

# Eaton 169054

Catalog Number: 169054

Eaton DA1 Variable frequency drive, 400 V AC, 3-phase, 9.5 A, 4 kW, IP20/NEMA 0, Radio interference suppression filter, 7-digital display assembly



### General specifications

Product Name	Catalog Number
Eaton DA1 Variable frequency drive	169054
EAN	Product Length/Depth
4015081655458	186 mm
Product Height	Product Width
231 mm	107 mm
Product Weight	Certifications
1.8 kg	RoHS, ISO 9001
	Certified by UL for use in Canada
	UL Category Control No.: NMMS, NMMS7
	CE
	CUL
	UL File No.: E172143
	UL report applies to both US and Canada
	IEC/EN61800-5
	EAC
	UkrSEPRO
	IEC/EN61800-3
	Specification for general requirements:
	IEC/EN 61800-2
	UL 508C
	CSA-C22.2 No. 14
	RCM
	IEC/EN 61800-3
	Safety: EN 61800-5-1: 2003
	UL

## General

### Cable length

200 m, screened, with motor choke, maximum permissible, Motor feeder  
100 m, screened, maximum permissible, Motor feeder  
 $C2 \leq 5$  m, Radio interference level, maximum motor cable length  
150 m, unscreened, maximum permissible, Motor feeder  
300 m, unscreened, with motor choke, maximum permissible, Motor feeder  
 $C3 \leq 25$  m, Radio interference level, maximum motor cable length

### Communication interface

EtherCAT, optional  
PROFINET, optional  
DeviceNet, optional  
Modbus-TCP, optional  
OP-Bus (RS485), built in  
CANopen®, built in  
PROFIBUS, optional  
SmartWire-DT, optional  
Modbus RTU, built in  
Ethernet IP, optional

### Connection to SmartWire-DT

Yes  
In conjunction with DX-NET-SWD1 SmartWire DT module

### Degree of protection

IP20  
NEMA Other

### Electromagnetic compatibility

1st and 2nd environments (according to EN 61800-3)

### Fitted with:

Additional PCB protection  
Radio interference suppression filter  
PC connection  
Control unit  
Brake chopper  
Breaking resistance  
7-digital display assembly  
IGBT inverter  
Internal DC link

### Frame size

FS2

## Climatic environmental conditions

### Ambient operating temperature - min

-10 °C

### Altitude

Max. 4000 m  
Above 1000 m with 1 % derating per 100 m  
Max. 1000 m

### Ambient operating temperature - max

50 °C

### Ambient operating temperature at 150% overload - min

-10 °C

### Ambient operating temperature at 150% overload - max

50 °C

### Ambient storage temperature - min

-40 °C

### Ambient storage temperature - max

60 °C

### Climatic proofing

< 95 average relative humidity (RH), no condensation, no corrosion

## Main circuit

### Efficiency

96.6 % (  $\eta$  )

### Heat dissipation at current/speed

111 W at 100% current and 50% speed  
134 W at 100% current and 90% speed  
56 W at 25% current and 0% speed  
56 W at 25% current and 50% speed  
59 W at 50% current and 0% speed  
70 W at 50% current and 50% speed  
85 W at 50% current and 90% speed  
87 W at 100% current and 0% speed

### Input current ILN at 150% overload

11.5 A

### Leakage current at ground IPE - max

4.65 mA

### Mains switch-on frequency

## Functions

4-quadrant operation possible

## Mounting position

Vertical

## Product Category

Variable frequency drives

## Protection

Finger and back-of-hand proof, Protection against direct contact (BGV A3, VBG4)

## Protocol

PROFINET IO

PROFIBUS

MODBUS

CAN

EtherNet/IP

Other bus systems

DeviceNet

TCP/IP

## Safety function/level

STO (Safe Torque Off, SIL2, PLc Cat 2)

## Suitable for

Branch circuits, (UL/CSA)

## Radio interference class

Optional external radio interference suppression filter for longer motor cable lengths and for use in different EMC environments C2, C3: depending on the motor cable length, the connected load, and ambient conditions. External radio interference suppression filters (optional) may be necessary.

Maximum of one time every 30 seconds

## Mains voltage - min

380 V

## Mains voltage - max

480 V

## Operating mode

U/f control

Optional: Vector control with feedback (CLV)

Speed control with slip compensation

Sensorless vector control (SLV)

## Output frequency - min

0 Hz

## Output frequency - max

500 Hz

## Output voltage (U2)

480 V AC, 3-phase

400 V AC, 3-phase

## Overload current IL at 150% overload

14.25 A

## Rated control supply voltage

10 V DC (Us, max. 10 mA)

## Rated frequency - min

48 Hz

## Rated frequency - max

62 Hz

## Rated operational current (Ie) at 150% overload

9.5 A

## Rated operational power at 380/400 V, 50 Hz, 3-phase

4 kW

## Rated operational voltage

400 V AC, 3-phase

480 V AC, 3-phase

## Resolution

0.1 Hz (Frequency resolution, setpoint value)

## Short-circuit protection rating

15 A, UL (Class CC or J), Safety device (fuse or miniature circuit-breaker), Power Wiring

## Starting current - max

200 %, IH, max. starting current (High Overload), for 4 seconds

every 40 seconds, Power section

#### Supply frequency

50/60 Hz

#### Switching frequency

8 kHz, 4 - 32 kHz adjustable (audible), fPWM, Power section,  
Main circuit

#### System configuration type

AC supply systems with earthed center point

#### Voltage rating - max

480 VAC

### Motor rating

Assigned motor current  $I_M$  at 400 V, 50 Hz, 150% overload

8.5 A

Assigned motor current  $I_M$  at 440 - 480 V, 60 Hz, 150% overload

7.6 A

Assigned motor power at 460/480 V, 60 Hz, 3-phase

5 HP

### Apparent power

Apparent power at 400 V

6.58 kVA

Apparent power at 480 V

7.9 kVA

### Braking function

#### Braking resistance

100  $\Omega$

#### Braking torque

Max. 100 % of rated operational current  $I_e$ , variable, DC - Main  
circuit

Max. 30 % MN, Standard - Main circuit

Max. 100 % of rated operational current  $I_e$  with external braking  
resistor - Main circuit

#### Switch-on threshold for the braking transistor

780 VDC

### Control circuit

Number of inputs (analog)

2

Number of inputs (digital)

5

Number of outputs (analog)

2

Number of outputs (digital)

2

Number of relay outputs

2 (parameterizable, 1 N/O and 1 changeover contact, 6 A (250  
V, AC-1) / 5 A (30 V, DC-1))

Rated control voltage ( $U_c$ )

24 V DC (external, max. 100 mA)

### Design verification

Equipment heat dissipation, current-dependent  $P_{vid}$

136 W

Heat dissipation capacity  $P_{diss}$

0 W

### Resources

Application notes

Connecting drives to generator supplies

Update DX-COM-STICK3

Dual Rating What exactly does that mean?

Equal load sharing with the droop function

Heat dissipation per pole, current-dependent P<sub>vid</sub>

0 W

Rated operational current for specified heat dissipation (I<sub>n</sub>)

9.5 A

Static heat dissipation, non-current-dependent P<sub>vs</sub>

0 W

#### 10.2.2 Corrosion resistance

Meets the product standard's requirements.

##### 10.2.3.1 Verification of thermal stability of enclosures

Meets the product standard's requirements.

##### 10.2.3.2 Verification of resistance of insulating materials to normal heat

Meets the product standard's requirements.

##### 10.2.3.3 Resist. of insul. mat. to abnormal heat/fire by internal elect. effects

Meets the product standard's requirements.

#### 10.2.4 Resistance to ultra-violet (UV) radiation

Meets the product standard's requirements.

#### 10.2.5 Lifting

Does not apply, since the entire switchgear needs to be evaluated.

#### 10.2.6 Mechanical impact

Does not apply, since the entire switchgear needs to be evaluated.

#### 10.2.7 Inscriptions

Meets the product standard's requirements.

#### 10.3 Degree of protection of assemblies

Does not apply, since the entire switchgear needs to be evaluated.

#### 10.4 Clearances and creepage distances

Meets the product standard's requirements.

#### 10.6 Incorporation of switching devices and components

Does not apply, since the entire switchgear needs to be evaluated.

#### 10.7 Internal electrical circuits and connections

Is the panel builder's responsibility.

#### 10.8 Connections for external conductors

Is the panel builder's responsibility.

#### 10.9.2 Power-frequency electric strength

Setpoint Setting

Hoist applications

Motor data Motor Protection V/f curves for induction motors

Operating Permanent Magnet and Brushless DC Motors

Master slave operation

I/O Configuration

Starting, Stopping and Operation

PID controller

How does the internal motor protection work?

Electromagnetic compatibility (EMC)

Access to Parameter Level 2 and 3 Parameter Lock RESET

Use of multiple ramps

DX-COM-STICK3\_Connection

Dependency of the output current on switching frequency and ambient temperature

Conformal Coating

The OP System Bus - Parameterizing - Control

Closed Loop Vector Control

Vector Control of Induction Motors

#### Brochures

[eaton-powerxl-variable-frequency-drives-dc1-da1-brochure-br040001en-en-us.pdf](#)

[DA-SW-DA1 Profinet GSDML V2.25 Config File](#)

[DA-SW-DA1 Profinet Library](#)

[DA-SW-drivesConnect](#)

[DA-SW-DA1 Profinet ConfigFile](#)

#### Catalogs

[Product Range Catalog Drives Engineering](#)

#### Declarations of conformity

[DA-DC-00005021.pdf](#)

[DA-DC-00005020.pdf](#)

[DA-DC-00003964.pdf](#)

[DA-DC-00004184.pdf](#)

#### Drawings

[eaton-frequency-inverter-dimensions-027.eps](#)

[eaton-frequency-inverter-3d-drawing-012.eps](#)

#### eCAD model

[DA-CE-ETN.DA1-349D5FB-A20C](#)

#### Installation instructions

Is the panel builder's responsibility.

#### 10.9.3 Impulse withstand voltage

Is the panel builder's responsibility.

#### 10.9.4 Testing of enclosures made of insulating material

Is the panel builder's responsibility.

#### 10.10 Temperature rise

The panel builder is responsible for the temperature rise calculation. Eaton will provide heat dissipation data for the devices.

#### 10.11 Short-circuit rating

Is the panel builder's responsibility. The specifications for the switchgear must be observed.

#### 10.12 Electromagnetic compatibility

Is the panel builder's responsibility. The specifications for the switchgear must be observed.

#### 10.13 Mechanical function

The device meets the requirements, provided the information in the instruction leaflet (IL) is observed.

[eaton-da1-variable-frequency-drive-il04020010z.pdf](#)

#### Installation videos

[Video PowerXL DA1](#)

[PowerXL Variable Frequency Drives DC1 and DA1 - EN](#)

#### Manuals and user guides

[MN040003\\_EN](#)

[eaton-da1-variable-frequency-drive-mn040063-en-us.pdf](#)

[MN04020005Z\\_EN](#)

[MN040018\\_EN](#)

[MN04020006Z\\_EN](#)

[eaton-canopen-communication-manual-for-variable-frequency-drives-variable-speed-starters-da1-db1-dc1-de11-mn040019-en-us.pdf](#)

#### mCAD model

[DA-CS-da1\\_fs2\\_ip20](#)

[DA-CD-da1\\_fs2\\_ip20](#)

#### Multimedia

[System solutions based on EtherCAT](#)

[Looking for variable frequency drives DC1 and DA1 which can be used in harsh environments?](#)

#### Product notifications

[eaton-drives-ecodesign-directive-mz040046en-en.pdf](#)



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