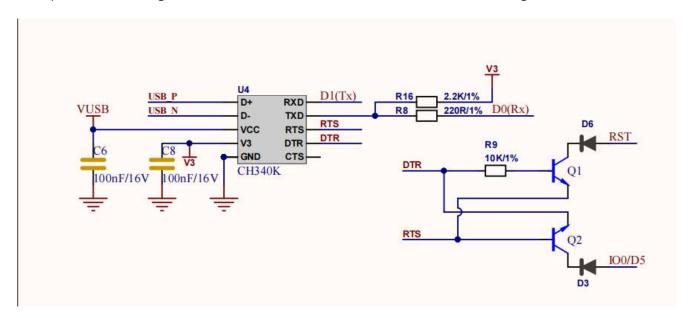
Pin Number	Name	Function	ADC	Communication	Remark
GPIO 3	3/RXD	Used as input or output		UARTO_RX	Occupied when using USB power supply and serial printing
GPIO 4	4/D12	Used as input or output	ADC2_CH0		
GPIO 12	12/D13	Used as input or output	ADC2_CH5		
GPIO 13	13/D7	Used as input or output	ADC2_CH4		
GPIO 14	14/D6	Used as input or output	ADC2_CH6		
GPIO 15	15/A4	Used as input or output	ADC2_CH3		
GPIO 18	18/SCK	Used as input or output		SPI_SCK	
GPIO 19	19/MISO	Used as input or output		SPI_MISO	
GPIO 21	21/SDA	Used as input or output		I2C_SDA	
GPIO 22	22/SCL	Used as input or output		I2C_SCL	

		Used as		
GPIO 23	23/MOSI	input or	SPI_MOSI	
		output		

Pin Number	Name	Function	ADC	Communication	Remark
GPIO 25	25/D2	Used as input or output	ADC2_CH8		DAC_1 (Range: 0- 255; Output Voltage: 0-3.3V)
GPIO 26	26/D3	Used as input or output	ADC2_CH9		DAC_2 (Range: 0- 255; Output Voltage: 0-3.3V)
GPIO 34	34/A2	Used as input only	ADC1_CH6		
GPIO 35	35/A3	Used as input only	ADC1_CH7		
GPIO 36	36/A0	Used as input only			
GPIO 39	39/A1	Used as input only			

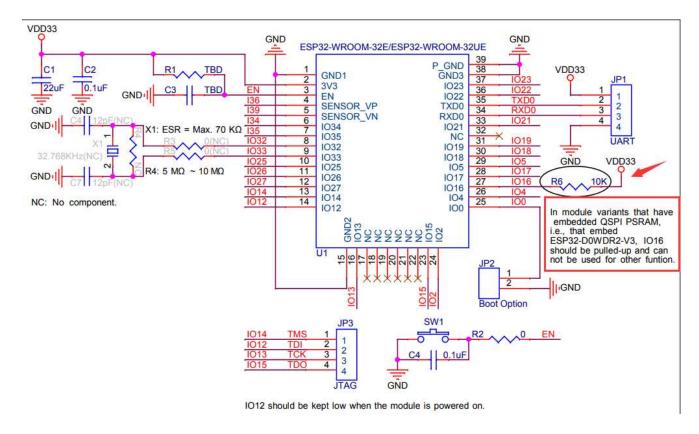
Note:

• It is recommended not to multiplex the pin IO0/D5, IO1/TXD and IO3/RX since they will be occupied when using USB-related function. The USB-related circuit design is shown below:



• IO34-39 are for input only.

 NC Pin Explanation: Originally designated as IO16/D11 pin, it is now changed to NC pin, which means it should not be used for any other functions. Please refer to the datasheet for the reasons behind this change.



• FireBeetle 2 ESP32-E(N16R2) has two 8-bit DAC channel that converts 2-way digital signal to 2 analog voltage outputs. Two channels can work independently. DAC circuit is composed of built-in resistors in series and a buffer. The two DACs can be used as reference voltage.

6. Dimension

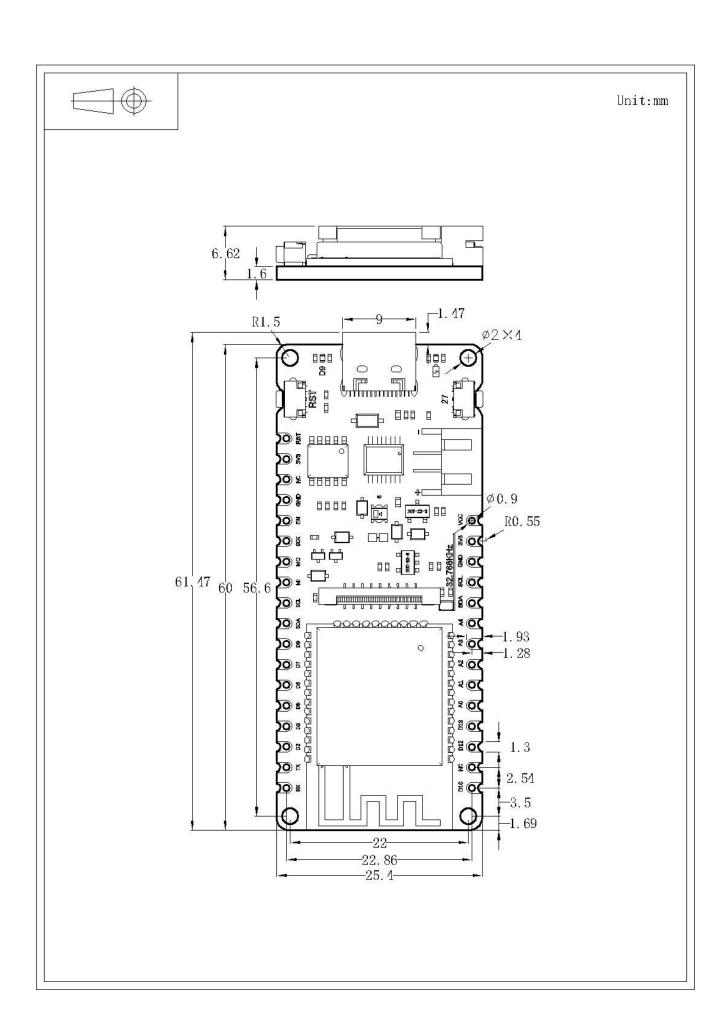
• Pin Pitch: 2.54mm

Mounting Hole Pitch: 22mm or 56.6mm

Mounting Hole Size: 2mm

Board Size: 25.4×60mm/1×2.36"

• Thickness: 1.6mm



7. Getting Started (Use for first time)

7.1 Download Arduino IDE

- Click to enter the official Arduino website (https://www.arduino.cc/en/Main/Software)
- Select and download the Arduino IDE package that is appropriate for your computer OS.

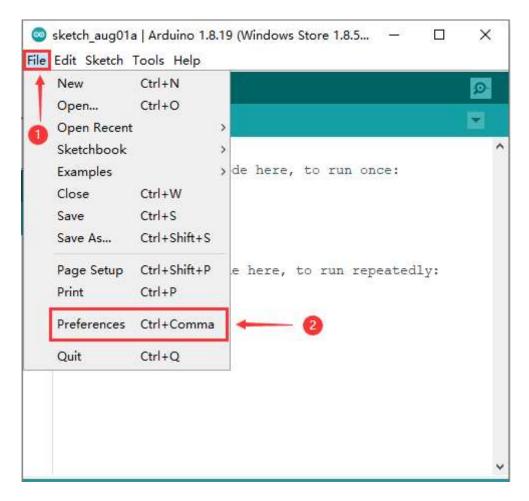
Downloads



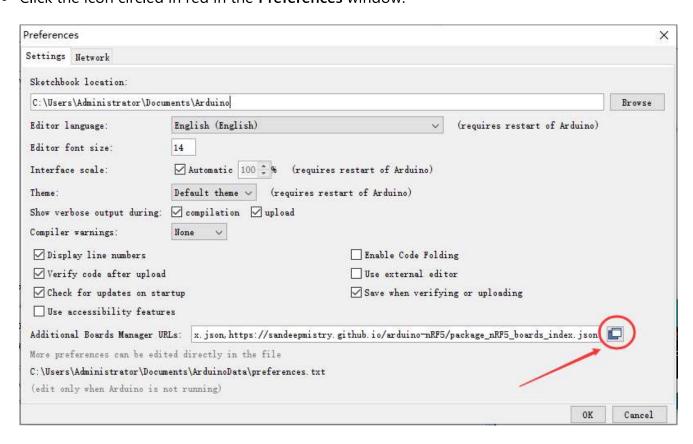
7.2 Configure Arduino IDE

It is required to install ESP32 board in Arduino IDE for using FireBeetle 2 ESP32-E for the first time.

• Open Arduino IDE, click File-Preferences, as shown below



• Click the icon circled in red in the **Preferences** window.



Add the icen LIDI below to the newly penned up window. There should be one LIDI for each

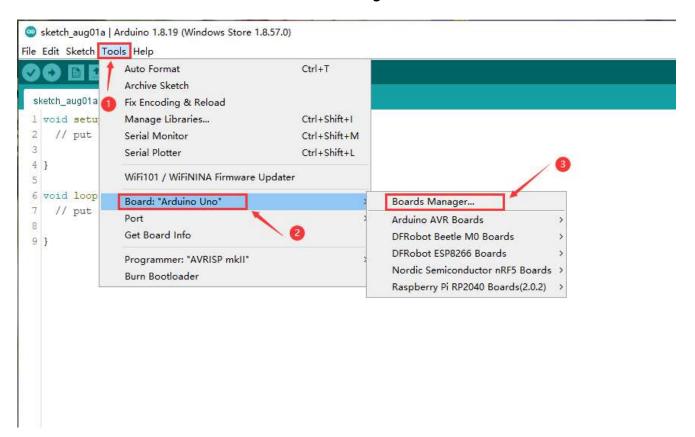
Add the Json one below to the newly-popped up willdow. There should be one one for lor each
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https://espressif.github.io/arduino-esp32/package_esp32_index.json (https://espressif.github.io/arduino-esp32/package_esp32_index.json)

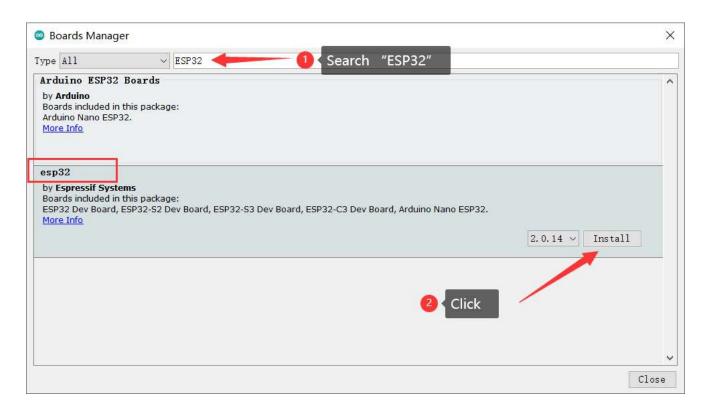
• Click OK then.



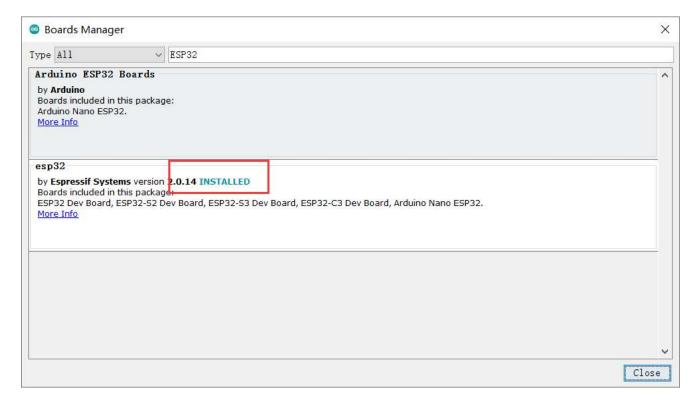
Download SDK. Click Tools->Board>Boards Manager.



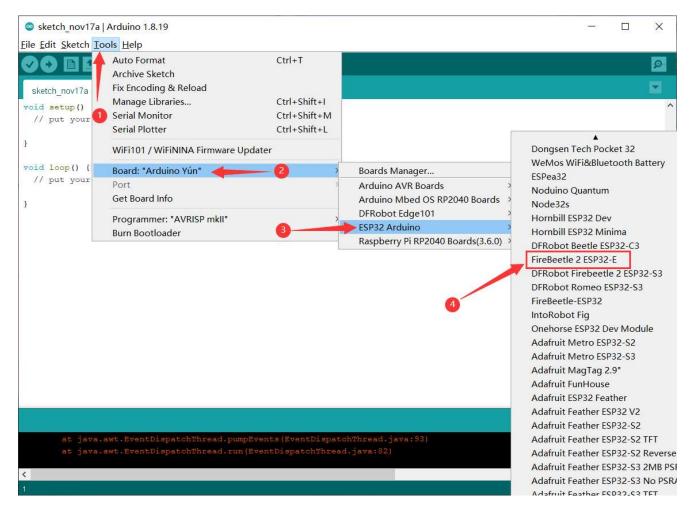
• Enter "ESP32" in the search bar, then the SDK for **esp32** will appear automatically. Click install now.



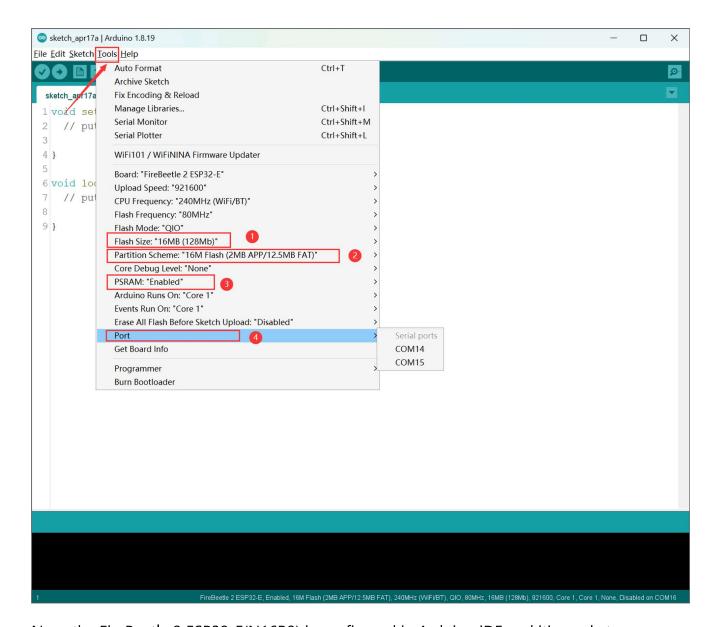
• When the SDK installation completes, the word "installed" will appear at the position marked in red below. Close the window.



• Select FireBeetle 2 ESP32-E development board. Click **Tools-->Board-->ESP32 Arduino-->FireBeetle ESP32-E**, as shown below.



• After that, connect your FireBeetle 2 ESP32-E to your computer. Here, a port COM4 comes out after the connection, indicating that it is the port for FireBeetle 2 ESP32-E. Select it as the way shown below.



• Now, the FireBeetle 2 ESP32-E(N16R2) is configured in Arduino IDE and it's ready to go.

8. Arduino Tutorials

Note: FireBeetle 2 ESP32-E(N16R2) does not have the IO16/D11 pin available. If this pin is used in the following tutorials, please modify the configuration to use another pin.

The basic tutorials (click here to jump)

(https://wiki.dfrobot.com/FireBeetle_Board_ESP32_E_SKU_DFR0654#target_10) include tutorials on GPIO, RGB LED, serial communication, capacitive touch sensor, interrupts, I2C, SPI, and GDI.

The advanced tutorials (click here to jump)

(https://wiki.dfrobot.com/FireBeetle_Board_ESP32_E_SKU_DFR0654#target_20) include tutorials on Deep Sleep mode, SD card, WiFi, Bluetooth, Alibaba Cloud IoT, and IFTTT.

1. Cannot add board link to Arduino IDE?

A: First off all, make sure the Network connection is in good condition. Hope this post (https://forum.arduino.cc/t/arduino-ide-cant-download-libraries-and-boards/650155/5) from Arduino helps. If that doesn't work, try replacing the board link from

https://downloadcd.dfrobot.com.cn/FireBeetle/package_DFRobot_index.json (https://downloadcd.dfrobot.com.cn/FireBeetle/package_DFRobot_index.json) to http://downloadcd.dfrobot.com.cn/FireBeetle/package_DFRobot_index.json (http://downloadcd.dfrobot.com.cn/FireBeetle/package_DFRobot_index.json) and reload it.

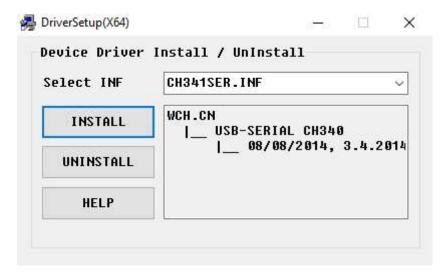
2. When using the SD library, the serial monitor does not show any print output or displays a connection failure after uploading the program.

A: Press RST button to reset and try again.

3. The driver is not installed automatically after plugging into the device?

A: FireBeetle 2 ESP32-E(N16R2) uses the CH340 serial chip, which can be used without installing a driver in most devices. If you find that the driver is not automatically installed when you plug in the device, you can manually install it yourself:

- CH340 Driver for Windows
 (https://dfimg.dfrobot.com/nobody/wiki/0e0d6b3864f7163833ec5d7ad4af7632.EXE)
- CH340 Driver for MAC (https://dfimg.dfrobot.com/nobody/wiki/c195a13df2a1989d5dc04e76e6bcb701.ZIP)



For any other questions, advice or cool ideas to share, please visit the **DFRobot Forum** (https://www.dfrobot.com/forum/).

More Documents

- esp32-wroom-32e/32ue_datasheet.pdf (https://dfimg.dfrobot.com/60c1e008bddfc41c3293de80/wiki/17135ab9d90c9a2d0f681b591b3076a8.pdf)
- DFR1139_schematic.PDF
 (https://img.dfrobot.com.cn/wiki/60c1e008bddfc41c3293de80/501d2c3b5efcacf99b768b834 7bfc4da.PDF)
- DFR1139_2D File.zip (https://img.dfrobot.com.cn/wiki/60c1e008bddfc41c3293de80/dc5bfe2095243851d2f25a4d8 a17edaf.zip)
- DFR1139_STP File.zip (https://img.dfrobot.com.cn/wiki/60c1e008bddfc41c3293de80/7bd2ec5d7bfda206a709256b 4b8571f2.zip)
- Shell stl file (https://img.dfrobot.com.cn/wiki/5d57611a3416442fa39bffca/94baeab196b1381ee2ad404fb 9b4a14a.zip)