

# X20(c)IF1082-2

Data sheet  
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## **Publishing information**

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## **Version history**

B&R makes every effort to keep documents as current as possible. The most current versions are available for download on the B&R website ([www.br-automation.com](http://www.br-automation.com)).

# 1 General information

## 1.1 Other applicable documents

For additional and supplementary information, see the following documents.

### Other applicable documents

Document name	Title
MAX20	<a href="#">X20 System user's manual</a>

### Additional documentation

Document name	Title
MAREDSYS	<a href="#">Redundancy for control systems</a>

## 1.2 Coated modules

Coated modules are X20 modules with a protective coating for the electronics component. This coating protects X20c modules from condensation and corrosive gases.

The modules' electronics are fully compatible with the corresponding X20 modules.



For simplification purposes, only images and module IDs of uncoated modules are used in this data sheet.

The coating has been certified according to the following standards:

- Condensation: BMW GS 95011-4, 2x 1 cycle
- Corrosive gas: EN 60068-2-60, method 4, exposure 21 days



## 1.3 Order data

Order number	Short description	Figure
	<b>X20 interface module communication</b>	
X20IF1082-2	X20 interface module, 1 POWERLINK interface, managing or controlled node, integrated 2-port hub, ring redundancy function, PRC function	
X20cIF1082-2	X20 interface module, coated, 1 POWERLINK interface, managing or controlled node, integrated 2-port hub, ring redundancy function, PRC function	

Table 1: X20IF1082-2, X20cIF1082-2 - Order data

### Optional accessories

Model number	Short description
X20CA0E61.xxxxx	POWERLINK/Ethernet connection cable, RJ45 to RJ45, 0.2 to 20 m
X20CA0E61.xxxx	POWERLINK/Ethernet connection cable, RJ45 to RJ45, 20 m and longer

## 1.4 Module description

The interface module is used for application-specific expansion of the X20 controllers. It is equipped with a POWERLINK interface.

The interface has two RJ45 sockets. Both connections lead to an integrated hub. This makes it easy to create daisy-chain connections using POWERLINK.

Functions:

- [POWERLINK](#)
- [Configurable ring redundancy](#)

### **POWERLINK**

POWERLINK is a standard protocol for Fast Ethernet equipped with hard real-time characteristics.

### **Redundancy system**

In ring redundancy systems, multiple nodes are connected within a ring and data packets can be transmitted in both directions if needed.

## 2 Technical description

### 2.1 Technical data

Order number	X20IF1082-2	X20cIF1082-2
Short description		
Communication module	1x POWERLINK (V1/V2) managing or controlled node	
General information		
B&R ID code	0xA7A3	0xE236
Status indicators	Module status, bus function	
Diagnostics		
Module status	Yes, using LED status indicator and software	
Bus function	Yes, using LED status indicator and software	
Power consumption	2 W	
Additional power dissipation caused by actuators (resistive) [W]	-	
Certifications		
CE	Yes	
UKCA	Yes	
ATEX	Zone 2, II 3G Ex nA nC IIA T5 Gc IP20, Ta (see X20 user's manual) FTZÚ 09 ATEX 0083X	
UL	cULus E115267 Industrial control equipment	
HazLoc	cCSAus 244665 Process control equipment for hazardous locations Class I, Division 2, Groups ABCD, T5	
DNV	Temperature: <b>B</b> (0 to 55°C) Humidity: <b>B</b> (up to 100%) Vibration: <b>B</b> (4 g) EMC: <b>B</b> (bridge and open deck)	
CCS	Yes	-
LR	ENV1	
KR	Yes	
ABS	Yes	
BV	<b>EC33B</b> Temperature: 5 - 55°C Vibration: 4 g EMC: Bridge and open deck	
KC	Yes	-
Interfaces		
Fieldbus	POWERLINK (V1/V2) managing or controlled node	
Type	Type 4 <sup>1)</sup>	
Variant	2x shielded RJ45 (hub)	
Line length	Max. 100 m between 2 stations (segment length)	
Transfer rate	100 Mbit/s	
Transfer		
Physical layer	100BASE-TX	
Half-duplex	Yes	
Full-duplex	No	
Autonegotiation	Yes	
Auto-MDI/MDIX	Yes	
Hub propagation delay	0.96 to 1 µs	
Controller	POWERLINK MAC	
Electrical properties		
Electrical isolation	PLC isolated from POWERLINK (X1 and X2)	
Operating conditions		
Mounting orientation		
Horizontal	Yes	
Vertical	Yes	
Installation elevation above sea level		
0 to 2000 m	No limitation	
>2000 m	Reduction of ambient temperature by 0.5°C per 100 m	
Degree of protection per EN 60529	IP20	

Table 2: X20IF1082-2, X20cIF1082-2 - Technical data

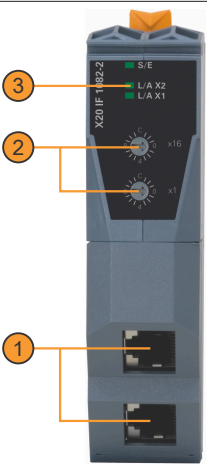
Technical description

Order number	X20IF1082-2		X20cIF1082-2
Ambient conditions			
Temperature			
Operation			
Horizontal mounting orientation	-25 to 60°C		
Vertical mounting orientation	-25 to 50°C		
Derating	-		
Storage	-40 to 85°C		
Transport	-40 to 85°C		
Relative humidity			
Operation	5 to 95%, non-condensing	Up to 100%, condensing	
Storage	5 to 95%, non-condensing		
Transport	5 to 95%, non-condensing		
Mechanical properties			
Slot	In the X20 PLC		In the X20c PLC

Table 2: X20IF1082-2, X20cIF1082-2 - Technical data

1) For additional information, see section "Communication / POWERLINK / General information / Hardware - IF/LS" in Automation Help.

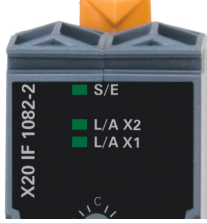
2.2 Operating and connection elements



The diagram shows the front panel of the X20IF1082-2 module. It features a green LED indicator at the top labeled 'S/E'. Below it are two green LEDs labeled 'L/A X2' and 'L/A X1'. A rotary switch with positions 'x1' and 'x16' is located in the middle. At the bottom, there are two RJ45 ports. Numbered callouts point to these features: 1 points to the RJ45 ports, 2 points to the rotary switch, and 3 points to the LEDs.

1	POWERLINK connection with 2x RJ45 for simple wiring	2	Node number switches
3	LED status indicators	4	-

## 2.2.1 LED status indicators

Figure	LED	Color	Status	Description
	S/E	Green/Red		Status/Error LED. The LED indicators are described in section "LED "S/E" (status/error LED)" on page 7.
	L/A X1/X2	Green	On	A link to the remote station has been established.
			Blinking	A link to the remote station has been established. Indicates Ethernet activity is taking place on the bus

### 2.2.1.1 LED "S/E" (status/error LED)

This LED is a green/red dual LED and indicates the state of the POWERLINK interface. The LED states have a different meaning depending on the operating mode of the POWERLINK interface.

#### 2.2.1.1.1 Ethernet mode

In this mode, the interface is operated as an Ethernet interface.

LED "S/E"		Description
Green	Red	
On	Off	The interface is operated as an Ethernet interface.

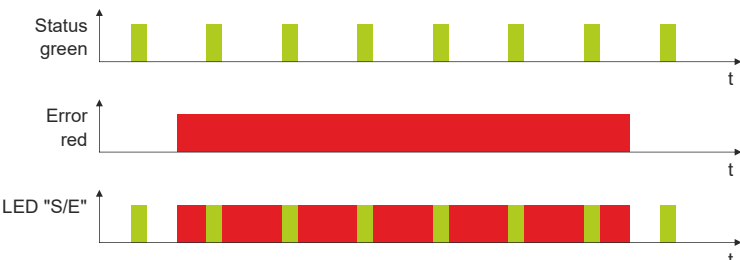
#### 2.2.1.1.2 POWERLINK V1 mode

LED "S/E"		Current state of the POWERLINK node
Green	Red	
On	Off	The POWERLINK node is running with no errors.
Off	On	A system error occurred. The type of error can be read using the PLC logbook. An irreparable problem has occurred. The system can no longer properly carry out its tasks. This state can only be changed by resetting the module.
Blinking alternately		The POWERLINK managing node has failed. This error code can only occur when operated as a controlled node. This means that the set node number lies within the range 0x01 - 0xFD.
Off	Blinking	System stop. The red blinking LED indicates an error code (see "System stop error codes" on page 9).
Off	Off	The interface is either not active or one of the following states or errors is present: <ul style="list-style-type: none"> <li>The device is switched off.</li> <li>The device is in the startup phase.</li> <li>The interface or device is not configured correctly in Automation Studio.</li> <li>The interface or device is defective.</li> </ul>

Table 3: LED "S/E": POWERLINK V1 mode

#### 2.2.1.1.3 POWERLINK V2 mode

##### Error message

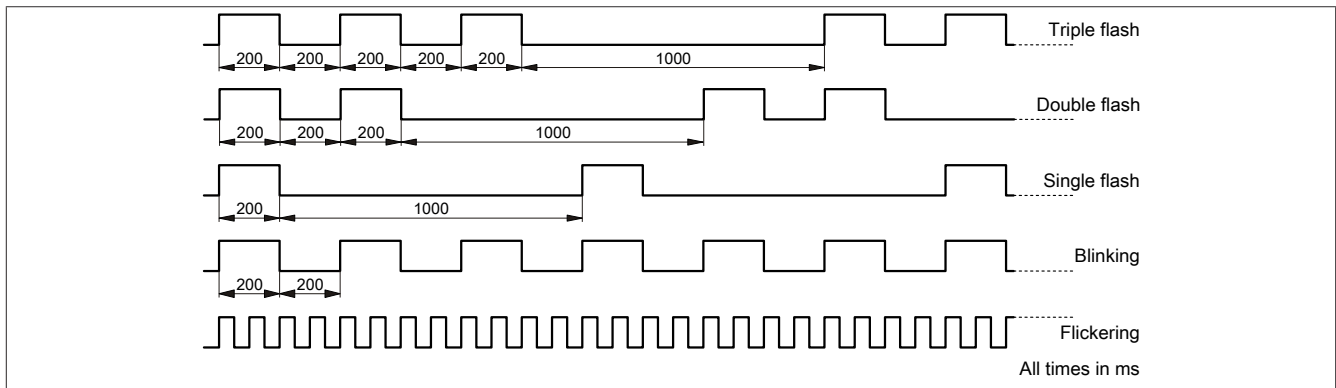
LED "S/E"		Description
Green	Red	
Off	On	The interface is in error mode (failed Ethernet frames, increased number of collisions on the network, etc.). Note: Several red blinking signals are displayed immediately after the device is switched on. These are not errors, however.
Blinking	On	If an error occurs in the following modes, then the green LED blinks over the red LED: <ul style="list-style-type: none"> <li>PRE_OPERATIONAL_1</li> <li>PRE_OPERATIONAL_2</li> <li>READY_TO_OPERATE</li> </ul> 

## Interface status

LED "S/E"		Description
Green	Red	
Off	Off	<p><b>Mode: NOT_ACTIVE</b> The interface is either in mode NOT_ACTIVE or one of the following modes or errors is present:</p> <ul style="list-style-type: none"> <li>The device is switched off.</li> <li>The device is in the startup phase.</li> <li>The interface or device is not configured correctly in Automation Studio.</li> <li>The interface or device is defective.</li> </ul> <p><b>Managing node (MN)</b> The network is monitored for POWERLINK frames. If a frame is not received within the configured time window (time-out), the interface immediately enters mode PRE_OPERATIONAL_1. If POWERLINK communication is detected before the time has elapsed, however, the MN is not started.</p> <p><b>Controlled node (CN)</b> The network is monitored for POWERLINK frames. If a frame is not received within the configured time window (time-out), the interface immediately enters mode BASIC_ETHERNET. If POWERLINK communication is detected before this time expires, however, the interface immediately enters mode PRE_OPERATIONAL_1.</p>
Flickering (approx. 10 Hz)	Off	<p><b>Mode: BASIC_ETHERNET</b> The interface is in mode BASIC_ETHERNET. The interface is operated in <a href="#">Ethernet mode</a>.</p> <p><b>Managing node (MN)</b> This mode can only be exited by resetting the controller.</p> <p><b>Controlled node (CN)</b> If POWERLINK communication is detected during this mode, the interface enters mode PRE_OPERATIONAL_1.</p>
Single flash (approx. 1 Hz)	Off	<p><b>Mode: PRE_OPERATIONAL_1</b> The interface is in mode PRE_OPERATIONAL_1.</p> <p><b>Managing node (MN)</b> The MN is in "reduced cycle" mode. The CNs are configured in this mode. Cyclic communication is not yet taking place.</p> <p><b>Controlled node (CN)</b> The CN can be configured by the MN in this mode. The CN waits until it receives an SoC frame and then switches to mode PRE_OPERATIONAL_2.</p>
	On	<p><b>Controlled node (CN)</b> If the red LED lights up in this mode, this means that the MN has failed.</p>
Double flash (approx. 1 Hz)	Off	<p><b>Mode: PRE_OPERATIONAL_2</b> The interface is in mode PRE_OPERATIONAL_2.</p> <p><b>Managing node (MN)</b> The MN starts cyclic communication (cyclic input data is not yet evaluated). The CNs are configured in this mode.</p> <p><b>Controlled node (CN)</b> The CN can be configured by the MN in this mode. A command then switches the mode to READY_TO_OPERATE.</p>
	On	<p><b>Controlled node (CN)</b> If the red LED lights up in this mode, this means that the MN has failed.</p>
Triple flash (approx. 1 Hz)	Off	<p><b>Mode: READY_TO_OPERATE</b> The interface is in mode READY_TO_OPERATE.</p> <p><b>Managing node (MN)</b> Cyclic and asynchronous communication. Received PDO data is ignored.</p> <p><b>Controlled node (CN)</b> The configuration of the CN is completed. Normal cyclic and asynchronous communication. The transmitted PDO data corresponds to the PDO mapping. However, cyclic data is not yet evaluated.</p>
	On	<p><b>Controlled node (CN)</b> If the red LED lights up in this mode, this means that the MN has failed.</p>
On	Off	<p><b>Mode: OPERATIONAL</b> The interface is in mode OPERATIONAL. PDO mapping is active and cyclic data is evaluated.</p>
Blinking (approx. 2.5 Hz)	Off	<p><b>Mode: STOPPED</b> The interface is in mode STOPPED.</p> <p><b>Managing node (MN)</b> This mode does not occur for the MN.</p> <p><b>Controlled node (CN)</b> Output data is not being output, and no input data is being provided. This mode can only be reached and exited by a corresponding command from the MN.</p>



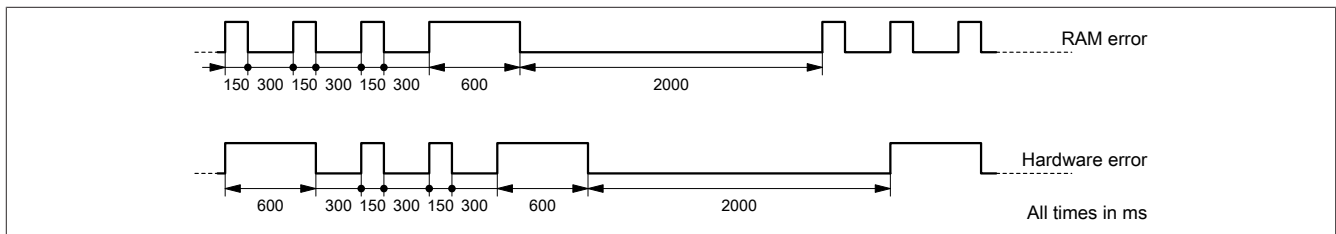
## Blink times



### 2.2.1.1.4 System stop error codes

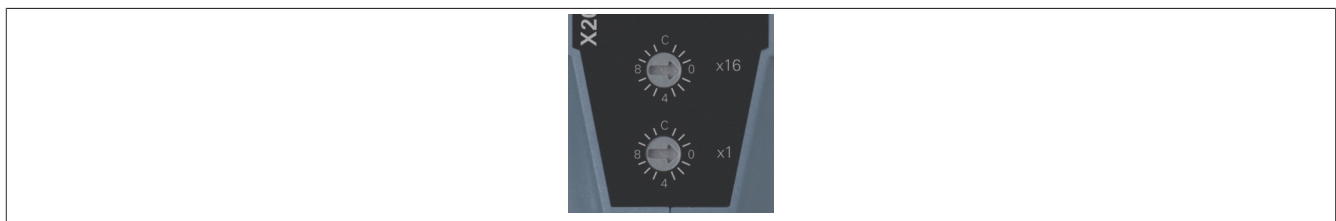
A system stop error can occur due to incorrect configuration or defective hardware.

The error code is indicated by LED "S/E" blinking red. The blinking signal of the error code consists of 4 switch-on phases with short (150 ms) or long (600 ms) duration. The error code is repeated every 2 seconds.



Error	Error description
RAM error	The device is defective and must be replaced.
Hardware error	The device or a system component is defective and must be replaced.

## 2.2.2 POWERLINK node number



The node number for the POWERLINK station is set using the two number switches. The node number can also be directly configured using Automation Studio.

### 2.2.2.1 POWERLINK V1

Switch position	Description
0x00	Operation as managing node.
0x01 - 0xFD	Node number of the POWERLINK node. Operation as controlled node.
0xFE - 0xFF	Reserved, switch position not permitted.

### 2.2.2.2 POWERLINK V2

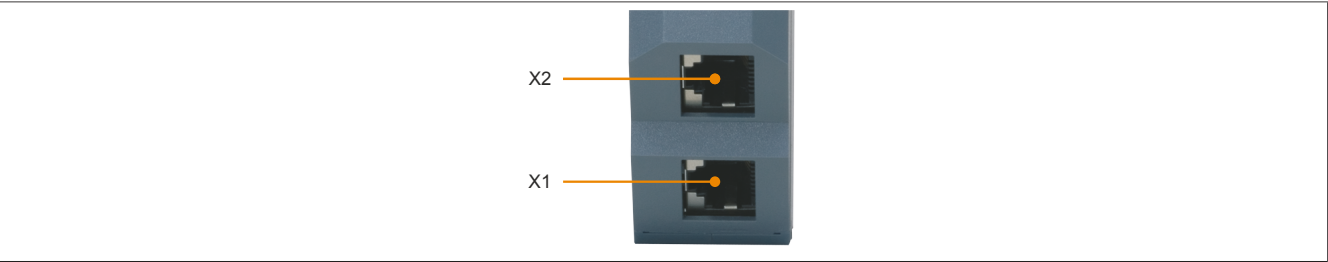
Switch position	Description
0x00	Reserved, switch position not permitted.
0x01 - 0xEF	Node number of the POWERLINK node. Operation as a controlled node (CN).
0xF0	Operation as a managing node (MN).
0xF1 - 0xFF	Reserved, switch position not permitted.

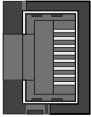
### 2.2.2.3 Ethernet mode

In this mode, the interface is operated as an Ethernet interface. The INA2000 station number is set using the Automation Studio software.

2.2.3 Ethernet interface

For information about wiring X20 modules with an Ethernet interface, see section "Mechanical and electrical configuration - Wiring guidelines for X20 modules with Ethernet cables" in the X20 user's manual.



Interface	Pinout		
	Pin	Ethernet	
 Shielded RJ45	1	RXD	Receive data
	2	RXD\	Receive data\
	3	TXD	Transmit data
	4	Termination	
	5	Termination	
	6	TXD\	Transmit data\
	7	Termination	
	8	Termination	

## 3 Function description

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### 3.1 POWERLINK

POWERLINK is an Ethernet-based, real-time capable fieldbus. POWERLINK extends the IEEE 802.3 Ethernet standard by a deterministic access method and also defines a CANopen-compatible fieldbus interface. POWERLINK distinguishes between process and service data in the same way as CANopen. Process data (PDO) is exchanged cyclically in the cyclic phase, while service data (SDO) is transferred acyclically. Service data objects are transmitted in the acyclic phases of POWERLINK using a connection-oriented protocol. The cyclic transfer of data in PDOs is enabled by "mapping".

For additional information, see [POWERLINK bus controller user's manual](#) and [www.br-automation.com/en/technologies/powerlink](http://www.br-automation.com/en/technologies/powerlink).

### 3.2 POWERLINK redundancy system

It is often indispensable to have redundant network cabling, especially in systems that handle technical processes. The potential for danger, especially to the lines that run through the system, is disproportionately high in relation to the need to keep communication active in all operating situations. This risk is effectively reduced with double cabling that is routed separately.

When using POWERLINK ring redundancy, multiple nodes are connected within a ring. The ring manager must be inside the ring. In normal operation, the ring manager checks the continuity of the ring. However, it does not forward packets and thus prevents them from circulating endlessly in the ring. If a node or line fails, then the test packets sent from one of the ring manager's connections are not received on its other connection. The ring manager transmits the packets in both directions from now on.



#### Information:

Details about the structure of a redundancy system can be found in the "Redundancy for control systems" user's manual. The user's manual is available in the Downloads section of the B&R website [www.br-automation.com](http://www.br-automation.com).

## 4 Commissioning

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### 4.1 Firmware

The module comes with preinstalled firmware. The firmware is part of the Automation Studio project. The module is automatically brought up to this level.

A hardware upgrade must be performed to upgrade the firmware included in Automation Studio (see Help "Project management - Workspace - Upgrades" in Automation Help).