

Eaton 185794

Catalog Number: 185794

Eaton DC1 Variable frequency drive, 230 V AC, 1-phase, 7 A, 1.5 kW, IP20/NEMA 0, Brake chopper, FS2 DC1-127D0NB-A20CE1



General specifications

| Product Name | Catalog Number |
|------------------------------------|---|
| Eaton DC1 Variable frequency drive | 185794 |
| EAN | Product Length/Depth |
| 4015081812936 | 152 mm |
| Product Height | Product Width |
| 231 mm | 107 mm |
| Product Weight | Certifications |
| 2 kg | RoHS, ISO 9001 |
| | IEC/EN61800-5 |
| | UkrSEPRO |
| | UL |
| | UL File No.: E172143 |
| | UL Category Control No.: NMMS, |
| | NMMS7 |
| | Safety requirements: IEC/EN 61800-5-1 |
| | UL 508C |
| | Certified by UL for use in Canada |
| | RCM |
| | CE |
| | CSA-C22.2 No. 14 |
| | CUL |
| | EAC |
| | IEC/EN 61800-3 |
| | IEC/EN61800-3 |
| | Specification for general requirements: |
| | IEC/EN 61800-2 |
| | UL report applies to both US and |
| | Canada |

Features & Functions

Features

Parameterization: drivesConnect

Parameterization: drivesConnect mobile (App)

Parameterization: Fieldbus

Parameterization: Keypad

Fitted with:

Brake chopper

IGBT inverter

7-digital display assembly

Internal DC link

Breaking resistance

Control unit

PC connection

Additional PCB protection

Functions

4-quadrant operation possible

General

Cable length

100 m, screened, maximum permissible, Motor feeder

300 m, unscreened, with motor choke, maximum permissible, Motor feeder

200 m, screened, with motor choke, maximum permissible, Motor feeder

150 m, unscreened, maximum permissible, Motor feeder

Communication interface

Modbus RTU, built in

CANopen®, built in

OP-Bus (RS485), built in

SmartWire-DT, optional

Connection to SmartWire-DT

In conjunction with DX-NET-SWD3 SmartWire DT module

Yes

Degree of protection

IP20

NEMA Other

Frame size

FS2

Mounting position

Vertical

Product category

Variable frequency drives

Protection

Finger and back-of-hand proof, Protection against direct contact (BGV A3, VBG4)

Protocol

CAN

MODBUS

EtherNet/IP

Other bus systems

Radio interference class

Optional external radio interference suppression filter for longer motor cable lengths and for use in different EMC environments

Suitable for

Branch circuits, (UL/CSA)

Climatic environmental conditions

Altitude

Max. 4000 m

Above 1000 m with 1 % derating per 100 m

Ambient operating temperature - min

-10 °C

Ambient operating temperature - max

50 °C

Ambient operating temperature at 150% overload - min

-10 °C

Ambient operating temperature at 150% overload - max

50 °C

Ambient storage temperature - min

-40 °C

Ambient storage temperature - max

60 °C

Climatic proofing

< 95 average relative humidity (RH), no condensation, no corrosion

Main circuit

Efficiency

95.8 % (η)

Heat dissipation capacity P_{diss}

0 W

Input current I_{LN} at 150% overload

12.9 A

Leakage current at ground IPE - max

4.8 mA

Mains switch-on frequency

Maximum of one time every 30 seconds

Mains voltage - min

200 V

Mains voltage - max

240 V

Operating mode

U/f control

Sensorless vector control (SLV)

Speed control with slip compensation

BLDC motors

PM motors

Synchronous reluctance motors

Output frequency - min

0 Hz

Output frequency - max

500 Hz

Output voltage (U_2)

230 V AC, 3-phase

240 V AC, 3-phase

Overload current I_L at 150% overload

10.5 A

Rated control supply voltage

10 V DC (U_s , max. 10 mA)

Rated frequency - min

48 Hz

Rated frequency - max

62 Hz

Rated operational current (Ie)

7 A at 150% overload (at an operating frequency of 16 kHz and an ambient air temperature of +50 °C)

Rated operational voltage

230 V AC, 1-phase
240 V AC, 1-phase

Resolution

0.1 Hz (Frequency resolution, setpoint value)

Short-circuit protection rating

15 A, UL (Class CC or J), Safety device (fuse or miniature circuit-breaker), Power Wiring

Starting current - max

175 %, IH, max. starting current (High Overload), For 2.5 seconds every 600 seconds, Power section

Supply frequency

50/60 Hz

Switching frequency

8 kHz, 4 - 32 kHz adjustable (audible), fPWM, Power section, Main circuit

System configuration type

AC supply systems with earthed center point

Voltage rating - max

240 V

Apparent power

Apparent power at 230 V

2.79 kVA

Apparent power at 240 V

2.91 kVA

Control circuit

Number of inputs (analog)

Motor rating

Assigned motor current IM at 110/120 V, 60 Hz, 150% overload

6.8 A

Assigned motor current IM at 115 V, 50 Hz, 150% overload

6.3 A

Assigned motor current IM at 220 - 240 V, 60 Hz, 150% overload

6.8 A

Assigned motor current IM at 230 V, 50 Hz, 150% overload

6.3 A

Assigned motor current IM at 400 V, 50 Hz, 150% overload

6.3 A

Assigned motor current IM at 440 - 480 V, 60 Hz, 150% overload

6.8 A

Assigned motor power at 115/120 V, 60 Hz, 1-phase

2 HP

Assigned motor power at 230/240 V, 60 Hz, 1-phase

2 HP

Assigned motor power at 460/480 V, 60 Hz

2 HP

Assigned motor power at 460/480 V, 60 Hz, 3-phase

2 HP

Braking function

Braking resistance

100 Ω

Braking torque

Max. 30 % MN, Standard - Main circuit
Max. 100 % of rated operational current Ie with external braking resistor - Main circuit
Max. 100 % of rated operational current Ie, variable, DC - Main circuit

Switch-on threshold for the braking transistor

390 VDC

Design verification

Equipment heat dissipation, current-dependent Pvid

2 (parameterizable, 0 - 10 V DC, 0/4 - 20 mA)

Number of inputs (digital)

4 (parameterizable, 10 - 30 V DC)

Number of outputs (analog)

1

Number of outputs (digital)

1

Number of relay outputs

1 (parameterizable, N/O, 6 A (250 V, AC-1) / 5 A (30 V, DC-1))

63 W

Heat dissipation capacity P_{diss}

0 W

Heat dissipation per pole, current-dependent P_{vid}

0 W

Rated operational current for specified heat dissipation (I_n)

7 A

Static heat dissipation, non-current-dependent P_{vs}

0 W

10.2.2 Corrosion resistance

Meets the product standard's requirements.

10.2.3.1 Verification of thermal stability of enclosures

Meets the product standard's requirements.

10.2.3.2 Verification of resistance of insulating materials to normal heat

Meets the product standard's requirements.

10.2.3.3 Resist. of insul. mat. to abnormal heat/fire by internal elect. effects

Meets the product standard's requirements.

10.2.4 Resistance to ultra-violet (UV) radiation

Meets the product standard's requirements.

10.2.5 Lifting

Does not apply, since the entire switchgear needs to be evaluated.

10.2.6 Mechanical impact

Does not apply, since the entire switchgear needs to be evaluated.

10.2.7 Inscriptions

Meets the product standard's requirements.

10.3 Degree of protection of assemblies

Does not apply, since the entire switchgear needs to be evaluated.

10.4 Clearances and creepage distances

Meets the product standard's requirements.

10.5 Protection against electric shock

Does not apply, since the entire switchgear needs to be evaluated.

10.6 Incorporation of switching devices and components

Does not apply, since the entire switchgear needs to be

evaluated.

10.7 Internal electrical circuits and connections

Is the panel builder's responsibility.

10.8 Connections for external conductors

Is the panel builder's responsibility.

10.9.2 Power-frequency electric strength

Is the panel builder's responsibility.

10.9.3 Impulse withstand voltage

Is the panel builder's responsibility.

10.9.4 Testing of enclosures made of insulating material

Is the panel builder's responsibility.

10.10 Temperature rise

The panel builder is responsible for the temperature rise calculation. Eaton will provide heat dissipation data for the devices.

10.11 Short-circuit rating

Is the panel builder's responsibility. The specifications for the switchgear must be observed.

10.12 Electromagnetic compatibility

Is the panel builder's responsibility. The specifications for the switchgear must be observed.

10.13 Mechanical function

The device meets the requirements, provided the information in the instruction leaflet (IL) is observed.

Resources

Application notes

[Starting, Stopping and Operation](#)

[Electromagnetic compatibility \(EMC\)](#)

[How does the internal motor protection work?](#)

[Update DX-COM-STICK3](#)

[Connecting drives to generator supplies](#)

[Access to Parameter Levels 2 + 3 Parameter Lock - Load Default](#)

[Operating Single Phase Motors](#)

[Fire Mode](#)

[Low Temperature Applications](#)

[Operating Permanent Magnet and Brushless DC Motors](#)

[DX-COM-STICK3_Connection](#)

[PI controller](#)

[Set Point Setting](#)

[I/O Configuration](#)

[Dependency of the output current on switching frequency and ambient temperature](#)

[Conformal Coating](#)

[The OP System Bus - Parameterizing - Control](#)

[Motor data - Motor Protection - V/f curves Slip Compensation](#)

Brochures

[eaton-powerxl-variable-frequency-drives-dc1-da1-brochure-br040001en-en-us.pdf](#)

[DA-SW-drivesConnect](#)

Catalogs

[Product Range Catalog Drives Engineering](#)

Declarations of conformity

[DA-DC-00003964.pdf](#)

[DA-DC-00004555.pdf](#)

[DA-DC-00004184.pdf](#)

[DA-DC-00004552.pdf](#)

Drawings

[eaton-frequency-inverter-dimensions-026.eps](#)

[eaton-frequency-inverter-dimensions-016.eps](#)

[eaton-frequency-inverter-3d-drawing-006.eps](#)

eCAD model

[DA-CE-ETN.DC1-127D0NB-A20CE1](#)

Installation instructions

[IL04020009Z](#)

Installation videos

[PowerXL Variable Frequency Drives DC1 and DA1 - EN](#)

[Video PowerXL DA1](#)

Manuals and user guides

[MN040059_EN](#)

[MN040018_EN](#)

[MN040003_EN](#)

[MN040022_EN](#)

[eaton-canopen-communication-manual-for-variable-frequency-drives-variable-speed-starters-da1-db1-dc1-de11-mn040019-en-us.pdf](#)

mCAD model

[DA-CS-dc1_fs2](#)

[DA-CD-dc1_fs2](#)

Multimedia

[Looking for variable frequency drives DC1 and DA1 which can be used in harsh environments?](#)

Product notifications

[eaton-drives-ecodesign-directive-mz040046en-en.pdf](#)



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