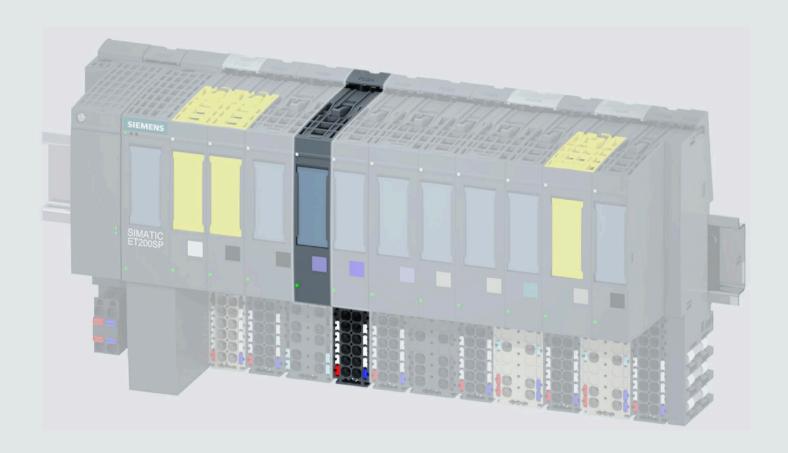
# **SIEMENS**



Manual

# **SIMATIC**

# **ET 200SP**

Analog input module AI 2xU/I 2-/4-wire HF (6ES7134-6HB00-0CA1)

Edition

05/2021

support.industry.siemens.com

# **SIEMENS**

## **SIMATIC**

ET 200SP Analog input module AI 2xU/I 2-/4-wire HF (6ES7134-6HB00-0CA1)

**Equipment Manual** 

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### Legal information

#### Warning notice system

This manual contains notices you have to observe in order to ensure your personal safety, as well as to prevent damage to property. The notices referring to your personal safety are highlighted in the manual by a safety alert symbol, notices referring only to property damage have no safety alert symbol. These notices shown below are graded according to the degree of danger.

### DANGER

indicates that death or severe personal injury will result if proper precautions are not taken.

### **MARNING**

indicates that death or severe personal injury may result if proper precautions are not taken.

### **A**CAUTION

indicates that minor personal injury can result if proper precautions are not taken.

#### NOTICE

indicates that property damage can result if proper precautions are not taken.

If more than one degree of danger is present, the warning notice representing the highest degree of danger will be used. A notice warning of injury to persons with a safety alert symbol may also include a warning relating to property damage.

#### **Qualified Personnel**

The product/system described in this documentation may be operated only by **personnel qualified** for the specific task in accordance with the relevant documentation, in particular its warning notices and safety instructions. Qualified personnel are those who, based on their training and experience, are capable of identifying risks and avoiding potential hazards when working with these products/systems.

#### **Proper use of Siemens products**

Note the following:

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Siemens products may only be used for the applications described in the catalog and in the relevant technical documentation. If products and components from other manufacturers are used, these must be recommended or approved by Siemens. Proper transport, storage, installation, assembly, commissioning, operation and maintenance are required to ensure that the products operate safely and without any problems. The permissible ambient conditions must be complied with. The information in the relevant documentation must be observed.

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#### **Disclaimer of Liability**

We have reviewed the contents of this publication to ensure consistency with the hardware and software described. Since variance cannot be precluded entirely, we cannot guarantee full consistency. However, the information in this publication is reviewed regularly and any necessary corrections are included in subsequent editions.

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Preface

### 1.1 Open Source Software

Open-source software is used in the firmware of the I/O modules. Open Source Software is provided free of charge. We are liable for the product described, including the open-source software contained in it, pursuant to the conditions applicable to the product. Siemens accepts no liability for the use of the open source software over and above the intended program sequence, or for any faults caused by modifications to the software.

For legal reasons, we are obliged to publish the original text of the license conditions and copyright notices. Please read the information relating to this on the Internet (https://support.industry.siemens.com/cs/ww/en/view/109739516).

#### See also

GNU V5.3.1 201805 (https://support.industry.siemens.com/cs/ww/en/view/109757558)

### 1.2 Security information

Siemens provides products and solutions with industrial security functions that support the secure operation of plants, systems, machines and networks.

In order to protect plants, systems, machines and networks against cyber threats, it is necessary to implement – and continuously maintain – a holistic, state-of-the-art industrial security concept. Siemens' products and solutions constitute one element of such a concept.

Customers are responsible for preventing unauthorized access to their plants, systems, machines and networks. Such systems, machines and components should only be connected to an enterprise network or the internet if and to the extent such a connection is necessary and only when appropriate security measures (e.g. firewalls and/or network segmentation) are in place.

For additional information on industrial security measures that may be implemented, please visit (https://www.siemens.com/industrialsecurity).

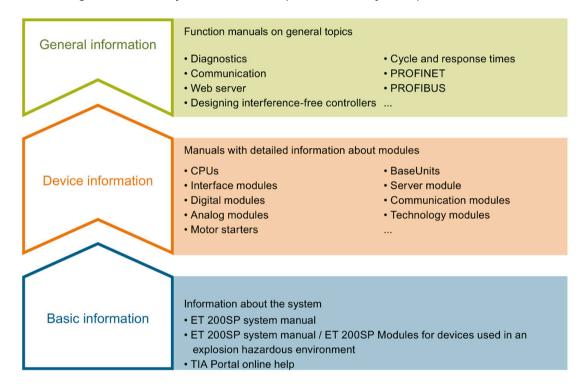
Siemens' products and solutions undergo continuous development to make them more secure. Siemens strongly recommends that product updates are applied as soon as they are available and that the latest product versions are used. Use of product versions that are no longer supported, and failure to apply the latest updates may increase customers' exposure to cyber threats.

To stay informed about product updates, subscribe to the Siemens Industrial Security RSS Feed visit (<a href="https://www.siemens.com/industrialsecurity">https://www.siemens.com/industrialsecurity</a>).

ET 200SP Documentation Guide

The documentation for the SIMATIC ET 200SP distributed I/O system is arranged into three areas.

This arrangement enables you to access the specific content you require.



#### **Basic information**

The System Manual and Getting Started describe in detail the configuration, installation, wiring and commissioning of the SIMATIC ET 200SP distributed I/O system. The STEP 7 online help supports you in the configuration and programming.

#### **Device information**

Product manuals contain a compact description of the module-specific information, such as properties, wiring diagrams, characteristics and technical specifications.

#### **General information**

The function manuals contain detailed descriptions on general topics regarding the SIMATIC ET 200SP distributed I/O system, e.g. diagnostics, communication, Web server, motion control and OPC UA.

You can download the documentation free of charge from the Internet (https://support.industry.siemens.com/cs/ww/en/view/109742709).

Changes and supplements to the manuals are documented in a Product Information.

You can download the product information free of charge from the Internet (<a href="https://support.industry.siemens.com/cs/us/en/view/73021864">https://support.industry.siemens.com/cs/us/en/view/73021864</a>).

#### Manual Collection ET 200SP

The Manual Collection contains the complete documentation on the SIMATIC ET 200SP distributed I/O system gathered together in one file.

You can find the Manual Collection on the Internet (https://support.automation.siemens.com/WW/view/en/84133942).

### "mySupport"

With "mySupport", your personal workspace, you make the best out of your Industry Online Support.

In "mySupport", you can save filters, favorites and tags, request CAx data and compile your personal library in the Documentation area. In addition, your data is already filled out in support requests and you can get an overview of your current requests at any time.

You must register once to use the full functionality of "mySupport".

You can find "mySupport" on the Internet (https://support.industry.siemens.com/My/ww/en).

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In "mySupport", you can save filters, favorites and tags, request CAx data and compile your personal library in the Documentation area. In addition, your data is already filled out in support requests and you can get an overview of your current requests at any time.

You must register once to use the full functionality of "mySupport".

You can find "mySupport" on the Internet (https://support.industry.siemens.com/My/ww/en/documentation).

### "mySupport" - CAx data

In the CAx data area of "mySupport", you can access the latest product data for your CAx or CAe system.

You configure your own download package with a few clicks.

In doing so you can select:

- Product images, 2D dimension drawings, 3D models, internal circuit diagrams, EPLAN macro files
- Manuals, characteristics, operating manuals, certificates
- · Product master data

You can find "mySupport" - CAx data on the Internet (https://support.industry.siemens.com/my/ww/en/CAxOnline).

### **Application examples**

The application examples support you with various tools and examples for solving your automation tasks. Solutions are shown in interplay with multiple components in the system - separated from the focus on individual products.

You will find the application examples on the Internet (https://support.industry.siemens.com/cs/ww/en/ps/ae).

#### **TIA Selection Tool**

With the TIA Selection Tool, you can select, configure and order devices for Totally Integrated Automation (TIA).

This tool is the successor of the SIMATIC Selection Tool and combines the known configurators for automation technology into one tool.

With the TIA Selection Tool, you can generate a complete order list from your product selection or product configuration.

You can find the TIA Selection Tool on the Internet (https://support.industry.siemens.com/cs/ww/en/view/109767888).

#### **SIMATIC Automation Tool**

You can use the SIMATIC Automation Tool to perform commissioning and maintenance activities simultaneously on various SIMATIC S7 stations as a bulk operation independent of TIA Portal.

The SIMATIC Automation Tool provides a multitude of functions:

- Scanning of a PROFINET/Ethernet system network and identification of all connected CPUs
- Address assignment (IP, subnet, gateway) and station name (PROFINET device) to a CPU
- Transfer of the date and the programming device/PC time converted to UTC time to the module
- Program download to CPU
- RUN/STOP mode switchover
- CPU localization by means of LED flashing
- Reading out of CPU error information
- Reading of the CPU diagnostics buffer
- Reset to factory settings
- Firmware update of the CPU and connected modules

You can find the SIMATIC Automation Tool on the Internet (https://support.industry.siemens.com/cs/ww/en/view/98161300).

#### **PRONETA**

SIEMENS PRONETA (PROFINET network analysis) allows you to analyze the plant network during commissioning. PRONETA features two core functions:

- The topology overview automatically scans the PROFINET and all connected components.
- The IO check is a fast test of the wiring and the module configuration of a plant, incl. failsafe inputs and outputs.

You can find SIEMENS PRONETA on the Internet (https://support.industry.siemens.com/cs/ww/en/view/67460624).

#### **SINETPLAN**

SINETPLAN, the Siemens Network Planner, supports you in planning automation systems and networks based on PROFINET. The tool facilitates professional and predictive dimensioning of your PROFINET installation as early as in the planning stage. In addition, SINETPLAN supports you during network optimization and helps you to exploit network resources optimally and to plan reserves. This helps to prevent problems in commissioning or failures during productive operation even in advance of a planned operation. This increases the availability of the production plant and helps improve operational safety.

The advantages at a glance

- Network optimization thanks to port-specific calculation of the network load
- Increased production availability thanks to online scan and verification of existing systems
- Transparency before commissioning through importing and simulation of existing STEP 7 projects
- Efficiency through securing existing investments in the long term and the optimal use of resources

You can find SINETPLAN on the Internet (https://www.siemens.com/sinetplan).

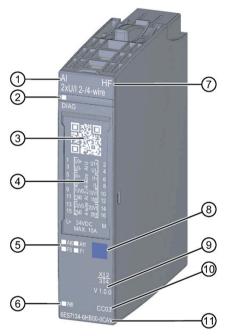
Product overview 3

## 3.1 Properties

### Article number

6ES7134-6HB00-0CA1

### View of the module



- ① Module type and name
- ② LED for diagnostics
- 3 2D matrix code
- 4 Wiring diagram
- (5) LEDs for channel status
- 6 LED for supply voltage
- Function class
- 8 Color coding module type
- 9 Function and firmware version
- (10) Color code for selecting the color identification labels
- 11) Article number

Figure 3-1 View of the module AI 2×U/I 2-/4-wire HF

#### 3.1 Properties

### **Properties**

The module has the following technical properties:

- · Analog input module with 2 inputs
- Resolution: Up to 16 bits including sign
- Single channel electrical isolation
- · Voltage measurement type can be set per channel
- Current measuring type can be set per channel (for 2-wire or 4-wire transducer)
- Configurable diagnostics for each channel

The module supports the following functions:

- · Firmware update
- · I&M identification data
- Configuration in RUN
- PROFlenergy
- Calibration in runtime
- Isochronous mode (PROFINET IO only)
- Value status (PROFINET IO only)

Table 3-1 Version dependencies of other module functions

Function	Product version of the module as of	Firmware version of the module as of
Measuring range adjustment	1	V2.0.0
Scaling of measured values	1	V2.0.0
Module-internal shared input (MSI)	1	V2.0.0

You can configure the module with STEP 7 (TIA Portal) and with a GSD file.

More information about version dependency of the GSD file is available on the Internet (https://support.industry.siemens.com/cs/ww/en/view/57138621).

#### Accessories

The following accessories must be ordered separately:

- · Labeling strips
- Color identification labels
- Reference identification label
- Shield connector

#### See also

You can find additional information on the accessories in the ET 200SP distributed I/O system (<a href="https://support.industry.siemens.com/cs/ww/en/view/58649293">https://support.industry.siemens.com/cs/ww/en/view/58649293</a>) system manual.

Wiring

### 4.1 Wiring and block diagram

This section includes the block diagram of the AI 2xU/I 2-/4-wire HF module with the various terminal assignments for a 2- und 4-wire connection.

You can find information on wiring the BaseUnit in the ET 200SP distributed I/O system (http://support.automation.siemens.com/WW/view/en/58649293) system manual.

#### Note

You can use and combine the different wiring options for all channels.

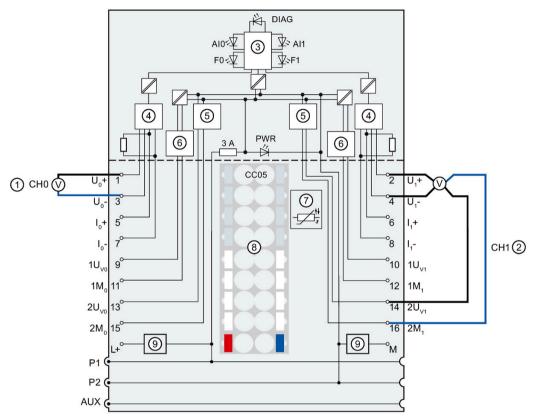
#### Note

The load group of the module must begin with a light-colored BaseUnit. Keep this in mind also during the configuration.

### 4.1 Wiring and block diagram

### Wiring: Voltage measurement 2-wire and 4-wire connection

The following figure shows the block diagram and an example of the terminal assignment of the analog input module AI 2xU/I 2-/4-wire HF on the BaseUnit BU type AO/A1.



1	2-wire connection for voltage measurement	In+	Current input positive, channel n
2	4-wire connection for voltage measurement	In-	Current input negative, channel n
3	Backplane bus interface	Uvn	Supply voltage, channel n
4	Analog-to-digital converter (ADC)	Mn	Reference ground to Uvn, channel n
5	Current limitation (4-wire)	L+	24 V DC (infeed only with light-colored BaseUnit)
6	Current limitation (2-wire)	P1, P2, AUX	Internal self-assembling voltage buses Connection to left (dark-colored BaseUnit) Connection to left interrupted (light-colored BaseUnit)
7	Temperature recording for BU type A1 only (function cannot be used for this module)	DIAG	Diagnostics LED (green, red)
8	Color-coded label with color code CC05 (optional)	AIO, AI1	Channel status LED (green)
9	Filter connection supply voltage (only when light-colored BaseUnit is present)	F0, F1	Channel fault LED (red)
Un+	Voltage input positive, channel n	PWR	Power LED (green)
Un-	Voltage input negative, channel n		

Figure 4-1 Wiring and block diagram for voltage measurement 2-wire and 4-wire connection

4.1 Wiring and block diagram

#### Note

A connection between the current inputs  $I_{\text{\tiny D}}$  and the reference ground  $M_{\text{\tiny D}}$  is not allowed and leads to malfunctions of the module.

#### 4.1 Wiring and block diagram

### Wiring: Voltage and current measurement 3-wire connection

The following figure shows the block diagram and an example of the terminal assignment of the analog input module AI 2xU/I 2-/4-wire HF on the BaseUnit BU type AO/A1.

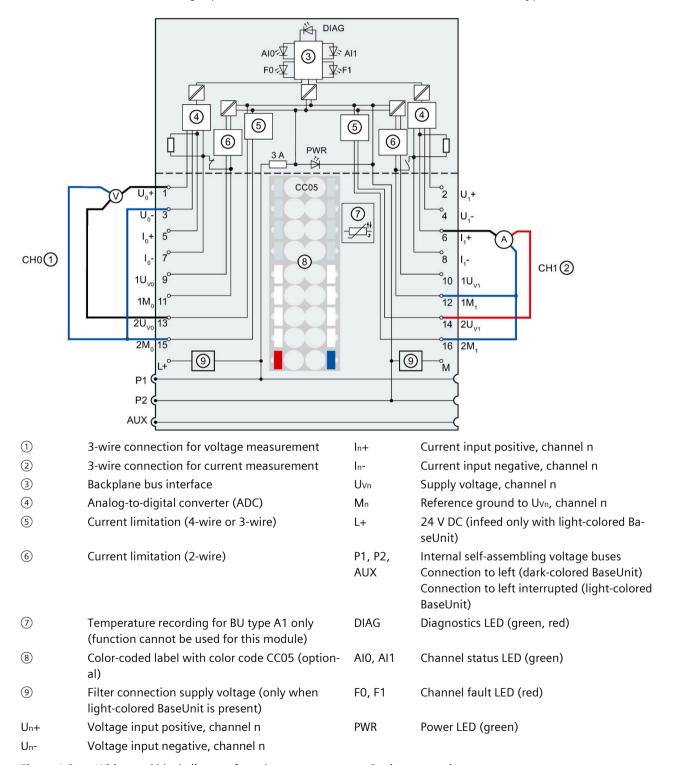
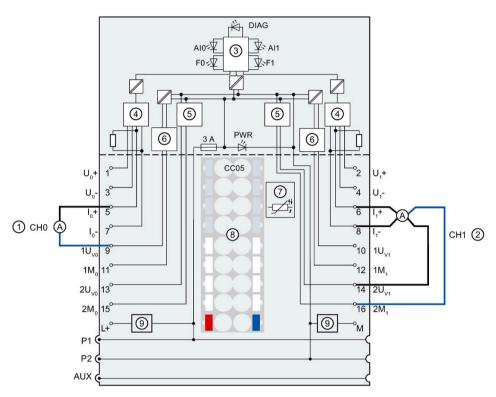


Figure 4-2 Wiring and block diagram for voltage measurement 3-wire connection

### Wiring: Current measurement 2-wire and 4-wire connection (2-wire and 4-wire transducer)

The following figure shows the block diagram and an example of the terminal assignment of the analog input module AI 2xU/I 2-/4-wire HF on the BaseUnit BU type AO/A1.



1	2-wire connection for current measurement (2-wire transducer)	Un+	Voltage input positive, channel n
2	4-wire connection for current measurement (4-wire transducer)	Un-	Voltage input negative, channel n
3	Backplane bus interface	Uvn	Supply voltage, channel n
4	Analog-to-digital converter (ADC)	Mn	Reference ground to Uvn, channel n
5	Current limitation (4-wire)	L+	24 V DC (infeed only with light-colored BaseUnit)
6	Current limitation (2-wire)	P1, P2, AUX	Internal self-assembling voltage buses Connection to left (dark-colored BaseUnit) Connection to left interrupted (light-colored BaseUnit)
7	Temperature recording for BU type A1 only (function cannot be used for this module)	DIAG	Diagnostics LED (green, red)
8	Color-coded label with color code CC05 (optional)	AIO, AI1	Channel status LED (green)
9	Filter connection supply voltage (only when light-colored BaseUnit is present)	F0, F1	Channel fault LED (red)
In+	Current input positive, channel n	PWR	Power LED (green)
In-	Current input negative, channel n		

Figure 4-3 Wiring and block diagram for current measurement 2-wire and 4-wire connection (2-wire and 4-wire transducer)

Parameters/address space

### 5.1 Measurement types and measuring ranges

The following table shows the measurement types and the respective measuring range.

Table 5-1 Measurement types and measuring ranges

Measurement type	Measuring range	Resolution
Voltage	± 5 V	16 bits incl. sign
	± 10 V	16 bits incl. sign
	1 to 5 V	15 bits
	0 to 10 V	15 bits
Current	0 to 20 mA (2-wire and 4-wire transducer)	15 bits
	4 to 20 mA (2-wire and 4-wire transducer)	15 bits
	± 20 mA (only with 4-wire transducer)	16 bit including sign

You can find the tables of measuring ranges and overflow, overrange, etc. in the appendix Representation of analog values (Page 67) and the "Analog value processing" function manual.

### Measuring range adjustment

See Measuring range adjustment (Page 30).

### Scaling of measured values

See Scaling of measured values (Page 34).

### 5.2 Parameters

#### Parameters of the AI 2xU/I 2-/4-wire HF

The following table lists the configurable parameters. The effective range of the configurable parameters depends on the type of configuration. The following configurations are possible:

- Central operation with an ET 200SP CPU
- Distributed operation on PROFINET IO in an ET 200SP system
- Distributed operation on PROFIBUS DP in an ET 200SP system

When assigning parameters in the user program, use the WRREC instruction to transfer the parameters to the module by means of data records; refer to the section Parameter assignment and structure of parameter data record (Page 55).

The following parameter settings are possible:

Table 5-2 Configurable parameters and their defaults (GSD file)

Parameter	Range of values	Default	Default Configuration Scope with configuration in RUN ware, e.g. STEP 7 (T		_
				GSD file PROFINET IO	GSD file PROFIBUS DP
Diagnostics No supply voltage L+	<ul><li>Disable</li><li>Enable</li></ul>	Disable	Yes	Channel	Channel
Diagnostics: Short-circuit to ground	<ul><li>Disable</li><li>Enable</li></ul>	Disable	Yes	Channel	Channel
Diagnostics: Overflow	<ul><li>Disable</li><li>Enable</li></ul>	Disable	Yes	Channel	Channel
Diagnostics: Underflow	<ul><li>Disable</li><li>Enable</li></ul>	Disable	Yes	Channel	Channel
Diagnostics: Wire break	<ul><li>Disable</li><li>Enable</li></ul>	Disable	Yes	Channel	Channel

Parameter	Range of values		Configuration in RUN	Scope with configuration software, e.g. STEP 7 (TIA Portal)	
				GSD file PROFINET IO	GSD file PROFIBUS DP
Measurement type/measuring range	<ul> <li>Deactivated</li> <li>Voltage         <ul> <li>±5 V</li> <li>±10 V</li> <li>1 V to 5 V</li> <li>0 V to 10 V</li> </ul> </li> <li>Current (4-wire transducer)         <ul> <li>0 to 20 mA</li> <li>±20 mA</li> </ul> </li> <li>Current (2-wire transducer)         <ul> <li>0 to 20 mA</li> <li>4 to 20 mA</li> </ul> </li> <li>4 to 20 mA</li> <li>4 to 20 mA</li> <li>4 to 20 mA</li> </ul>	Current (4-wire transducer) 420 mA	Yes	Channel	Channel
Smoothing	<ul><li>None</li><li>2 times</li><li>4 times</li><li>8 times</li><li>16 times</li><li>32 times</li></ul>	None	Yes	Channel	Channel
Interference frequency suppression <sup>2</sup>	<ul> <li>16.6 Hz (67.5 ms)</li> <li>50 Hz (22.5 ms)</li> <li>60 Hz (18.75 ms)</li> <li>300 Hz (10 ms)</li> <li>600 Hz (5 ms)</li> <li>1.2 kHz (2.5 ms)</li> <li>2.4 kHz (1.25 ms)</li> <li>4.8 kHz (0.625 ms)</li> </ul>	50 Hz (22.5 ms)	Yes	Channel	Channel
Adjust measuring range	<ul><li>Disable</li><li>Enable</li></ul>	Disable	Yes	Channel	-
Measuring range adjustment high limit <sup>1</sup>	Value within the nomi- nal range of the meas- uring range in mV or µA	0	Yes	Channel	-
Measuring range adjustment low limit <sup>1</sup>	Value within the nominal range of the measuring range in mV or µA	0	Yes	Channel	-
Scaled high nominal range limit <sup>3</sup>	REAL	20.0	Yes	Channel	-

#### 5.2 Parameters

Parameter	Range of values		Configuration in RUN	Scope with configuration software, e.g. STEP 7 (TIA Portal)	
				GSD file PROFINET IO	GSD file PROFIBUS DP
Scaled low nominal range limit <sup>3</sup>	REAL	4.0	Yes	Channel	-
Hardware interrupt high limit 1 <sup>1</sup>	<ul><li>Disable</li><li>Enable</li></ul>	Disable	Yes	Channel	-
High limit 1 <sup>1</sup>	Value (INT) Value (REAL) <sup>3</sup>	• 276480 • 0.0 <sup>3</sup>	Yes	Channel	-
Hardware interrupt low limit 1 <sup>1</sup>	Disable     Enable	Disable	Yes	Channel	-
Low limit 1 <sup>1</sup>	Value (INT) Value (REAL) <sup>3</sup>	• 0 • 0.0 <sup>3</sup>	Yes	Channel	-
Hardware interrupt high limit 2 <sup>1</sup>	Disable     Enable	Disable	Yes	Channel	-
High limit 2 <sup>1</sup>	Value (INT) Value (REAL) <sup>3</sup>	• 27648 • 0.0 <sup>3</sup>	Yes	Channel	-
Hardware interrupt low limit 2 <sup>1</sup>	<ul><li>Disable</li><li>Enable</li></ul>	Disable	Yes	Channel	-
Low limit 2 <sup>1</sup>	Value (INT) Value (REAL) <sup>3</sup>	• 0 • 0.0 <sup>3</sup>	Yes	Channel	-
Potential group	Use potential group of the left module (dark-colored Ba- seUnit)	Use potential group of the left module (dark- colored BaseUnit)	No	Module	Module
	Enable new poten- tial group (light- colored BaseUnit)				

Due to the limited number of parameters at a maximum of 244 bytes per ET 200SP station with a PROFIBUS GSD configuration, the configuration options are restricted. If required, you can assign these parameters using data record 128 as described in the "GSD file PROFINET IO" column (see table above). The parameter length of the I/O module is 7 bytes.

In normal operation, different interference frequency suppression settings can be configured for both channels. These cause different integration times for the analog-to-digital conversion. The module-internal time for updating the user data is now based on the longer integration time for both channels.
In isochronous mode, both channels must be configured with the same interference frequency suppression of 4.8 kHz.

<sup>&</sup>lt;sup>3</sup> Only for configuration SCALE.

#### Note

For the 3-wire connection configure the parameter "Type/range of measurement" with "Current (4-wire transducer) 0..20 mA" or "Current (4-wire transducer) 4..20 mA".

#### Note

#### Unused channels

Deactivate the unused inputs in the parameter assignment.

A deactivated channel always returns the value 7FFFH (with configuration SCALE: 7F800000H).

#### Note

Note that the settings in the "Interference frequency suppression" parameter have a direct effect on the cycle time of the module. The analog value is therefore also affected by additionally set filtering via the "Smoothing" parameter.

### Property of the module in isochronous mode

The permitted interference frequency suppression of both channels for isochronous mode of the modules is 4.8 kHz (0.625 ms).

Note that no instantaneous value for the time Ti is returned in isochronous mode. The analog module AI 2xU/I 2-/4-wire HF returns a mean value for the range of 0.625 ms starting at Ti.

#### 5.3 Explanation of parameters

### 5.3 Explanation of parameters

### Diagnostics No supply voltage L+

Enabling of the diagnostics for no or insufficient supply voltage L+.

### Diagnostics: Short-circuit to ground

Enabling of the diagnostics if a short-circuit of the actuator supply to ground occurs. A short-circuit is also detected in the range of 1 to 5 V if the input signal is short-circuited or the input is not connected.

The short-circuit and underflow diagnostics can be activated simultaneously. If both diagnostics events occur simultaneously, the short-circuit diagnostics is output.

### **Diagnostics: Overflow**

Enabling of the diagnostics when the measured value exceeds the overrange.

### **Diagnostics: Underflow**

Enabling of the diagnostics when the measured value falls below the underrange.

### **Diagnostics: Wire break**

Enable the diagnostics if the module has no current flow or has too little current for the measurement in the range of 4 to 20 mA.

The wire break and underflow diagnostics can be activated simultaneously. If both diagnostics events occur simultaneously, the wire break diagnostics is output.

### Type/range of measurement

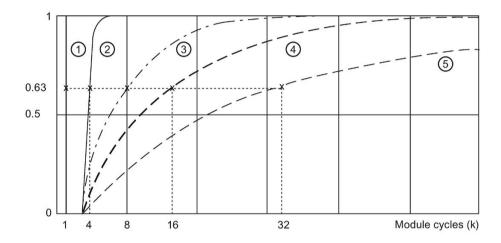
See section Measurement types and measuring ranges (Page 21)

### **Smoothing**

The individual measured values are smoothed by filtering. The smoothing can be set in 5 levels.

Smoothing time = number of module cycles (k) x cycle time of the module.

The following figure shows how many module cycles it takes for the smoothed analog value to approach 100%, depending on the configured smoothing. This applies to every signal change at the analog input.



- ① No smoothing (k = 1)
- $\bigcirc$  Weak (k = 4)
- $\bigcirc$  Medium (k = 8)
- 4 Strong (k = 16)
- $\bigcirc$  Very strong (k = 32)

Figure 5-1 Smoothing AI 2×U/I 2-/4-wire HF

### Interference frequency suppression

Suppresses the interference affecting analog input modules that is caused by the frequency of the AC voltage network used.

The frequency of the AC voltage network can negatively affect the measured value, in particular when measuring in the low voltage range and with thermocouples. With this parameter, the user specifies the line frequency that is predominant in the plant.

#### Adjust measuring range

See section Measuring range adjustment (Page 30).

### Measuring range adjustment high limit

See section Measuring range adjustment (Page 30).

#### 5.3 Explanation of parameters

### Measuring range adjustment low limit

See section Measuring range adjustment (Page 30).

### Scaled high nominal range limit

See section Scaling of measured values (Page 34).

### Scaled low nominal range limit

See section Scaling of measured values (Page 34).

### Hardware interrupt high limit 1/2

Enabling of a hardware interrupt if the high limit 1/2 is violated.

### Hardware interrupt low limit 1/2

Enabling of a hardware interrupt if the low limit 1/2 is violated.

### High limit 1/2

Specify a threshold which triggers a hardware interrupt when violated.

### Low limit 1/2

Specify a threshold which triggers a hardware interrupt when violated.

### **Potential group**

Specifies whether a light-colored BaseUnit with incoming supply voltage or a dark-colored BaseUnit is located in this slot (see ET 200SP distributed I/O system (http://support.automation.siemens.com/WW/view/en/58649293) system manual).

A potential group consists of a group of directly adjacent I/O modules within an ET 200SP station, which are supplied via a common supply voltage.

A potential group begins with a light-colored BaseUnit through which the required voltage is supplied for all modules of the potential group. The light-colored BaseUnit interrupts the three self-assembling voltage buses P1, P2 and AUX to the left neighbor.

All additional I/O modules of this potential group are plugged into dark-colored BaseUnits. You take the potential of the self-assembling voltage buses P1, P2 and AUX from the left neighbor.

A potential group ends with a dark-colored BaseUnit, which follows a light-colored BaseUnit or server module in the station configuration.

#### See also

You can find additional information in the system manual ET 200SP distributed I/O system (http://support.automation.siemens.com/WW/view/en/58649293).

### 5.4 Measuring range adjustment

### 5.4 Measuring range adjustment

#### **Function**

The measuring range adjustment is a limited section of a measuring range supported by the module.

It allows you to increase the resolution for a configurable part of the measuring range in S7 format. The section of the measuring range is defined by the high and low limits of the measuring range adjustment.

- The function is enabled with the "Adjust measuring range" parameter
- The "Measuring range adjustment high limit" parameter sets the high limit of the measuring range in mV or μA.
- The "Measuring range adjustment low limit" parameter sets the low limit of the measuring range in mV or µA.

#### Note

The "Measuring range adjustment" function can be used in combination with the "Measured value scaling" function. See also Scaling of measured values (Page 34).

The measuring range adjustment is available for current and voltage measuring ranges.

The measuring range adjustment (base measuring range) is valid for the following ranges:

- Nominal range
- Underrange (of the measuring range adjustment)
- Overrange (of the measuring range adjustment)

#### Note

Live zero measuring ranges are not supported.

#### Note

When the "Measuring range adjustment high limit" and "Measuring range adjustment low limit" parameters are too close together, resolution may be lost, which means it may no longer be possible to show every value.

#### Rules

- The limits of the measuring range adjustment must be selected within the nominal range of the base measuring range. They are specified in integers.
- The measuring range adjustment is resolved depending on the base measuring range from 0<sub>H</sub> to 6C00<sub>H</sub> or 9400<sub>H</sub> to 6C00<sub>H</sub>.
- Underranges/overranges apply in accordance with the S7 format and the base measuring range.

Special consideration: Negative values are not possible for "Current (2-wire transducer) 0..20 mA". With a measuring range adjustment, an underrange is offered when possible and cut off at 0 mA. If the underrange limit (ED00 $_{\rm H}$ ) is > 0 mA, QI = 0 and the analog value 8000 $_{\rm H}$  are output when it is violated.

### **Example**

The following values result, for example:

Table 5-3 Example of measuring range adjustment

Measuring range adjustment	Measuring range resolution		
	Bipolar	Unipolar	
Base measuring range	±10 V	0 V to 10 V	
Adjusted measuring range	+2 V to +5 V	+2 V to +5 V	
Measuring range adjustment high limit	5000 mV (S7: +27648)	5000 mV (S7: +27648)	
Measuring range adjustment low limit	2000 mV (S7: -27648)	2000 mV (S7: 0)	

The following example illustrates the effect of a measuring range adjustment:

### 5.4 Measuring range adjustment

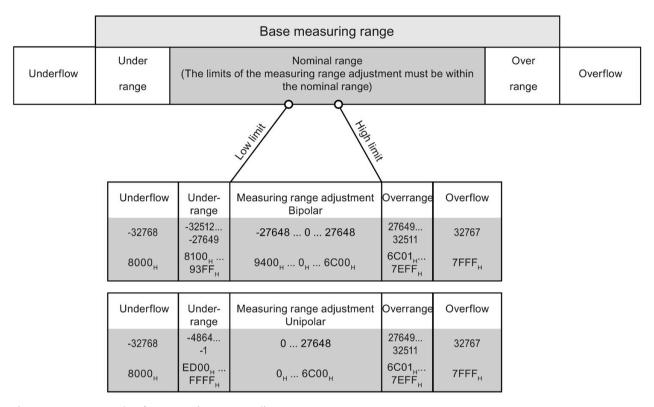


Figure 5-2 Example of a measuring range adjustment

### Configuration

The following figure shows an example of a configuration:

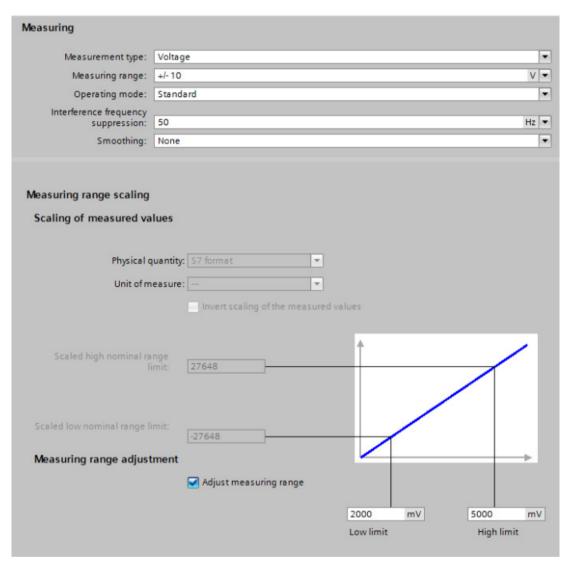


Figure 5-3 Example of a configuration

In the configuration example, a measuring range adjustment of 2000 mV to 5000 mV is displayed.

### 5.5 Scaling of measured values

#### **Function**

With measured value scaling, the user data of the module is displayed as REAL (32-bit floating point) instead of in S7 format.

The representation of the measuring range is defined by the following parameters:

- The "Scaled high nominal range limit" parameter sets the desired display value (in REAL) for the high nominal range limit of the measuring range.
- The "Scaled low nominal range limit" parameter sets the desired display value (in REAL) for the low nominal range limit of the measuring range.

#### Note

With measured value scaling, the substitute value is minus infinity for underflow (FF800000H) and plus infinity for overflow (7F800000H).

#### Note

#### Effects of inversion

It is possible to set the "Scaled high nominal range limit" parameter lower than the "Scaled low nominal range limit" parameter, whereby the representation of the measuring range will be inverted compared to the terminal value (V, mA).

Overflow/underflow and hardware interrupts are always based on representation in REAL. A terminal value of > 11.76 V triggered an underflow for an inverted measured value scaling. Hardware interrupts react similarly.

#### Note

When the Parameter "Scaled high nominal range limit" and "Scaled low nominal range limit" parameters are too close together, resolution may be lost, which means it may no longer be possible to show every value.

The measured value scaling can be combined with the measuring range adjustment. In this case, the measuring range is adjusted first and then the representation of the measuring range is scaled.

### Example

The following values result, for example:

Table 5-4 Example of measured value scaling

	Low nominal range limit	High nominal range limit
Base measuring range	-10 V	+10 V
S7 format	-27648	+27648
Scaling of measured values	1.00	7.00

As shown in the table, -10 V corresponds to 1.00 and +10 V corresponds to 7.00.

### Combination with measuring range adjustment

If the measuring range adjustment is enabled in addition to measured value scaling, first the measuring range is scaled and then the representation of the measuring range. The table below shows an example of the combination of measured value scaling and measuring range adjustment.

Table 5-5 Example for a combination of measured value scaling and measuring range adjustment

	Low nominal range limit	High nominal range limit
Measuring range adjustment	-4000 mV	8000 mV
S7 format	-27648	+27648
Scaling of measured values	1.00	7.00

As shown in the table, -4 V corresponds to 1.00 and +8 V corresponds to 7.00.

#### 5.5 Scaling of measured values

### Configuration

The following figures show examples of a configuration in STEP 7:

### Configuration of measured value scaling

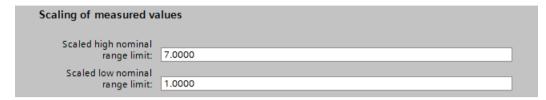


Figure 5-4 Configuration of measured value scaling

### Configuration with measuring range adjustment and measured value scaling

In the configuration example, a measuring range adjustment of -4000 mV to 8000 mV is displayed and additionally converted to a scaled high and low nominal range limit of 1.00 to 7.00.

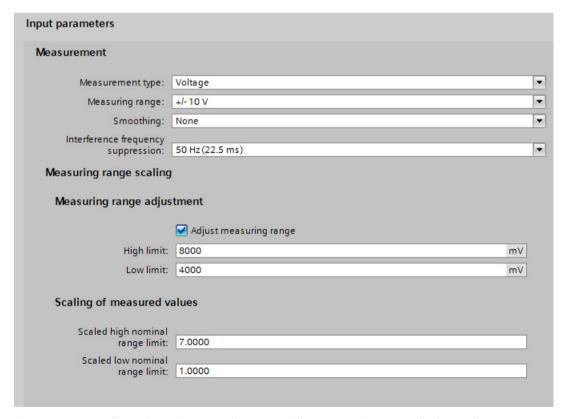


Figure 5-5 Configuration with measuring range adjustment and measured value scaling

### 5.6 Address space

The module can be configured differently; see following table. Depending on the configuration, additional/different addresses are assigned in the process image of the inputs.

### Configuration options of AI 2xU/I 2-/4-wire HF

You can configure the module with STEP 7 (TIA Portal) or with a GSD file. If you configure the module by means of a GSD file, the configurations are available under various short designations/module names; see the table below. The following configurations are possible:

Table 5-6 Configuration options with GSD file

Configuration	Short designa- tion/module name in the GSD file	Configuration software, e.g. with STEP 7 (TIA Portal)		
		Availability in hardware catalog STEP 7 (TIA Portal)	GSD file PROFINET IO	GSD file PROFIBUS DP
1 x 2-channel without value status	AI 2xU/I 2-, 4-wire HF V1.0	Integrated as of STEP7 V13	X	X
1 x 2-channel with value status	AI 2xU/I 2-, 4-wire HF V1.0, QI	Integrated as of STEP7 V13	X	
1 x 2-channel without value status	AI 2xU/I 2-, 4-wire HF V2.0	<ul><li>HSP161 STEP7 V13 SP1</li><li>Integrated as of STEP7 V14</li></ul>	X	Х
1 x 2-channel with value status	AI 2xU/I 2-, 4-wire HF V2.0, QI	<ul><li>HSP161 STEP7 V13 SP1</li><li>Integrated as of STEP7 V14</li></ul>	Х	
1 x 2-channel with value status for module-internal Shared Input with up to 4 submodules	AI 2xU/I 2-, 4-wire HF V2.0, MSI	<ul><li>HSP161 STEP7 V13 SP1</li><li>Integrated as of STEP7 V14</li></ul>	Х	
1 x 2-channel with value status and measured value scaling	AI 2xU/I 2-, 4-wire HF V2.0, SCALE	<ul><li>HSP161 STEP7 V13 SP1</li><li>Integrated as of STEP7 V14</li></ul>	Х	

### Value status (Quality Information, QI)

The value status is always activated for the following module names:

- Al 2xU/I 2-, 4-wire HF, QI,
- Al 2xU/I 2-, 4-wire HF, MSI
- AI 2xU/I 2-, 4-wire HF, SCALE

An additional bit is assigned to each channel for the value status. The value status bit indicates whether the read in analog value is valid. (0 = value is incorrect).

5.6 Address space

### **Evaluating the value status**

If you enable the value status for the analog module, an additional byte is occupied in the input address space. Bits 0 and 1 in this byte are assigned to a channel. They provide information about the validity of the analog value.

Bit = 1: No fault is present on the channel.

Bit = 0: The channel is disabled or the wiring or the value created on the channel, etc. is incorrect.

### Address space for configuration as 1 x 2-channel AI 2×U/I 2-/4-wire HF

The figure below shows the assignment of the address space for AI 2xU/I 2-/4-wire HF.

Assignment in the process image input (PII)

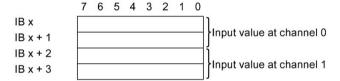


Figure 5-6 Address space of the analog input module AI 2xU/I 2-/4-wire HF

### Address space for configuration as 1 x 2-channel AI 2×U/I 2-/4-wire HF, QI

The figure below shows the assignment of the address space for AI 2xU/I 2-/4-wire HF.

Assignment in the process image input (PII)

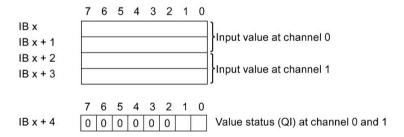


Figure 5-7 Address space of the analog input module AI 2xU/I 2-/4-wire HF, QI

### Address space for configuration as 1 x 2-channel AI 2×U/I 2-/4-wire HF MSI

For the configuration as a 1 x 2-channel module (module-internal shared input, MSI), channels 0 and 1 of module are copied to up to four submodules. Channels 0 and 1 are then available with identical input values in various submodules. These submodules can be assigned to up to four IO controllers when the module is used in a shared device. Each IO controller has read access to the same channels.

The number of usable submodules is dependent on the interface module used. Please observe the information in the manual for the particular interface module.

### Value status (Quality Information, QI)

The meaning of the value status depends on the submodule on which it occurs.

For the first submodule (=basic submodule), the value status 0 indicates that the value is incorrect.

For the 2nd to 4th submodule (=MSI submodule), the value status 0 indicates that the value is incorrect or the basic submodule has not yet been configured (not ready).

The following figure shows the assignment of the address space with submodules 1 and 2.

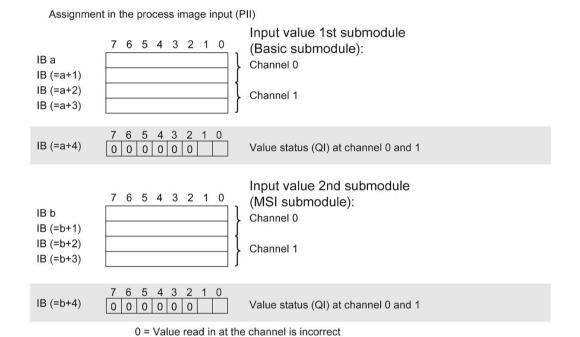


Figure 5-8 Address space for configuration as 1x 2-channel AI 2×U/I 2-/4-wire HF MSI

The figure below shows the assignment of the address space with submodules 3 and 4.

### 5.6 Address space

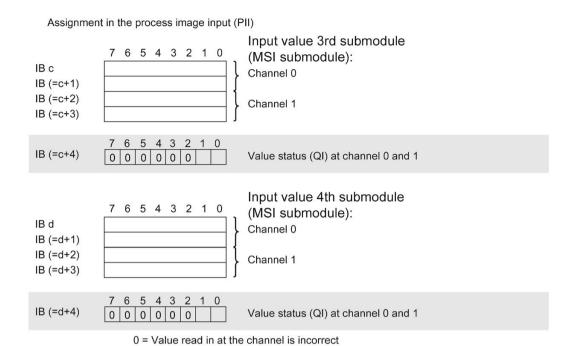


Figure 5-9 Address space for configuration as 1x 2-channel AI 2×U/I 2-/4-wire HF MSI

# Address space for configuration as 1 x 2-channel AI 2×U/I 2-/4-wire HF SCALE

The figure below shows the assignment of the address space for AI 2xU/I 2-/4-wire HF, SCALE.

Assignment in the process image input (PII)

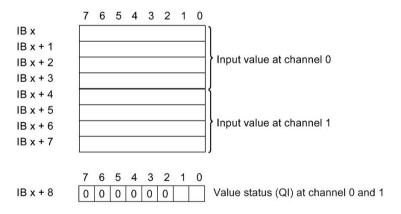


Figure 5-10 Address space for configuration as 1 x 2-channel Al 2×U/I 2-/4-wire HF, SCALE

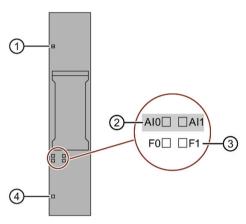
Interrupts/diagnostics alarms

# 6

# 6.1 Status and error displays

# **LED displays**

The following figure shows you the LED display of the AI 2xU/I 2-/4-wire HF.



- ① DIAG (green/red)
- ② Channel status (green)
- 3 Channel error (red)
- 4 PWR (green)

Figure 6-1 LED display

# 6.1 Status and error displays

# Meaning of the LED displays

The following tables contain the meaning of the status and error displays. Remedies for diagnostics alarms can be found in section Diagnostics alarms (Page 45).

Table 6-1 Error display DIAG LED

DIAG LED	Meaning
	Backplane bus supply of the system is interrupted or switched off.
Off	
崇	Module parameters not assigned
Flashes	
	Module parameters assigned and no module diagnostics
On	
崇	Module parameters assigned and module diagnostics
Flashes	

Table 6-2 Status and error display LED channel status / channel error

LEDs		Meaning
Channel status	Channel error	
Off	□ Off	Channel deactivated or no load voltage L+
On	□ Off	Channel activated and no channel diagnostics
Off	• On	Channel activated and channel diagnostics
• On	• On	Not permitted (error)

Table 6-3 PWR LED status display

PWR LED	Meaning
Off	Missing supply voltage L+
On	Supply voltage L+ present

# 6.2 Interrupts

The I/O module supports diagnostic and hardware interrupts.

# **Diagnostics interrupts**

The module generates a diagnostic interrupt at the following events:

- Short-circuit (current: sensor supply; voltage: 1 to 5 V, encoder supply)
- Wire break (current: 4 to 20 mA)
- High limit violated
- · Low limit violated
- Error
- Parameter assignment error
- Hardware interrupt lost
- Supply voltage missing
- Channel temporarily unavailable

# Hardware interrupts

The module generates a hardware interrupt at the following events:

- Violation of low limit 1
- Violation of high limit 1
- Violation of low limit 2
- Violation of high limit 2

### **S7-1500**

Detailed information on the event is available in the STEP 7 online help.

The block interface is represented here with optimized block access, which is set in the TIA Portal by default.

Name	Data type	Comment
LADDR	HW_IO	Hardware identifier of the module triggering the interrupt
USI	WORD	USI (High/Low)
IChannel	USInt	Channel that triggered the hardware interrupt
EventType	Byte	Error event

6.2 Interrupts

### S7-300/400 or a different CPU

You can obtain detailed information on the event in the hardware interrupt organization block with the "RALARM" (read additional interrupt information) instruction and in the STEP 7 online help.

The module channel that triggered the hardware interrupt is entered in the start information of the organization block. The following figure shows the assignment to the bits of double word 8 in local data.

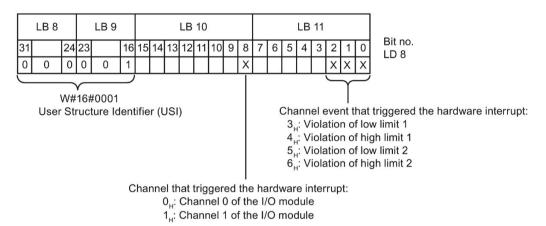


Figure 6-2 OB start information

# Structure of the additional interrupt information

Table 6-4 Structure of the additional interrupt information

Data block name		Content Comment		Bytes	
USI (User Structure Identifier)		W#16#0001	Additional interrupt information for hardware interrupts of the I/O module	2	
Char	nnel that triggered the hardw	are interrupt.			
Channel		B#16#00 to B#16#01	Channel 0 and 1 of the I/O module	1	
Even	t that triggered the hardware	e interrupt.			
	Error event	B#16#03	Violation of low limit 1	1	
		B#16#04	Violation of high limit 1		
		B#16#05	Violation of low limit 2		
		B#16#06	Violation of high limit 2		

# 6.3 Diagnostics alarms

A diagnostic message is generated and the DIAG-LED flashes red on the module for each diagnostics event. You can read out the diagnostics alarms, for example, in the diagnostics buffer of the CPU. You can evaluate the error codes with the user program.

Table 6-5 Diagnostics alarms, their meaning and corrective measures

Diagnostics alarm Error code		Meaning	Solution		
Short-circuit (encoder supply)	1н	Short-circuit encoder supply to ground	Correct interplay between module and encoder		
Short-circuit (1 to 5 V)	1н	Short-circuit of input signal	Correct interplay between module and encoder		
		Open input	Connect input		
Wire break (current 4 to 20 mA)	бн	Impedance of encoder circuit too high	Use a different encoder type or modify the wiring, e.g. use cables with larger cross-section		
		Wire break between the module and sensor	Connect the cable		
		Channel not connected (open)	Disable diagnostics		
			Connect the encoder contacts		
High limit violated	7н	Value is above the overrange	Correct interplay between module and encoder		
Low limit violated	8н	Value is below the underrange	Correct interplay between module and encoder		
Error	9н	Internal module fault has occurred (diagnostic message applies to the entire module)	Replace module		
Parameter assignment error	10н	The module cannot evaluate parameters for the channel	Correct the parameter assignment		
		Incorrect parameter assignment			
Supply voltage missing	11н	Missing or insufficient supply voltage L+	Check the supply voltage L+ on the BaseUnit		
			Check BaseUnit type		
Hardware interrupt lost	16н	Error is reported when a hardware inter-	Limits might be assigned twice		
		rupt (high/low limit) could not be reported.	If necessary, reduce the bus cycle		
			If necessary, use higher SFU		
Channel temporarily	1Fн	Firmware update is currently in progress or	Wait for firmware update		
unavailable		has been canceled. The module does not read in process values in this state.	Restart the firmware update		
		The channel is currently being calibrated.	Complete calibration		

# Diagnostic messages in the measured value of analog input modules

Each analog input module supplies the measured value 7FFFH or 8000H depending on the parameter assignment when an error is detected (with configuration SCALE: 7F800000H or FF800000H).

Technical specifications

# Technical specifications of the AI 2×U/I 2-/4-wire HF

The following table shows the technical specifications as of 03/2021. You can find a data sheet including daily updated technical specifications on the Internet (https://support.industry.siemens.com/cs/ww/en/pv/6ES7134-6HB00-0CA1/td?dl=en).

Article number	6ES7134-6HB00-0CA1			
General information				
Product type designation	AI 2xU/I 2-/4-wire HF			
HW functional status	From FS06			
Firmware version				
FW update possible	Yes			
usable BaseUnits	BU type A0, A1			
Color code for module-specific color identification plate	CC03			
Product function				
I&M data	Yes; I&M0 to I&M3			
Isochronous mode	Yes			
Measuring range scalable	No			
Engineering with				
<ul> <li>STEP 7 TIA Portal configurable/integrated from version</li> </ul>	V13			
<ul> <li>STEP 7 configurable/integrated from version</li> </ul>	V5.5 / -			
PCS 7 configurable/integrated from version	V8.1 SP1			
PROFIBUS from GSD version/GSD revision	One GSD file each, Revision 3 and 5 and higher			
PROFINET from GSD version/GSD revision	GSDML V2.3			
Operating mode				
<ul> <li>Oversampling</li> </ul>	No			
• MSI	Yes			
CiR - Configuration in RUN				
Reparameterization possible in RUN	Yes			
Calibration possible in RUN	Yes			
Supply voltage				
Rated value (DC)	24 V			
permissible range, lower limit (DC)	19.2 V			
permissible range, upper limit (DC)	28.8 V			
Reverse polarity protection	Yes			

Article number	6ES7134-6HB00-0CA1			
Input current				
Current consumption (rated value)	39 mA; without sensor supply			
24 V encoder supply				
• 24 V	Yes			
Short-circuit protection	Yes			
Output current, max.	20 mA; max. 50 mA per channel for a duration < 10 s (two-wire)			
Additional 24 V encoder supply				
Short-circuit protection	Yes; channel by channel			
Output current, max.	100 mA; max. 150 mA for a duration of < 10 s (four-wire)			
Power loss				
Power loss, typ.	0.95 W; without sensor supply			
Address area				
<ul><li>Address space per module</li><li>Address space per module, max.</li></ul>	4 byte; + 4 byte for scaling of measured values, + 1 byte for QI information			
Hardware configuration				
Automatic encoding	Yes			
Mechanical coding element	Yes			
Type of mechanical coding element	Type A			
Selection of BaseUnit for connection variants				
• 2-wire connection	BU type A0, A1			
4-wire connection	BU type A0, A1			
Analog inputs				
Number of analog inputs	2; Differential inputs			
For current measurement	2			
For voltage measurement	2			
permissible input voltage for voltage input (destruction limit), max.	30 V			
permissible input current for current input (destruction limit), max.	50 mA			
Analog input with oversampling	No			
Standardization of measured values	Yes			
Input ranges (rated values), voltages	Yes; 15 bit			
• 0 to +10 V				
<ul><li>Input resistance (0 to 10 V)</li></ul>	75 kΩ			
• 1 V to 5 V	Yes; 15 bit			
<ul><li>Input resistance (1 V to 5 V)</li></ul>	75 kΩ			
• -10 V to +10 V	Yes; 16 bit incl. sign			
<ul> <li>Input resistance (-10 V to +10 V)</li> </ul>	75 kΩ			
• -5 V to +5 V	Yes; 16 bit incl. sign			

A .12 .1		CEC7424 CUROO OCA4		
Article n		6ES7134-6HB00-0CA1 75 kΩ		
	Input resistance (-5 V to +5 V)	7.5 152		
-	nges (rated values), currents to 20 mA	Yes; 15 bit		
5 0		130 Ω		
_	Input resistance (0 to 20 mA)	Yes; 16 bit incl. sign		
• -2	20 mA to +20 mA	130 O		
_	Input resistance (-20 mA to +20 mA)	.55		
• 4	mA to 20 mA	Yes; 15 bit		
	,	130 Ω		
Cable le		4.000 200 f		
	nielded, max.	1 000 m; 200 m for voltage measurement		
	value generation for the inputs	s' b h		
	iurement principle ion and conversion time/resolution per	Sigma Delta		
channel				
	esolution with overrange (bit including	16 bit		
si	gn), max.			
• In	tegration time, parameterizable	Yes		
• In	ntegration time (ms)	67.5 / 22.5 / 18.75 / 10 / 5 / 2.5 / 1.25 / 0.625 ms		
	asic conversion time, including integration me (ms)	68.03 / 22.83 / 19.03 / 10.28 / 5.23 / 2.68 / 1.43 / 0.730 ms		
	nterference voltage suppression for inter- erence frequency f1 in Hz	16.6 / 50 / 60 / 300 / 600 / 1 200 / 2 400 / 4 800		
• C	onversion time (per channel)	68.2 / 23 / 19.2 / 10.45 / 5.40 / 2.85 / 1.6 / 0.9 ms		
	asic execution time of the module (all nannels released)	1 ms		
Smoothi	ing of measured values			
• N	umber of smoothing levels	6; none; 2-/4-/8-/16-/32-fold		
• pa	arameterizable	Yes		
Encoder				
Connect	ion of signal encoders			
• fc	or voltage measurement	Yes		
	or current measurement as 2-wire trans- ucer	Yes		
_	Burden of 2-wire transmitter, max.	650 Ω		
	or current measurement as 4-wire trans- ucer	Yes		
Errors/ac	ccuracies			
	rity error (relative to input range), (+/-) perature error (relative to input range), (+/-	0.01 % 0.003 %/K		

Article number	6ES7134-6HB00-0CA1			
Crosstalk between the inputs, min.	-50 dB			
Repeat accuracy in steady state at 25 $^{\circ}$ C (relative to input range), (+/-)	0.01 %			
Operational error limit in overall temperature range				
<ul> <li>Voltage, relative to input range, (+/-)</li> </ul>	0.1 %			
• Current, relative to input range, (+/-)	0.1 %			
Basic error limit (operational limit at 25 °C)				
<ul> <li>Voltage, relative to input range, (+/-)</li> </ul>	0.05 %; 0.1 % at SFU 4.8 kHz			
• Current, relative to input range, (+/-)	0.05 %; 0.1 % at SFU 4.8 kHz			
Interference voltage suppression for f = n x (f1 +/- 1 %), f1 = interference frequency				
Common mode voltage, max.	35 V			
Common mode interference, min.	90 dB			
Isochronous mode				
Filtering and processing time (TCI), min.	800 μs			
Bus cycle time (TDP), min.	1 ms			
Jitter, max.  Interrupts/diagnostics/status information	5 μs			
Diagnostics function	Yes			
Alarms	163			
Diagnostic alarm	Yes			
Limit value alarm	Yes; two upper and two lower limit values in each case			
Diagnoses				
<ul> <li>Monitoring the supply voltage</li> </ul>	Yes			
Wire-break	Yes; Measuring range 4 to 20 mA only			
Short-circuit	Yes; channel-by-channel, at 1 to 5 V or for short-circuit in encoder supply			
Group error	Yes			
Overflow/underflow	Yes			
Diagnostics indication LED				
• Monitoring of the supply voltage (PWR-LED)	Yes; green PWR LED			
Channel status display	Yes; green LED			
for channel diagnostics	Yes; red LED			
• for module diagnostics	Yes; green/red DIAG LED			
Potential separation				
Potential separation channels				
• between the channels	Yes			
between the channels and backplane bus	Yes			

Article number	6ES7134-6HB00-0CA1		
<ul> <li>between the channels and the power sup- ply of the electronics</li> </ul>	Yes		
Isolation			
Isolation tested with	707 V DC (type test)		
Ambient conditions			
Ambient temperature during operation			
<ul> <li>horizontal installation, min.</li> </ul>	-30 °C; < 0 °C as of FS06		
<ul> <li>horizontal installation, max.</li> </ul>	60 °C		
<ul> <li>vertical installation, min.</li> </ul>	-30 °C; < 0 °C as of FS06		
<ul> <li>vertical installation, max.</li> </ul>	50 °C		
Altitude during operation relating to sea level			
• Installation altitude above sea level, max.	5 000 m; Restrictions for installation altitudes > 2 000 m, see manual		
Dimensions			
Width	15 mm		
Height	73 mm		
Depth	58 mm		
Weights			
Weight, approx.	32 g		

# **Dimension drawing**

See manual ET 200SP BaseUnits (http://support.automation.siemens.com/WW/view/en/59753521)

Parameter data record



# A.1 Dependencies when configuring with GSD file

When configuring the module with a GSD file, remember that the settings of some parameters are dependent on each other.

#### Note

For configuration with STEP 7 V13 or higher (TIA Portal), real values between  $-7x10^{28}$  and  $+7x10^{28}$  can be input. This is true for configuration via HSP and via GSD file (PROFINET).

For configuration with STEP 7 V5.5 SP4 as of HF7, configuration by means of GSD file (PROFINET) with REAL values of  $-1.175 \times 10^{38}$  to  $+3.402 \times 10^{38}$  is possible.

With STEP 7 SP4 to HF6, parameter assignment of REAL values is not possible. Functions that require REAL values are not available in this case.

# Configuring with a PROFINET GSD file

The table lists the properties and their dependencies on the measurement type and measuring range for PROFINET.

Measure- ment type	Measuring	Diagnostics					Hardware
	range	Underflow	Overflow	Wire break	Short-circuit to ground	Missing supply voltage L+	interrupts
Deactivated	*	*	*	*	*	*	*
Voltage	±5 V	х	х	_	x 1	х	х
	±10 V	х	х	_	x 1	Х	х
	1 V to 5 V	х	х	_	х	х	х
	0 V to 10 V	х	х	_	x 1	х	х
Current (4-wire trans-	0 mA to 20 mA	x	x	_	х	x	х
ducer)	4 mA to 20 mA	х	х	x	х	х	х
	±20 mA	х	х	-	х	х	х
Current (2-wire trans- ducer)	0 mA to 20 mA	x <sup>1 2</sup>	х	_	х	x	х
	4 mA to 20 mA	х	х	х	х	х	х

x = property is allowed, - = property is **not allowed**, \* = property is not relevant

only possible as of firmware V2.0

The diagnostics Underflow can always be enabled for "Current (2-wire transducer) 0..20 mA", but it is only reported when a complete underflow range is created by the measuring range adjustment.

A.1 Dependencies when configuring with GSD file

# Configuring with a PROFIBUS GSD file

The table lists the properties and their dependencies on the measurement type and measuring range for PROFIBUS.

Table A-1 Dependencies of the measurement type and measuring range PB

Measure-	Measuring			Hardware				
ment type	range	Under- flow	Overflow	Overflow Wire break Load voltage L+		Short- circuit to ground	Smooth- ing / in- terferenc e fre- quency suppres- sion	interrupts
Deactivated	*	*	*	*	*	*	*	*
Voltage	±5 V	х	х	_	х	x 1	х	_
	±10 V	Х	х	_	х	x 1	Х	_
	1 V to 5 V	х	х	_	х	х	х	_
	0 V to 10 V	х	х	_	х	x 1	х	_
Current (4-wire	0 mA to 20 mA	х	х	-	x	x	x	_
transducer)	4 mA to 20 mA	х	x	х	х	x	x	_
	±20 mA	х	х	-	х	х	х	_
Current (2-wire	0 mA to 20 mA	_	х	-	х	х	×	_
transducer)	4 mA to 20 mA	х	х	х	х	х	х	_

x = property is allowed, - = property is **not allowed**, \* = property is not relevant

only possible as of firmware V2.0

The data records of the module have an identical structure, regardless of whether you configure the module with PROFIBUS DP or PROFINET IO.

# Parameter assignment in the user program

You can reassign the module parameters in RUN. For example, the measuring range of selected channels can be changed in RUN without having an effect on the other channels.

### Changing parameters in RUN

The "WRREC" instruction is used to transfer the parameters to the module using data record 128. The parameters set via the configuration do not change in the CPU, which means the parameters set in the CPU are still valid after a restart.

#### Note

#### Changing parameters in RUN

A parameter data record that has content different from the startup parameter assignment results in a brief exit from clocked measuring mode and renewed synchronization with the fieldbus cycle. The slowest channel provides the "internal" measuring cycle.

#### Note

Changing parameter settings in runtime can cause the process values to freeze for the duration of the parameter assignment for the module.

# **Output parameter STATUS**

If errors occur when transferring parameters with the "WRREC" instruction, the module continues operation with the previous parameter assignment. However, the STATUS output parameter contains a corresponding error code.

You will find a description of the "WRREC" instruction and the error codes in the STEP 7 online help.

### Structure of data record 128

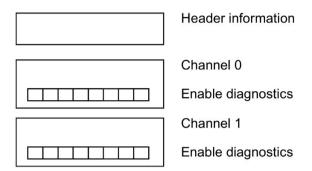


Figure A-1 Structure of data record 128

# Header information (V1.0)

The figure below shows the structure of the header information (V1.0).

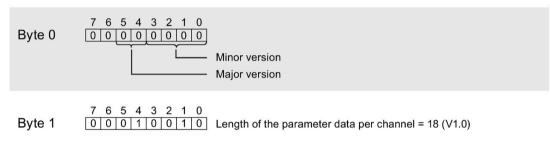


Figure A-2 Header information (V1.0)

# Header information (V2.0)

The figure below shows the structure of the header information (V2.0).

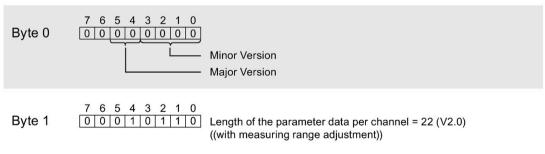


Figure A-3 Header information (V2.0)

# Header information (V2.0 SCALE)

The figure below shows the structure of the header information.

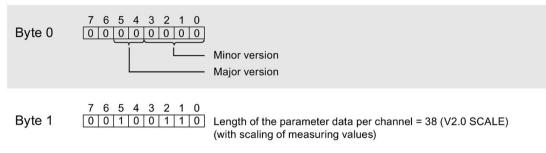


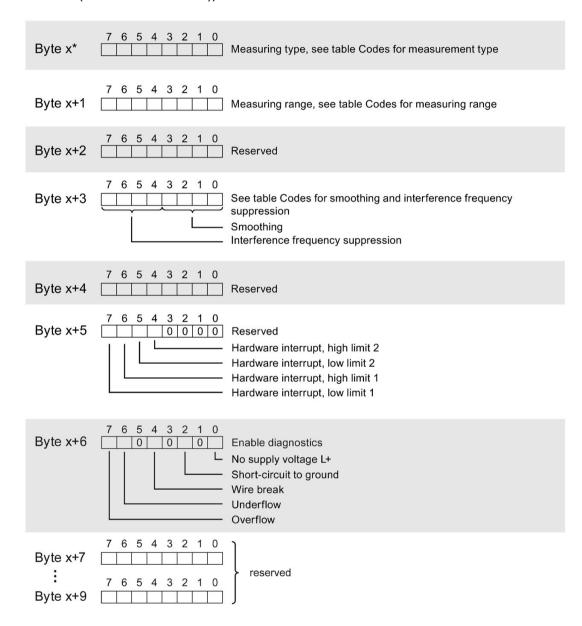
Figure A-4 Header information (V2.0 SCALE)

# Parameter (V1.0)

The following figure shows the structure of the parameters for channels 0 and 1.

You enable a parameter by setting the corresponding bit to "1".

\* x = 2 + (channel number x 18); channel number is 0 or 1



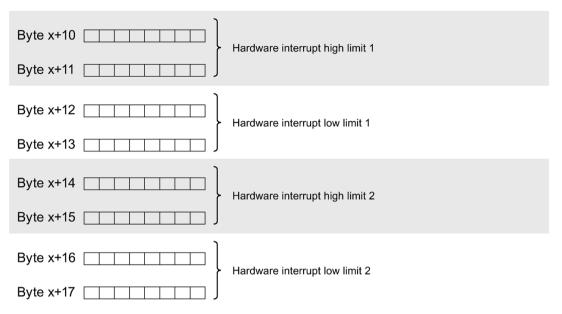


Figure A-5 Structure of byte x to x+17 for channel 0 and 1

# Parameter (V2.0)

The following figure shows the structure of the parameters for channels 0 and 1.

You enable a parameter by setting the corresponding bit to "1".

\* x = 2 + (channel number x 22); channel number is 0 or 1

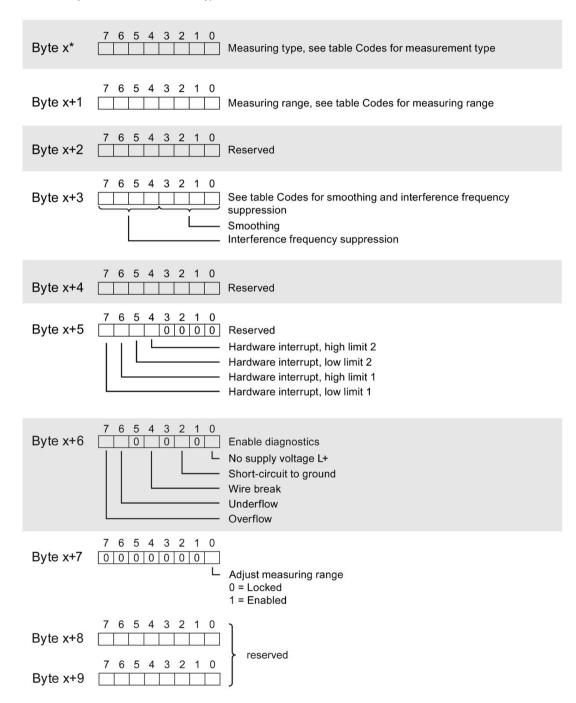




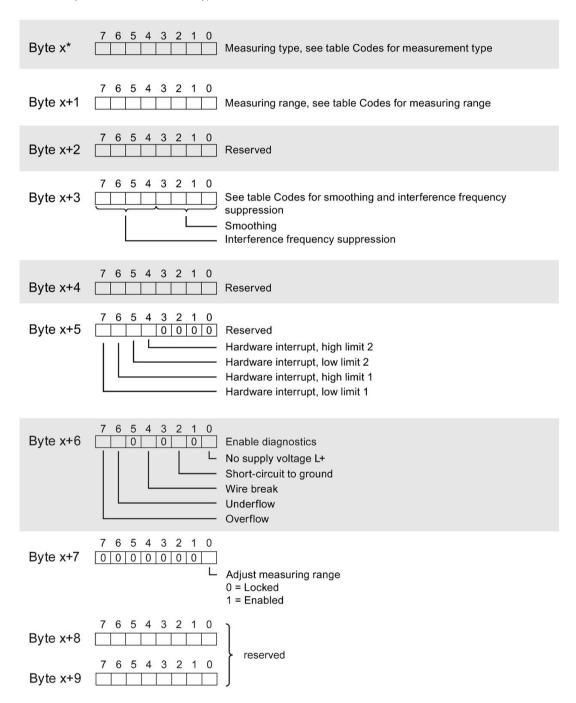
Figure A-6 Structure of bytes x to x+21 for channels 0 and 1

# Parameter (V2.0 SCALE)

The following figure shows the structure of the parameters for channels 0 and 1.

You enable a parameter by setting the corresponding bit to "1".

\* x = 2 + (channel number x 38); channel number is 0 or 1



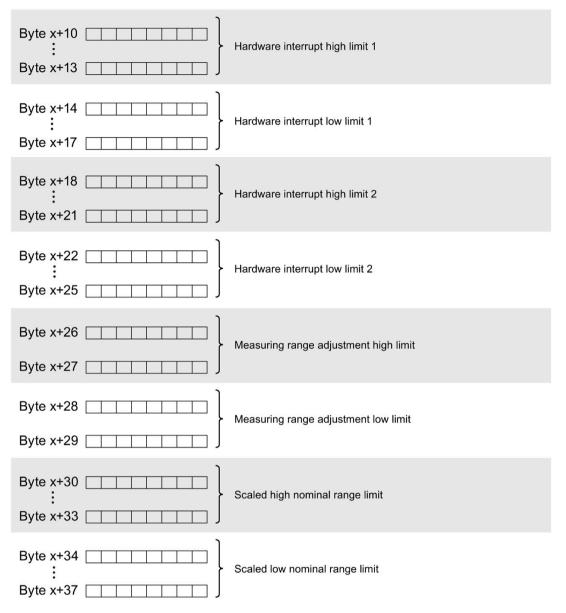


Figure A-7 Structure of bytes x to x+37 for channels 0 and 1

# Codes for measurement types

The following table contains all the measurement types of the analog input module with its codes. You must enter these codes at byte x (see previous figure).

Table A- 2 Codes for measurement types

Measurement type	Code
Deactivated	0000 0000
Voltage	0000 0001
Current, 4-wire transducer	0000 0010
Current, 2-wire transducer	0000 0011

# Codes for measuring ranges

The following table contains all codes for the measuring ranges of the analog input module. You must enter these codes at byte x+1 (see previous figure).

Table A- 3 Codes for measuring ranges

Measuring range	Code
Voltage	
±5 V	0000 1000
±10 V	0000 1001
1 to 5 V	0000 1010
0 to 10 V	0000 1011
Current	
0 mA to 20 mA	0000 0010
4 mA to 20 mA	0000 0011
±20 mA	0000 0100

# Codes for smoothing and interference frequency suppression

The following table contains all coding for smoothing and interference frequency suppression. You must enter these codes at byte x (see previous figure).

Table A- 4 Codes for smoothing

Smoothing	Code
None	0000
2 times	0100
4 times	0001
8 times	0101
16 times	0010
32 times	0011

Table A- 5 Codes for interference frequency suppression

Interference frequency suppression	Code	
16.6 Hz (67.5 ms)	0100	
50 Hz (22.5 ms)	0010	
60 Hz (18.75 ms)	0001	
300 Hz (10 ms)	0101	
600 Hz (5 ms)	0110	
1.2 kHz (2.5 ms)	0111	
2.4 kHz (1.25 ms)	1000	
4.8 kHz (0.625 ms)	1001	

# Error transmitting the data record

The module always checks all values of the transmitted data record. The module applies the values from the data record only when all values have been transmitted without errors.

The WRREC instruction for writing data records returns the appropriate error codes if there are errors in the STATUS parameter.

The following table shows the module-specific error codes and their meaning for parameter data record 128.

Error code in the STATUS pa- rameter (hexadecimal)			US pa-	Meaning	Solution				
Byte 0	Byte 1	Byte 2	Byte 3						
DF	80	ВО	xx	Number of the data record unknown	Enter valid number for data record.				
DF	80	B1	xx	Length of the data record incorrect	Enter valid value for data record length.				
DF	80	B2	xx	Slot invalid or unavailable	<ul> <li>Check the station whether the module is plugged in correctly.</li> <li>Check assigned values for the parameters of the WREC instruction.</li> </ul>				
DF	80	10	xx	Incorrect version or error in the header information	Correct the version, length and number of parameter blocks.				
DF 80 I1 xx			XX	Parameter error	Check the parameters of the module.				

Representation of analog values

B

This section shows the analog values for all measuring ranges supported by the analog input module AI 2xU/I 2-/4wire HF.

# Measured value resolution

The digitized analog value is the same for input and output values at the same nominal range. The analog values are represented as a fixed point number in the two's complement.

The resolutions 15 and 16 bits including sign are displayed. Each analog value is entered in the ACCU left-justified. The bits marked with "x" are set to "0".

Table B- 1 Resolution of the analog values

Resolution in bits	Values		Analog value				
	Decimal	Hexadecimal	High byte	Low byte			
15	2	2н	Sign 0 0 0 0 0 0 0	0000001x			
16	1	1н	Sign 0 0 0 0 0 0 0	00000001			

# **B.1** Representation of input ranges

The tables below set out the digitized representation of the input ranges by bipolar and unipolar input ranges. The resolution is 16 bits.

Table B- 2 Bipolar input ranges

Dec. val- ue	val- Measured Data word value in %										Range							
		215	214	213	212	211	210	<b>2</b> <sup>9</sup>	28	27	26	25	24	23	22	21	20	
32767	> 117.589	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	Overflow
32511	117.589	0	1	1	1	1	1	1	0	1	1	1	1	1	1	1	1	Overrange
27649	100.004	0	1	1	0	1	1	0	0	0	0	0	0	0	0	0	1	7
27648	100.000	0	1	1	0	1	1	0	0	0	0	0	0	0	0	0	0	
1	0.003617	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	
0	0.000	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	Nominal
-1	-0.003617	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	range
-27648	-100.000	1	0	0	1	0	1	0	0	0	0	0	0	0	0	0	0	
-27649	-100.004	1	0	0	1	0	0	1	1	1	1	1	1	1	1	1	1	Underrange
-32512	-117.593	1	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0	
-32768	< -117.593	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	Underflow

Table B- 3 Unipolar input ranges

Dec. val- ue	Measured value in %	Data	Data word									Range						
		2 <sup>15</sup>	214	213	212	211	210	2 <sup>9</sup>	28	27	26	2 <sup>5</sup>	24	23	<b>2</b> <sup>2</sup>	21	20	
32767	> 117.589	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	Overflow
32511	117.589	0	1	1	1	1	1	1	0	1	1	1	1	1	1	1	1	Overrange
27649	100.004	0	1	1	0	1	1	0	0	0	0	0	0	0	0	0	1	]
27648	100.000	0	1	1	0	1	1	0	0	0	0	0	0	0	0	0	0	Nominal
1	0.003617	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	range
0	0.000	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
-1	-0.003617	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	Underrange
-4864	-17.593	1	1	1	0	1	1	0	1	0	0	0	0	0	0	0	0	
-32768	< -17.593	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	Underflow

# B.2 Representation of analog values in voltage measuring ranges

The following tables list the decimal and hexadecimal values (codes) of the possible voltage measuring ranges.

Table B- 4 Voltage measuring range  $\pm 10 \text{ V}$  and  $\pm 5 \text{ V}$ 

Values		Voltage measuring	g range	Range		
Dec.	Hex.	±10 V	±5 V			
32767	7FFF	> 11.759 V	> 5.879 V	Overflow		
32511	7EFF	11.759 V	5.879 V	Overrange		
27649	6C01					
27648	6C00	10 V	5 V	Nominal range		
20736	5100	7.5 V	3.75 V			
1	1	361.7 μV	180.8 μV			
0	0	0 V	0 V			
-1	FFFF					
-20736	AF00	-7.5 V	-3.75 V			
-27648	9400	-10 V	-5 V			
-27649	93FF			Underrange		
-32512	8100	-11.759 V	-5.879 V			
-32768	8000	< -11.759 V	<-5.879 V	Underflow		

Table B- 5 Voltage measuring range 1 V to 5 V and 0 V to 10 V

Values		Voltage measuring	ı range	Range			
Dec.	Hex.	1 to 5 V	0 to 10 V				
32767	7FFF	> 5.704 V	> 11.759 V	Overflow			
32511	7EFF	5.704 V	11.759 V	Overrange			
27649	6C01						
27648	6C00	5 V	10 V	Nominal range			
20736	5100	4 V	7.5 V				
1	1	1 V + 144.7 μV	361.7 μV				
0	0	1 V	0 V				
-1	FFFF			Underrange			
-4864	ED00	0.296 V	-1.759 V				
-32768	8000	< 0.296 V	< -1.759 V	Underflow			

# B.3 Representation of analog values in the current measuring ranges

The following tables list the decimal and hexadecimal values (codes) of the possible current measuring ranges.

Table B- 6 Current measuring range ±20 mA

Values		Current measuring range	Range
Dec.	Hex.	±20 mA	
32767	7FFF	> 23.52 mA	Overflow
32511	7EFF	23.52 mA	Overrange
27649	6C01		
27648	6C00	20 mA	Nominal range
20736	5100	15 mA	
1	1	723.4 nA	
0	0	0 mA	
-1	FFFF		
-20736	AF00	-15 mA	
-27648	9400	-20 mA	
-27649	93FF		Underrange
-32512	8100	-23.52 mA	
-32768	8000	< -23.52 mA	Underflow

Table B-7 Current measuring ranges 0 to 20 mA and 4 to 20 mA

Values		Current measuring range		Range
Dec.	Hex.	0 to 20 mA*	4 to 20 mA	
32767	7FFF	> 23.52 mA	> 22.81 mA	Overflow
32511	7EFF	23.52 mA	22.81 mA	Overrange
27649	6C01			
27648	6C00	20 mA	20 mA	Nominal range
20736	5100	15 mA	16 mA	
1	1	723.4 nA	4 mA + 578.7 nA	
0	0	0 mA	4 mA	
-1	FFFF			Underrange
-4864	ED00	-3.52 mA	1.185 mA	
-32768	8000	< -3.52 mA	< 1.185 mA	Underflow

<sup>\*</sup> For measurement type "2-wire transducer", negative values are not possible for the range "0 to 20 mA". Therefore, no underrange or underflow exists here.

# B.4 Measured values for wire break

The following table contains the measured values at a wire break depending on enabled diagnostics.

Table B-8 Measured values at a wire break depending on enabled diagnostics

Programmable diagnos- tics		Measured value		Explanation
Wire break	Underflow			
Enable	Enable	32767	7FFF <sub>H</sub>	The "wire break" diagnostics is reported, because this has a higher priority.
Disable	Enable	-32768	8000н	The "Lower limit violated" diagnostics is reported.
Disable	Disable	-32768	8000н	No diagnostics reported.