



# Low Power, 3.6 MHz, Low Noise, Rail-to-Rail Output, Operational Amplifiers

## ADA4691-2/ADA4691-4/ADA4692-2/ADA4692-4

### FEATURES

**Low power:** 180  $\mu$ A typical  
**Very low input bias currents:** 0.5 pA typical  
**Low noise:** 16 nV/ $\sqrt{\text{Hz}}$  typical  
**3.6 MHz bandwidth**  
**Offset voltage:** 500  $\mu$ V typical  
**Low offset voltage drift:** 4  $\mu$ V/ $^{\circ}\text{C}$  maximum  
**Low distortion:** 0.003% THD + N  
**2.7 V to 5 V single supply or  $\pm 1.35$  V to  $\pm 2.5$  V dual supply**  
**Available in very small 2 mm  $\times$  2 mm LFCSP packages**

### APPLICATIONS

Photodiode amplifiers  
Sensor amplifiers  
Portable medical and instrumentation  
Portable audio: MP3s, PDAs, and smartphones  
Communications  
Low-side current sense  
ADC drivers  
Active filters  
Sample-and-hold

### GENERAL DESCRIPTION

The ADA4691-2/ADA4692-2 are dual and the ADA4691-4/ADA4692-4 are the quad rail-to-rail output, single-supply amplifiers featuring low power, wide bandwidth, and low noise. The ADA4691-2 has two independent shutdown pins, allowing further reduction in supply current. The ADA4691-4 is a quad with dual shutdown pins each controlling a pair of amplifiers and is available in the 16-lead LFCSP. The ADA4692-4 is a quad version without shutdown.

These amplifiers are ideal for a wide variety of applications. Audio, filters, photodiode amplifiers, and charge amplifiers, all benefit from this combination of performance and features. Additional applications for these amplifiers include portable consumer audio players with low noise and low distortion that provide high gain and slew rate response over the audio band at low power. Industrial applications with high impedance sensors, such as pyroelectric and IR sensors, benefit from the high impedance and low 0.5 pA input bias, low offset drift, and enough bandwidth and response for low gain applications.

Table 1.

|        | Micropower | Low Power | Low Power with Shutdown | Standard Op Amp With Shutdown | High Bandwidth |
|--------|------------|-----------|-------------------------|-------------------------------|----------------|
| Single | AD8613     |           |                         | AD8591                        | AD8691         |
| Dual   | AD8617     | ADA4692-2 | ADA4691-2               | AD8592                        | AD8692         |
| Quad   | AD8619     | ADA4692-4 | ADA4691-4               | AD8594                        | AD8694         |

### Rev. D

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The ADA4691/ADA4692 family is fully specified over the extended industrial temperature range ( $-40^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$ ). The ADA4691-2 is available in a 10-lead LFCSP and a 9-ball WLCSP. The ADA4692-2 is available in an 8-lead SOIC and 8-lead LFCSP. The ADA4691-4 is available in a 16-lead LFCSP. The ADA4692-4 is available in a 14-lead TSSOP. For pin configurations, see the [Pin Configurations](#) section.

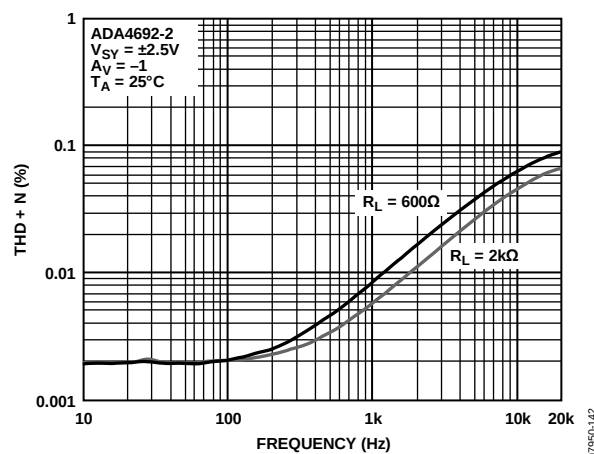


Figure 1. THD + Noise vs. Frequency

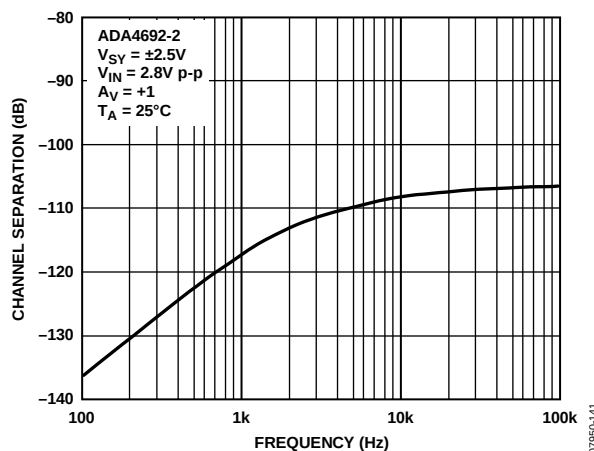


Figure 2. Channel Separation vs. Frequency

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## REVISION HISTORY

### 11/10—Rev. C to Rev. D

Changed 5 V to 6 V in Endnote 2, Table 4 ..... 6

### 12/09—Rev. B to Rev. C

Added ADA4691-4, 16-Lead LFCSP ..... Throughout  
 Added Figure 1, Figure 2, and Table 1; Renumbered  
 Sequentially ..... 1  
 Changes to Applications Section and General Description  
 Section..... 1  
 Changes to Table 1..... 3  
 Changes to Table 2..... 4  
 Changes to Table 4..... 6  
 Updated Outline Dimensions ..... 17  
 Changes to Ordering Guide ..... 20

### 9/09—Rev. A to Rev. B

Added ADA4691-2, 9-Ball WLCSP; ADA4692-2, 8-Lead  
 LFCSP; and ADA4692-4, 14-Lead TSSOP ..... Throughout  
 Changes to General Description ..... 1  
 Updated Outline Dimensions ..... 16  
 Changes to Ordering Guide ..... 17

### 6/09—Rev. 0 to Rev. A

Added ADA4691-2, 10-Lead LFCSP ..... Throughout  
 Changes to Table 1..... 3  
 Changes to Table 2..... 4  
 Changes to Captions for Figure 40, Figure 41, Figure 43, and  
 Figure 44 ..... 13  
 Added Shutdown Operations Section ..... 15  
 Updated Outline Dimensions..... 16  
 Changes to Ordering Guide ..... 16

### 3/09—Revision 0: Initial Version

## SPECIFICATIONS

### ELECTRICAL CHARACTERISTICS—2.7 V OPERATION

$V_{SY} = 2.7\text{ V}$ ,  $V_{CM} = V_{SY}/2$ ,  $T_A = 25^\circ\text{C}$ , unless otherwise specified.

Table 2.

| Parameter                      | Symbol                   | Test Conditions/Comments                                                                    | Min  | Typ      | Max  | Unit                         |
|--------------------------------|--------------------------|---------------------------------------------------------------------------------------------|------|----------|------|------------------------------|
| INPUT CHARACTERISTICS          |                          |                                                                                             |      |          |      |                              |
| Offset Voltage                 | $V_{OS}$                 | $V_{CM} = -0.3\text{ V to }+1.6\text{ V}$                                                   |      | 0.5      | 2.5  | mV                           |
| Dual (ADA469x-2)               |                          | $V_{CM} = -0.1\text{ V to }+1.6\text{ V}; -40^\circ\text{C} < T_A < +125^\circ\text{C}$     |      |          | 3.5  | mV                           |
| Quad (ADA469x-4)               |                          | $V_{CM} = -0.1\text{ V to }+1.6\text{ V}; -40^\circ\text{C} < T_A < +125^\circ\text{C}$     |      |          | 4.0  | mV                           |
| Offset Voltage Drift           | $\Delta V_{OS}/\Delta T$ | $-40^\circ\text{C} < T_A < +125^\circ\text{C}$                                              |      | 1        | 4    | $\mu\text{V}/^\circ\text{C}$ |
| Input Bias Current             | $I_B$                    | $-40^\circ\text{C} < T_A < +125^\circ\text{C}$                                              |      | 0.5      | 5    | pA                           |
| Input Offset Current           | $I_{OS}$                 | $-40^\circ\text{C} < T_A < +125^\circ\text{C}$                                              |      |          | 360  | pA                           |
| Input Voltage Range            |                          | $-40^\circ\text{C} < T_A < +125^\circ\text{C}$                                              |      | 1        | 8    | pA                           |
| Common-Mode Rejection Ratio    | CMRR                     | $V_{CM} = -0.3\text{ V to }+1.6\text{ V}$                                                   |      |          | 225  | pA                           |
| Large Signal Voltage Gain      | $A_{VO}$                 | $V_{CM} = -0.1\text{ V to }+1.6\text{ V}; -40^\circ\text{C} < T_A < +125^\circ\text{C}$     | -0.3 |          | +1.6 | V                            |
|                                |                          | $R_L = 2\text{ k}\Omega$ , $V_{OUT} = 0.5\text{ V to }2.2\text{ V}$                         | 70   | 90       |      | dB                           |
|                                |                          | $-40^\circ\text{C} < T_A < +85^\circ\text{C}$                                               | 62   |          |      | dB                           |
|                                |                          | $-40^\circ\text{C} < T_A < +125^\circ\text{C}$                                              | 90   | 100      |      | dB                           |
|                                |                          | $R_L = 600\text{ }\Omega$ , $V_{OUT} = 0.5\text{ V to }2.2\text{ V}$                        | 80   |          |      | dB                           |
|                                |                          |                                                                                             | 63   |          |      | dB                           |
|                                |                          |                                                                                             | 85   | 95       |      | dB                           |
| Input Capacitance              | $C_{IN}$                 |                                                                                             |      |          |      |                              |
| Differential Mode              | $C_{INDM}$               |                                                                                             |      | 2.5      |      | pF                           |
| Common Mode                    | $C_{INCM}$               |                                                                                             |      | 7        |      | pF                           |
| Logic High Voltage (Enabled)   | $V_{IH}$                 | $-40^\circ\text{C} < T_A < +125^\circ\text{C}$                                              | 1.6  |          |      | V                            |
| Logic Low Voltage (Power-Down) | $V_{IL}$                 | $-40^\circ\text{C} < T_A < +125^\circ\text{C}$                                              |      |          | 0.5  | V                            |
| Logic Input Current (Per Pin)  | $I_{IN}$                 | $-40^\circ\text{C} < T_A < +125^\circ\text{C}$ , $0\text{ V} \leq V_{SD} \leq 2.7\text{ V}$ |      |          | 1    | $\mu\text{A}$                |
| OUTPUT CHARACTERISTICS         |                          |                                                                                             |      |          |      |                              |
| Output Voltage High            | $V_{OH}$                 | $R_L = 2\text{ k}\Omega$ to GND                                                             | 2.65 | 2.67     |      | V                            |
|                                |                          | $-40^\circ\text{C} < T_A < +125^\circ\text{C}$                                              | 2.6  |          |      | V                            |
|                                |                          | $R_L = 600\text{ }\Omega$ to GND                                                            | 2.55 | 2.59     |      | V                            |
|                                |                          | $-40^\circ\text{C} < T_A < +125^\circ\text{C}$                                              | 2.5  |          |      | V                            |
| Output Voltage Low             | $V_{OL}$                 | $R_L = 2\text{ k}\Omega$ to $V_{SY}$                                                        |      | 24       | 30   | mV                           |
|                                |                          | $-40^\circ\text{C} < T_A < +125^\circ\text{C}$                                              |      |          | 40   | mV                           |
|                                |                          | $R_L = 600\text{ }\Omega$ to $V_{SY}$                                                       |      | 78       | 95   | mV                           |
|                                |                          | $-40^\circ\text{C} < T_A < +125^\circ\text{C}$                                              |      |          | 130  | mV                           |
| Short-Circuit Current          | $I_{SC}$                 | $V_{OUT} = V_{SY}$ or GND                                                                   |      | $\pm 15$ |      | mA                           |
| Closed-Loop Output Impedance   | $Z_{OUT}$                | $f = 1\text{ MHz}$ , $A_v = -100$                                                           |      | 372      |      | $\Omega$                     |
| Output Pin Leakage Current     |                          | $-40^\circ\text{C} < T_A < +125^\circ\text{C}$ , shutdown active, $V_{SD} = V_{SS}$         |      | 10       |      | nA                           |
| POWER SUPPLY                   |                          |                                                                                             |      |          |      |                              |
| Power Supply Rejection Ratio   | PSRR                     | $V_S = 2.7\text{ V to }5.5\text{ V}$                                                        | 80   | 90       |      | dB                           |
|                                |                          | $-40^\circ\text{C} < T_A < +125^\circ\text{C}$                                              | 75   |          |      | dB                           |
| Supply Current Per Amplifier   | $I_{SY}$                 | $V_{OUT} = V_{SY}/2$                                                                        |      | 165      | 200  | $\mu\text{A}$                |
|                                |                          | $-40^\circ\text{C} < T_A < +125^\circ\text{C}$                                              |      |          | 240  | $\mu\text{A}$                |
| Supply Current Shutdown Mode   | $I_{SD}$                 | All amplifiers shut down, $V_{SD} = V_{SS}$                                                 |      | 10       |      | nA                           |
|                                |                          | $-40^\circ\text{C} < T_A < +125^\circ\text{C}$                                              |      |          | 2    | $\mu\text{A}$                |

# ADA4691-2/ADA4691-4/ADA4692-2/ADA4692-4

| Parameter                  | Symbol            | Test Conditions/Comments                                                                                 | Min | Typ   | Max | Unit                   |
|----------------------------|-------------------|----------------------------------------------------------------------------------------------------------|-----|-------|-----|------------------------|
| <b>DYNAMIC PERFORMANCE</b> |                   |                                                                                                          |     |       |     |                        |
| Slew Rate                  | SR                | $R_L = 600\ \Omega$ , $C_L = 20\ \text{pF}$ , $A_V = +1$                                                 |     | 1.1   |     | V/ $\mu\text{s}$       |
|                            |                   | $R_L = 2\ \text{k}\Omega$ , $C_L = 20\ \text{pF}$ , $A_V = +1$                                           |     | 1.4   |     | V/ $\mu\text{s}$       |
| Settling Time to 0.1%      | $t_s$             | Step = 0.5 V, $R_L = 2\ \text{k}\Omega$ , 600 $\Omega$                                                   |     | 1     |     | $\mu\text{s}$          |
| Gain Bandwidth Product     | GBP               | $R_L = 1\ \text{M}\Omega$ , $C_L = 35\ \text{pF}$ , $A_V = +1$                                           |     | 3.6   |     | MHz                    |
| Phase Margin               | $\Phi_M$          | $R_L = 1\ \text{M}\Omega$ , $C_L = 35\ \text{pF}$ , $A_V = +1$                                           |     | 49    |     | Degrees                |
| Turn-On/Turn-Off Time      |                   | $R_L = 600\ \Omega$                                                                                      |     | 1     |     | $\mu\text{s}$          |
| <b>NOISE PERFORMANCE</b>   |                   |                                                                                                          |     |       |     |                        |
| Distortion                 | THD + N           | $A_V = -1$ , $R_L = 2\ \text{k}\Omega$ , $f = 1\ \text{kHz}$ , $V_{IN\ \text{rms}} = 0.15\ \text{V rms}$ |     | 0.009 |     | %                      |
|                            |                   | $A_V = -1$ , $R_L = 600\ \Omega$ , $f = 1\ \text{kHz}$ , $V_{IN\ \text{rms}} = 0.15\ \text{V rms}$       |     | 0.01  |     | %                      |
|                            |                   | $A_V = +1$ , $R_L = 2\ \text{k}\Omega$ , $f = 1\ \text{kHz}$ , $V_{IN\ \text{rms}} = 0.15\ \text{V rms}$ |     | 0.006 |     | %                      |
|                            |                   | $A_V = +1$ , $R_L = 600\ \Omega$ , $f = 1\ \text{kHz}$ , $V_{IN\ \text{rms}} = 0.15\ \text{V rms}$       |     | 0.009 |     | %                      |
| Voltage Noise              | $e_n\ \text{p-p}$ | $f = 0.1\ \text{Hz to } 10\ \text{Hz}$                                                                   |     | 3.1   |     | $\mu\text{V p-p}$      |
| Voltage Noise Density      | $e_n$             | $f = 1\ \text{kHz}$                                                                                      |     | 16    |     | nV/ $\sqrt{\text{Hz}}$ |
|                            |                   | $f = 10\ \text{kHz}$                                                                                     |     | 13    |     | nV/ $\sqrt{\text{Hz}}$ |

## ELECTRICAL CHARACTERISTICS—5 V OPERATION

$V_{SY} = 5\ \text{V}$ ,  $V_{CM} = V_{SY}/2$ ,  $T_A = 25^\circ\text{C}$ , unless otherwise specified.

Table 3.

| Parameter                      | Symbol                   | Test Conditions/Comments                                                                      | Min  | Typ | Max  | Unit                         |
|--------------------------------|--------------------------|-----------------------------------------------------------------------------------------------|------|-----|------|------------------------------|
| <b>INPUT CHARACTERISTICS</b>   |                          |                                                                                               |      |     |      |                              |
| Offset Voltage                 | $V_{OS}$                 | $V_{CM} = -0.3\ \text{V to } +3.9\ \text{V}$                                                  |      | 0.5 | 2.5  | mV                           |
| Dual (ADA469x-2)               |                          | $V_{CM} = -0.1\ \text{V to } +3.9\ \text{V}$ ; $-40^\circ\text{C} < T_A < +125^\circ\text{C}$ |      |     | 3.5  | mV                           |
| Quad (ADA469x-4)               |                          | $V_{CM} = -0.1\ \text{V to } +3.9\ \text{V}$ ; $-40^\circ\text{C} < T_A < +125^\circ\text{C}$ |      |     | 4.0  | mV                           |
| Offset Voltage Drift           | $\Delta V_{OS}/\Delta T$ | $-40^\circ\text{C} < T_A < +125^\circ\text{C}$                                                |      | 1   | 4    | $\mu\text{V}/^\circ\text{C}$ |
| Input Bias Current             | $I_B$                    | $-40^\circ\text{C} < T_A < +125^\circ\text{C}$                                                |      | 0.5 | 5    | pA                           |
|                                |                          |                                                                                               |      |     | 360  | pA                           |
| Input Offset Current           | $I_{OS}$                 | $-40^\circ\text{C} < T_A < +125^\circ\text{C}$                                                |      | 1   | 8    | pA                           |
|                                |                          |                                                                                               |      |     | 260  | pA                           |
| Input Voltage Range            |                          | $-40^\circ\text{C} < T_A < +125^\circ\text{C}$                                                | -0.3 |     | +3.9 | V                            |
| Common-Mode Rejection Ratio    | CMRR                     | $V_{CM} = -0.3\ \text{V to } +3.9\ \text{V}$                                                  | 75   | 98  |      | dB                           |
|                                |                          | $V_{CM} = -0.1\ \text{V to } +3.9\ \text{V}$ ; $-40^\circ\text{C} < T_A < +125^\circ\text{C}$ | 68   |     |      | dB                           |
| Large Signal Voltage Gain      | $A_{VO}$                 | $R_L = 2\ \text{k}\Omega$ , $V_O = 0.5\ \text{V to } 4.5\ \text{V}$ , $V_{CM} = 0\ \text{V}$  | 95   | 110 |      | dB                           |
|                                |                          | $-40^\circ\text{C} < T_A < +85^\circ\text{C}$                                                 | 80   |     |      | dB                           |
|                                |                          | $-40^\circ\text{C} < T_A < +125^\circ\text{C}$                                                | 70   |     |      | dB                           |
|                                |                          | $R_L = 600\ \Omega$ , $V_O = 0.5\ \text{V to } 4.5\ \text{V}$ , $V_{CM} = 0\ \text{V}$        | 90   | 100 |      | dB                           |
| Input Capacitance              |                          |                                                                                               |      |     |      |                              |
| Differential Mode              | $C_{INDM}$               |                                                                                               |      | 2.5 |      | pF                           |
| Common Mode                    | $C_{INCM}$               |                                                                                               |      | 7   |      | pF                           |
| Logic High Voltage (Enabled)   | $V_{IH}$                 | $-40^\circ\text{C} < T_A < +125^\circ\text{C}$                                                | 2.0  |     |      | V                            |
| Logic Low Voltage (Power-Down) | $V_{IL}$                 | $-40^\circ\text{C} < T_A < +125^\circ\text{C}$                                                |      |     | 0.8  | V                            |
| Logic Input Current (Per Pin)  | $I_{IN}$                 | $-40^\circ\text{C} < T_A < +125^\circ\text{C}$ , $0\ \text{V} \leq V_{SD} \leq 2.7\ \text{V}$ |      |     | 1    | $\mu\text{A}$                |

# ADA4691-2/ADA4691-4/ADA4692-2/ADA4692-4

| Parameter                    | Symbol             | Test Conditions/Comments                                                                       | Min  | Typ   | Max | Unit    |
|------------------------------|--------------------|------------------------------------------------------------------------------------------------|------|-------|-----|---------|
| OUTPUT CHARACTERISTICS       |                    |                                                                                                |      |       |     |         |
| Output Voltage High          | V <sub>OH</sub>    | R <sub>L</sub> = 2 kΩ<br>−40°C ≤ T <sub>A</sub> ≤ +125°C                                       | 4.95 | 4.97  |     | V       |
|                              |                    | R <sub>L</sub> = 600 Ω to GND<br>−40°C ≤ T <sub>A</sub> ≤ +125°C                               | 4.90 |       |     | V       |
|                              |                    |                                                                                                | 4.85 | 4.88  |     | V       |
|                              |                    |                                                                                                | 4.80 |       |     | V       |
| Output Voltage Low           | V <sub>OL</sub>    | R <sub>L</sub> = 2 kΩ<br>−40°C ≤ T <sub>A</sub> ≤ +125°C                                       |      | 30    | 35  | mV      |
|                              |                    | R <sub>L</sub> = 600 Ω<br>−40°C ≤ T <sub>A</sub> ≤ +125°C                                      |      |       | 50  | mV      |
|                              |                    |                                                                                                |      | 100   | 110 | mV      |
|                              |                    |                                                                                                |      |       | 155 | mV      |
| Short-Circuit Limit          | I <sub>SC</sub>    | V <sub>OUT</sub> = V <sub>SY</sub> or GND                                                      |      | ±55   |     | mA      |
| Closed-Loop Output Impedance | Z <sub>OUT</sub>   | ADA4691-2, f = 1 MHz, A <sub>V</sub> = −100                                                    |      | 364   |     | Ω       |
|                              |                    | ADA4691-2, f = 1 MHz, A <sub>V</sub> = −100                                                    |      | 246   |     | Ω       |
| Output Pin Leakage Current   |                    | −40°C < T <sub>A</sub> < +125°C, shutdown active, V <sub>SD</sub> = V <sub>SS</sub>            |      | 10    |     | nA      |
| POWER SUPPLY                 |                    |                                                                                                |      |       |     |         |
| Power Supply Rejection Ratio | PSRR               | V <sub>SY</sub> = 2.7 V to 5.5 V<br>−40°C ≤ T <sub>A</sub> ≤ +125°C                            | 80   | 90    |     | dB      |
|                              |                    |                                                                                                | 75   |       |     | dB      |
| Supply Current Per Amplifier | I <sub>SY</sub>    | V <sub>OUT</sub> = V <sub>SY</sub> /2<br>−40°C ≤ T <sub>A</sub> ≤ +125°C                       |      | 180   | 225 | μA      |
|                              |                    |                                                                                                |      |       | 275 | μA      |
| Supply Current Shutdown Mode | I <sub>SD</sub>    | All amplifiers shut down, V <sub>SD</sub> = V <sub>SS</sub><br>−40°C ≤ T <sub>A</sub> ≤ +125°C |      | 10    |     | nA      |
|                              |                    |                                                                                                |      |       | 2   | μA      |
| DYNAMIC PERFORMANCE          |                    |                                                                                                |      |       |     |         |
| Slew Rate                    | SR                 | R <sub>L</sub> = 2 kΩ, 600 Ω, C <sub>L</sub> = 20 pF, A <sub>V</sub> = +1                      |      | 1.3   |     | V/μs    |
| Settling Time to 0.1%        | t <sub>S</sub>     | V <sub>IN</sub> = 2 V step, R <sub>L</sub> = 2 kΩ or 600 Ω                                     |      | 1.5   |     | μs      |
| Gain Bandwidth Product       | GBP                | R <sub>L</sub> = 1 MΩ, C <sub>L</sub> = 35 pF, A <sub>V</sub> = +1                             |      | 3.6   |     | MHz     |
| Phase Margin                 | Φ <sub>M</sub>     | R <sub>L</sub> = 1 MΩ, C <sub>L</sub> = 35 pF, A <sub>V</sub> = +1                             |      | 52    |     | Degrees |
| Turn-On/Turn-Off Time        |                    | R <sub>L</sub> = 600 Ω                                                                         |      | 1     |     | μs      |
| NOISE PERFORMANCE            |                    |                                                                                                |      |       |     |         |
| Distortion                   | THD + N            | A <sub>V</sub> = −1, R <sub>L</sub> = 2 kΩ, f = 1 kHz, V <sub>IN</sub> rms = 0.8 V rms         |      | 0.006 |     | %       |
|                              |                    | A <sub>V</sub> = −1, R <sub>L</sub> = 600 Ω, f = 1 kHz, V <sub>IN</sub> rms = 0.8 V rms        |      | 0.008 |     | %       |
|                              |                    | A <sub>V</sub> = +1, R <sub>L</sub> = 2 kΩ, f = 1 kHz, V <sub>IN</sub> rms = 0.8 V rms         |      | 0.001 |     | %       |
|                              |                    | A <sub>V</sub> = +1, R <sub>L</sub> = 600 Ω, f = 1 kHz, V <sub>IN</sub> rms = 0.8 V rms        |      | 0.003 |     | %       |
| Voltage Noise                | e <sub>n</sub> p-p | f = 0.1 Hz to 10 Hz                                                                            |      | 3.2   |     | μV p-p  |
| Voltage Noise Density        | e <sub>n</sub>     | f = 1 kHz                                                                                      |      | 16    |     | nV/√Hz  |
|                              | e <sub>n</sub>     | f = 10 kHz                                                                                     |      | 13    |     | nV/√Hz  |

## ABSOLUTE MAXIMUM RATINGS

Table 4.

| Parameter                               | Rating                                               |
|-----------------------------------------|------------------------------------------------------|
| Supply Voltage                          | 6 V                                                  |
| Input Voltage                           | $V_{SS} - 0.3 \text{ V}$ to $V_{DD} + 0.3 \text{ V}$ |
| Input Current <sup>1</sup>              | $\pm 10 \text{ mA}$                                  |
| Shutdown Pin Rise/Fall Times            | 50 $\mu\text{s}$ maximum                             |
| Differential Input Voltage <sup>2</sup> | $\pm V_{SY}$                                         |
| Output Short-Circuit Duration to GND    | Indefinite                                           |
| Temperature                             |                                                      |
| Storage Temperature Range               | $-65^{\circ}\text{C}$ to $+150^{\circ}\text{C}$      |
| Operating Temperature Range             | $-40^{\circ}\text{C}$ to $+125^{\circ}\text{C}$      |
| Junction Temperature Range              | $-65^{\circ}\text{C}$ to $+150^{\circ}\text{C}$      |
| Lead Temperature (Soldering, 60 sec)    | $300^{\circ}\text{C}$                                |

<sup>1</sup> Input pins have clamp diodes to the supply pins. Limit the input current to 10 mA or less whenever the input signal exceeds the power supply rail by 0.3 V.

<sup>2</sup> Differential input voltage is limited to 6 V or the supply voltage, whichever is less.

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## THERMAL RESISTANCE

$\theta_{JA}$  is specified for the worst-case conditions, that is, a device soldered in a circuit board for surface-mount packages and measured using a standard 4-layer board, unless otherwise specified.

Table 5. Thermal Resistance

| Package Type             | $\theta_{JA}$ | $\theta_{JC}$    | Unit                 |
|--------------------------|---------------|------------------|----------------------|
| 8-Lead SOIC_N (R-8)      | 120           | 45               | $^{\circ}\text{C/W}$ |
| 8-Lead LFCSP (CP-8-6)    | 125           | 40               | $^{\circ}\text{C/W}$ |
| 9-Ball WLCSP (CB-9-3)    | 77            | N/A <sup>1</sup> | $^{\circ}\text{C/W}$ |
| 10-Lead LFCSP (CP-10-11) | 115           | 40               | $^{\circ}\text{C/W}$ |
| 16-Lead LFCSP (CP-16-22) | 75            | 12               | $^{\circ}\text{C/W}$ |
| 14-Lead TSSOP (RU-14)    | 112           | 35               | $^{\circ}\text{C/W}$ |

<sup>1</sup> N/A = not applicable.

## ESD CAUTION



**ESD (electrostatic discharge) sensitive device.** Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

## PIN CONFIGURATIONS

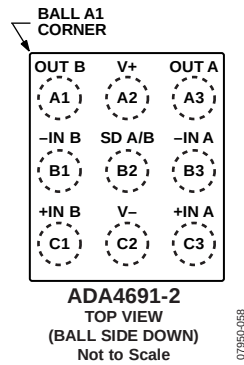


Figure 3. 9-Ball Wafer Level Chip Scale WLCSP (CB-9-3)

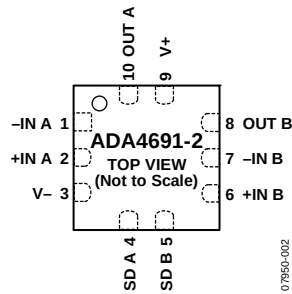
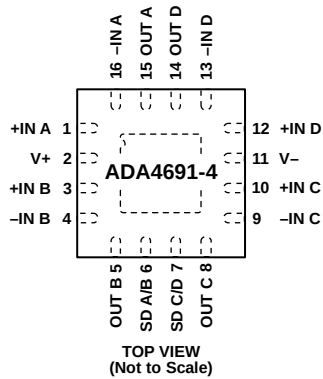


Figure 4. 10-Lead, 2 mm x 2 mm LFCSP (CP-10-11)



**NOTES**  
1. IT IS RECOMMENDED THAT THE EXPOSED PAD BE CONNECTED TO V-.

Figure 5. 16-Lead, 3 mm x 3 mm LFCSP (CP-16-22)

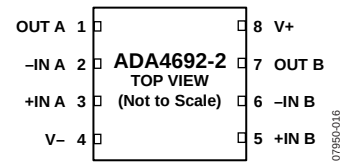


Figure 6. 8-Lead, 2 mm x 2 mm LFCSP (CP-8-6)

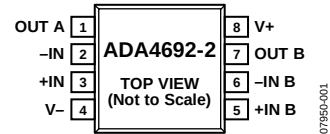


Figure 7. 8-Lead SOIC\_N (R-8)

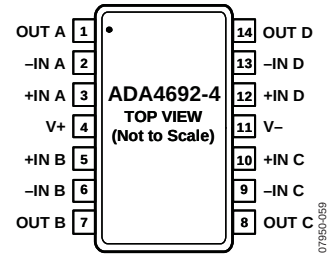


Figure 8. 14-Lead TSSOP (RU-14)

## TYPICAL PERFORMANCE CHARACTERISTICS

$T_A = 25^\circ\text{C}$ , unless otherwise noted.

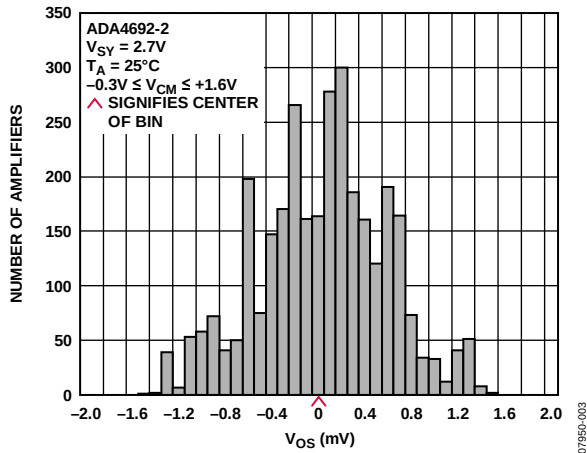


Figure 9. Input Offset Voltage Distribution

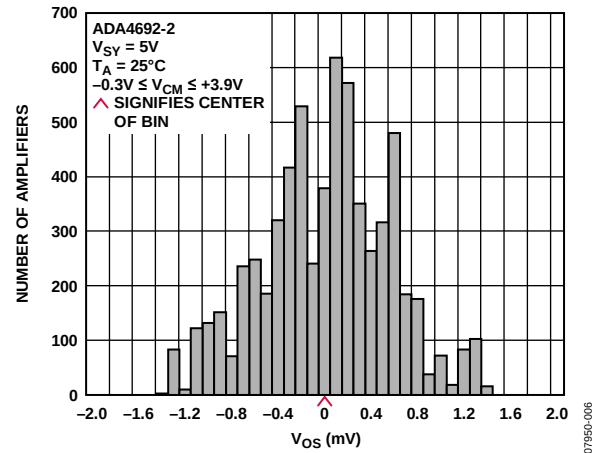


Figure 12. Input Offset Voltage Distribution

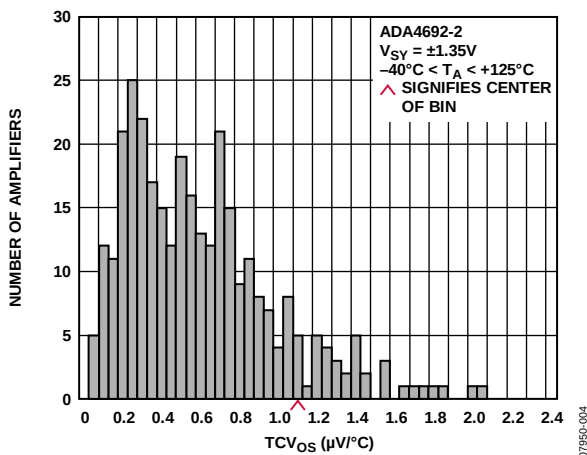


Figure 10. Input Offset Voltage Drift Distribution

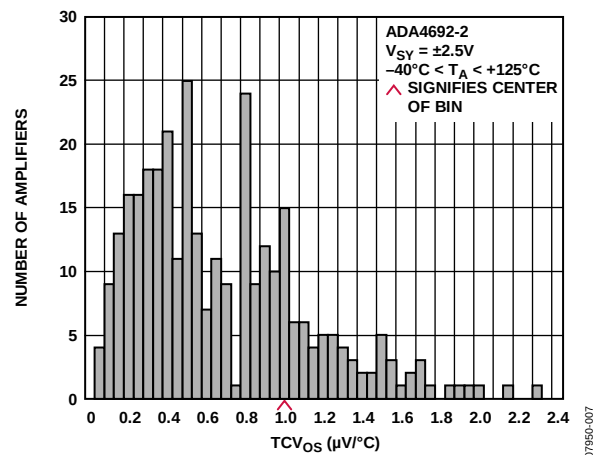


Figure 13. Input Offset Voltage Drift Distribution

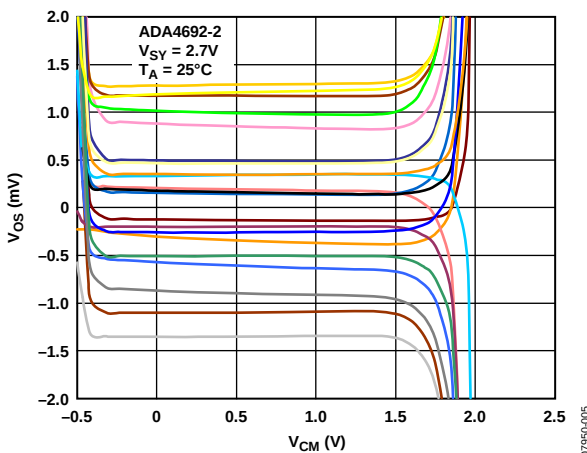


Figure 11. Input Offset Voltage vs. Common-Mode Voltage

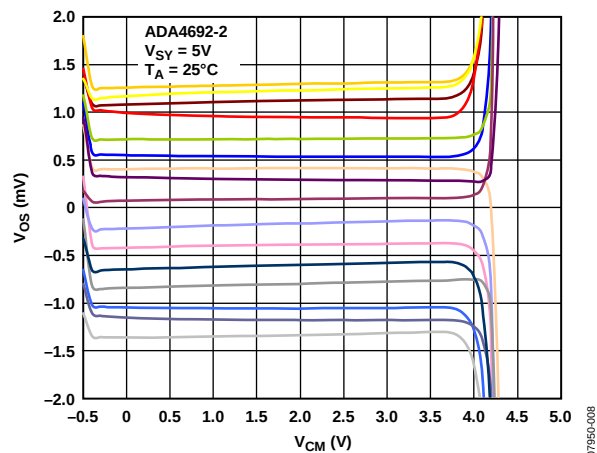


Figure 14. Input Offset Voltage vs. Common-Mode Voltage



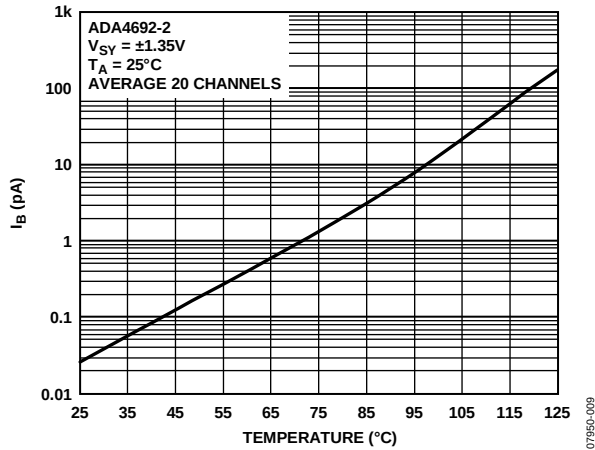


Figure 15. Input Bias Current vs. Temperature

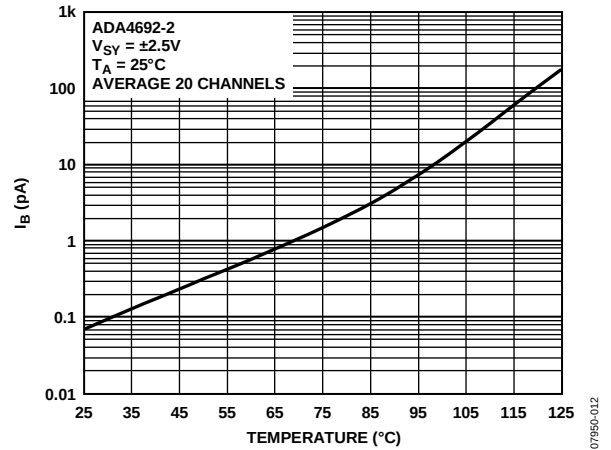


Figure 18. Input Bias Current vs. Temperature

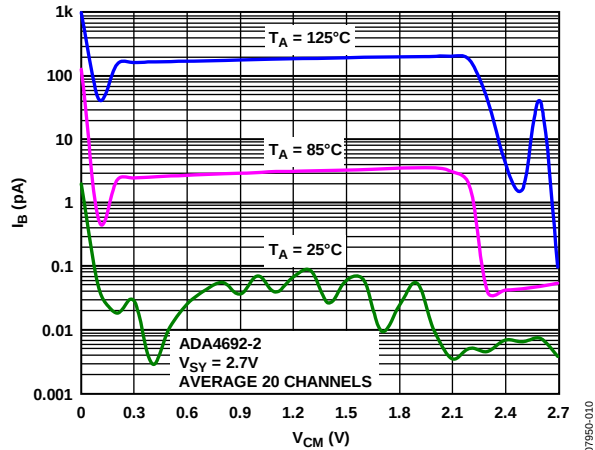


Figure 16. Input Bias Current vs. Common-Mode Voltage

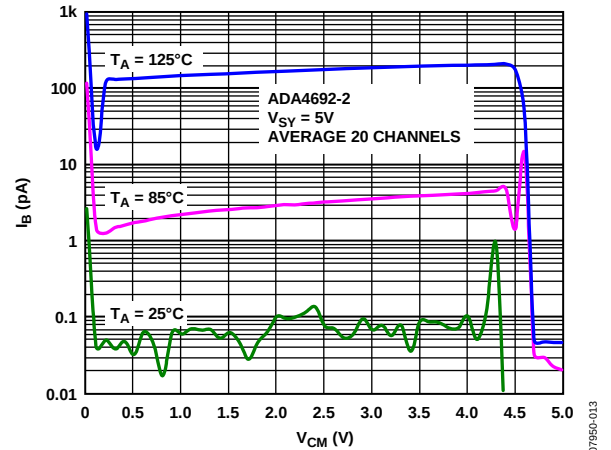


Figure 19. Input Bias Current vs. Common-Mode Voltage

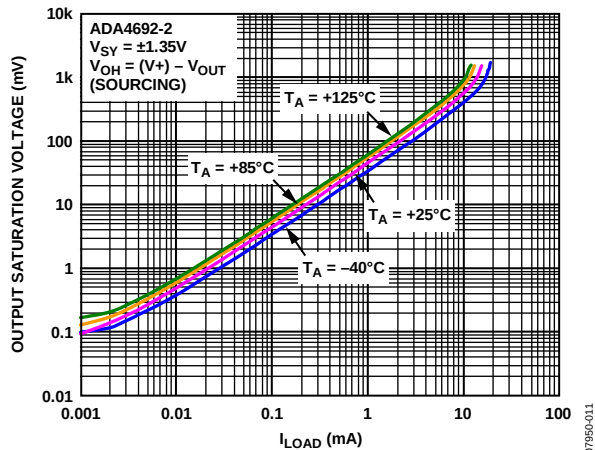


Figure 17. Output Voltage ( $V_{OH}$ ) to Supply Rail vs. Load Current

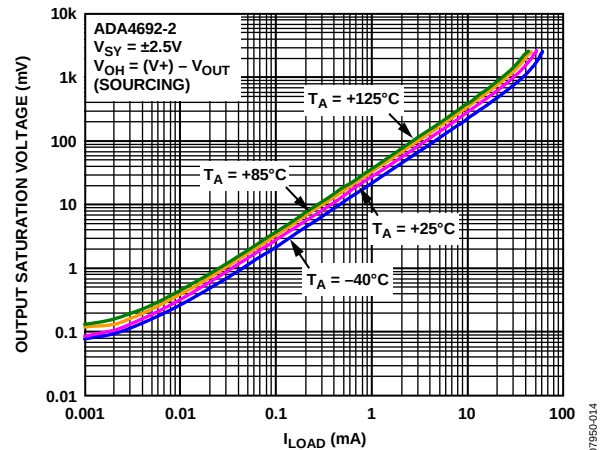


Figure 20. Output Voltage ( $V_{OH}$ ) to Supply Rail vs. Load Current

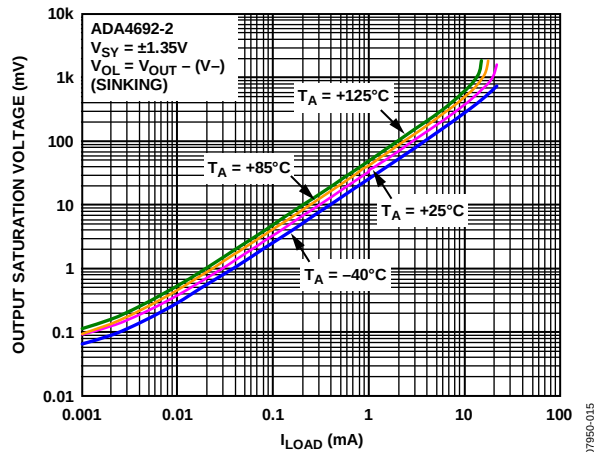


Figure 21. Output Voltage ( $V_{OL}$ ) to Supply Rail vs. Load Current

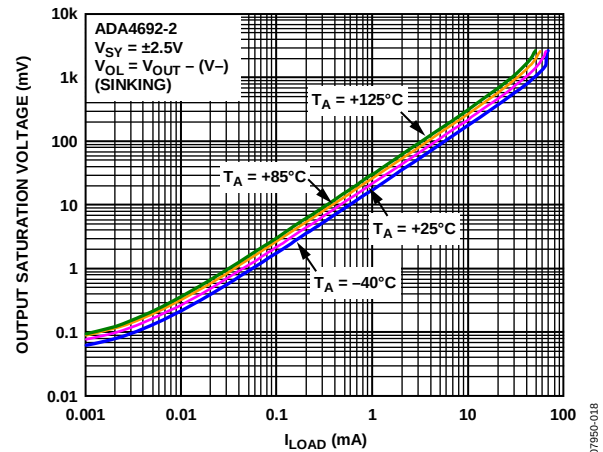


Figure 24. Output Voltage ( $V_{OL}$ ) to Supply Rail vs. Load Current

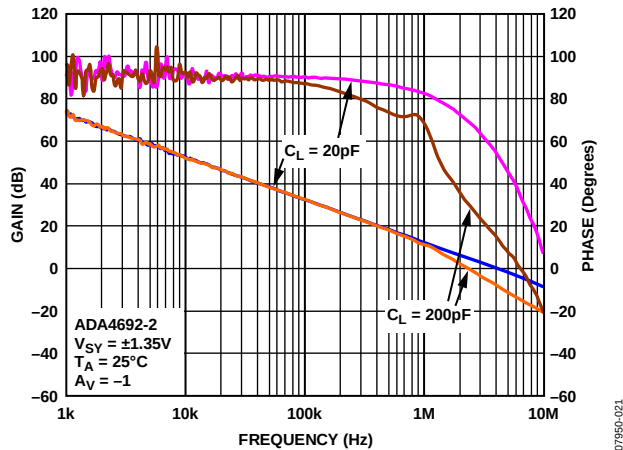


Figure 22. Open-Loop Gain and Phase vs. Frequency

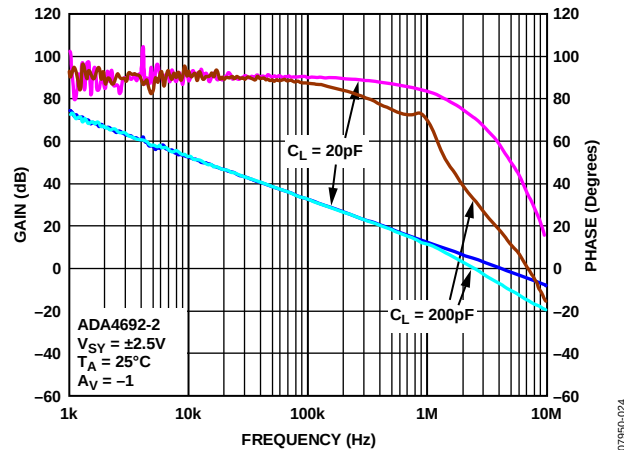


Figure 25. Open-Loop Gain and Phase vs. Frequency

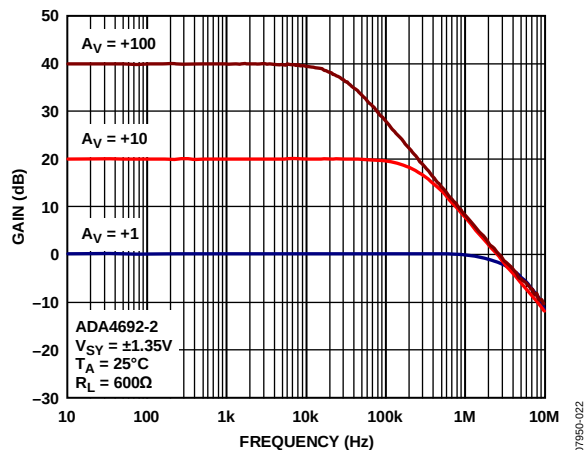


Figure 23. Closed-Loop Gain vs. Frequency

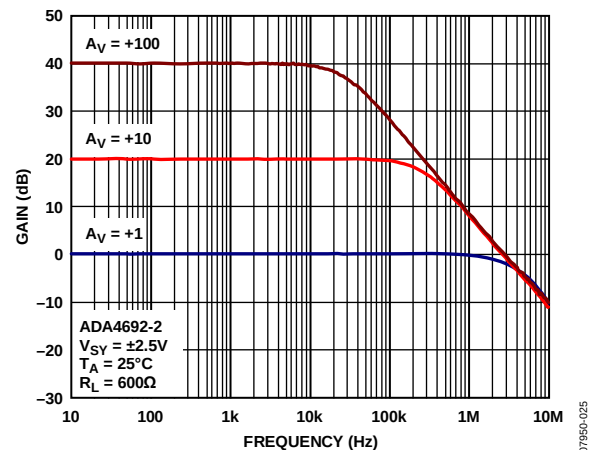


Figure 26. Closed-Loop Gain vs. Frequency

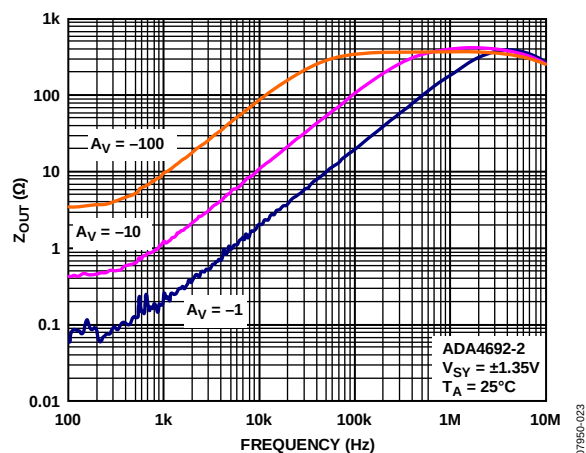


Figure 27. Output Impedance vs. Frequency

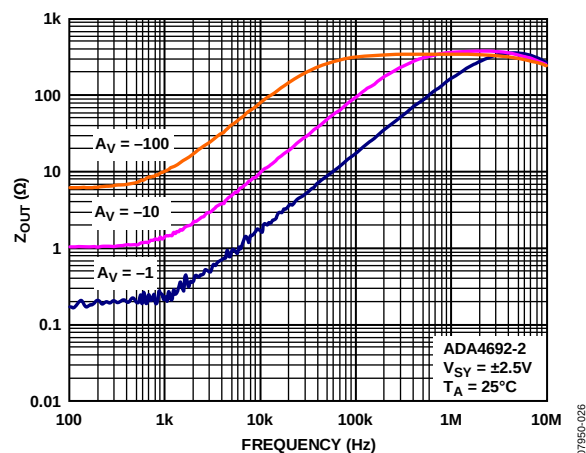


Figure 30. Output Impedance vs. Frequency

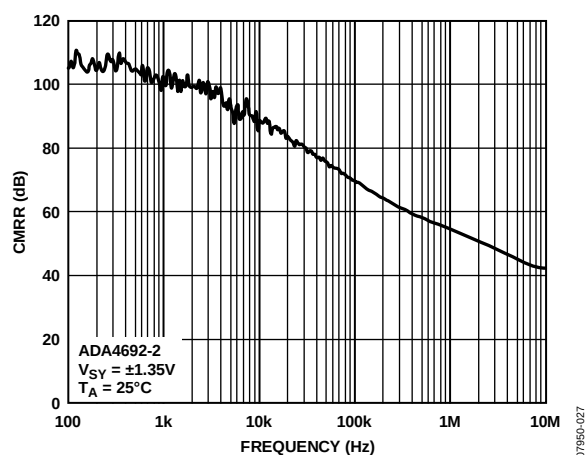


Figure 28. CMRR vs. Frequency

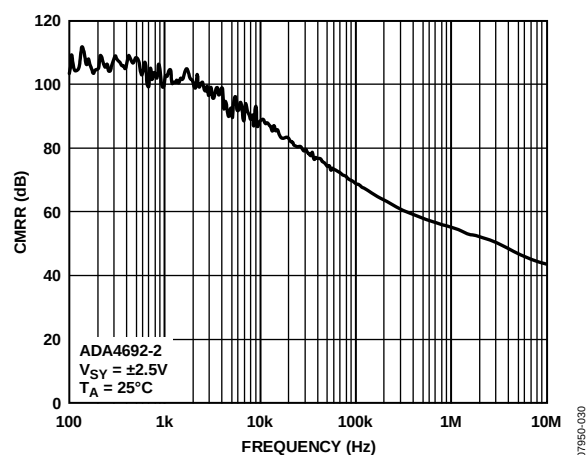


Figure 31. CMRR vs. Frequency

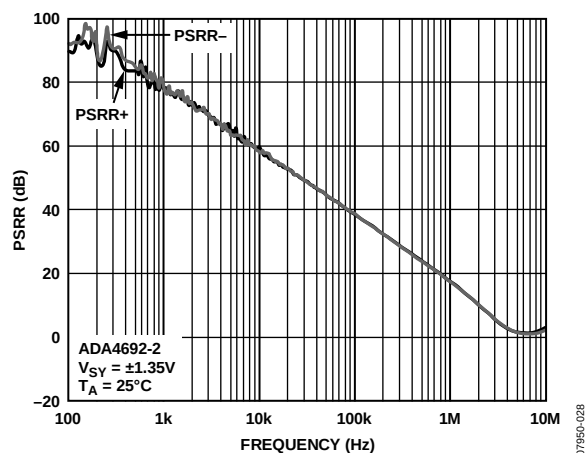


Figure 29. PSRR vs. Frequency

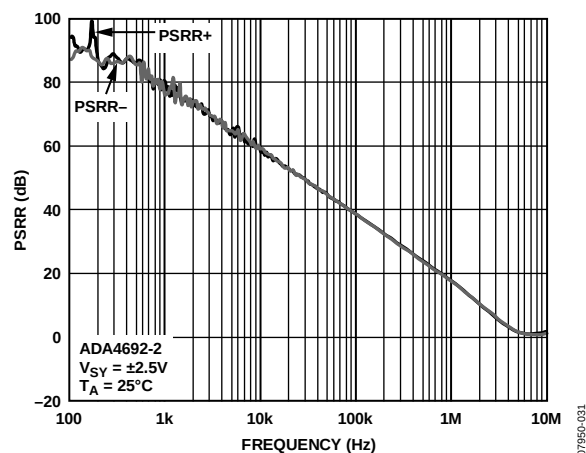


Figure 32. PSRR vs. Frequency

# ADA4691-2/ADA4691-4/ADA4692-2/ADA4692-4

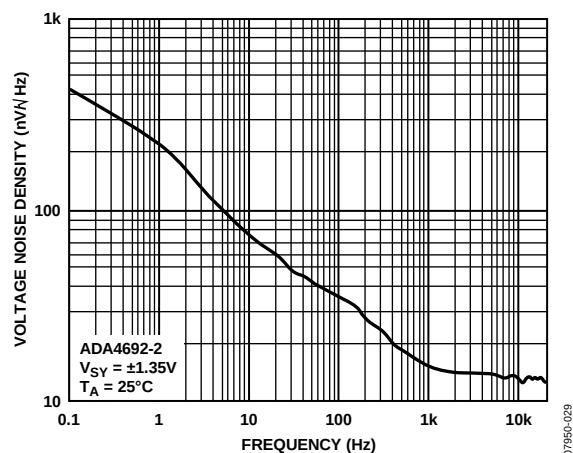


Figure 33. Voltage Noise Density vs. Frequency

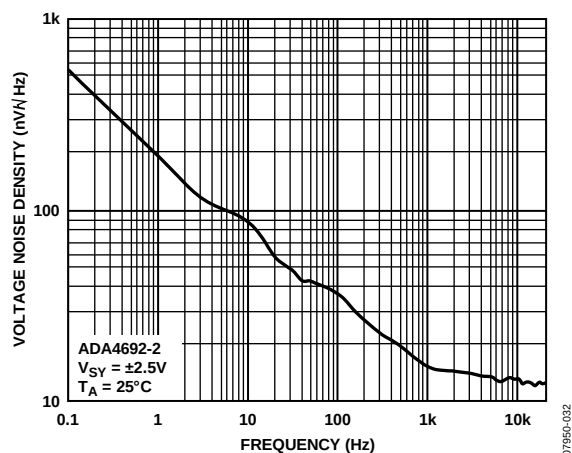


Figure 36. Voltage Noise Density vs. Frequency

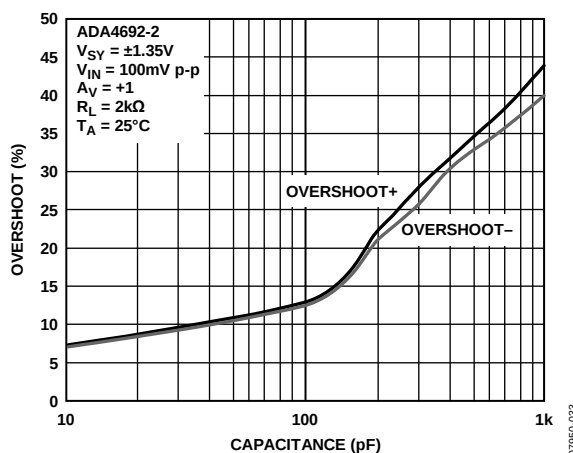


Figure 34. Small Signal Overshoot vs. Load Capacitance

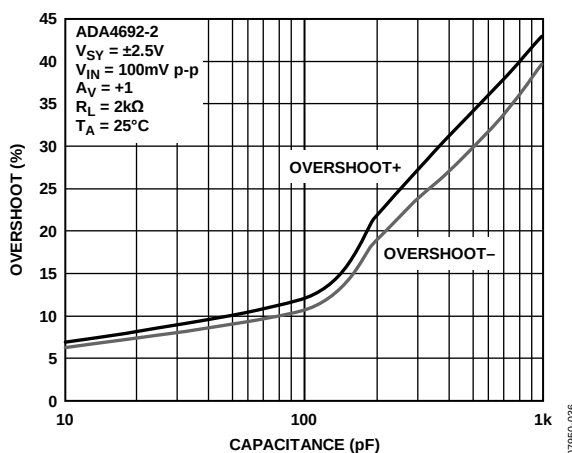


Figure 37. Small Signal Overshoot vs. Load Capacitance

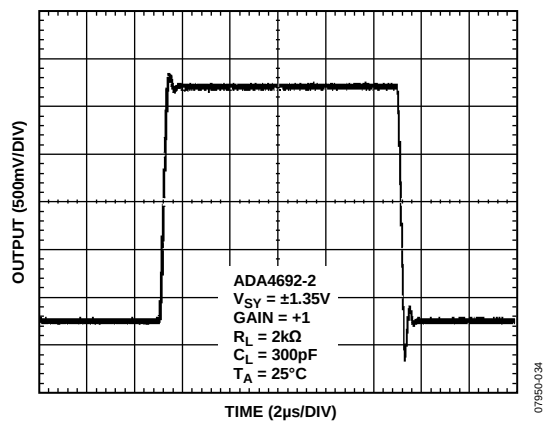


Figure 35. Large Signal Transient Response

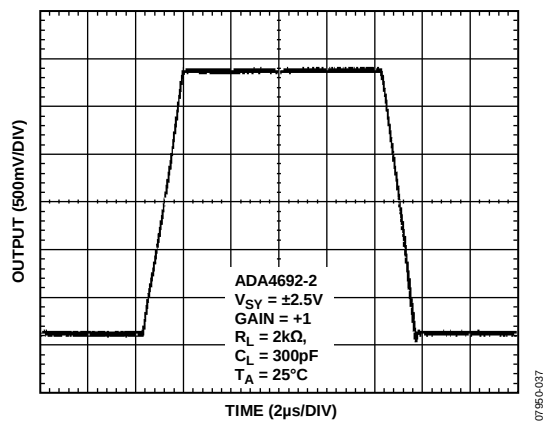


Figure 38. Large Signal Transient Response

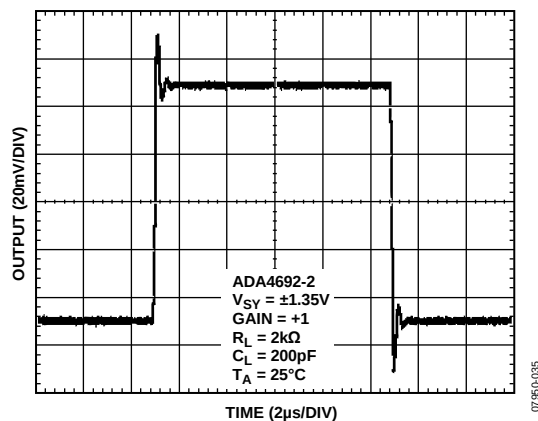


Figure 39. Small Signal Transient Response

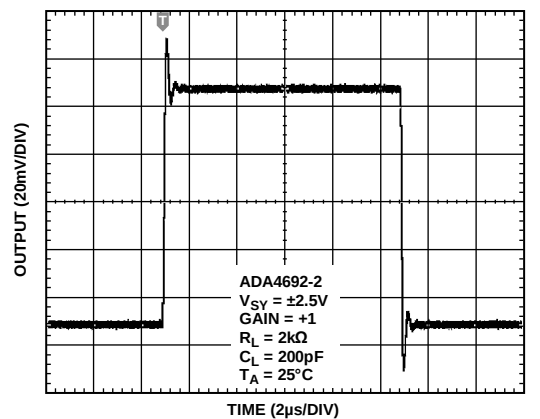


Figure 42. Small Signal Transient Response

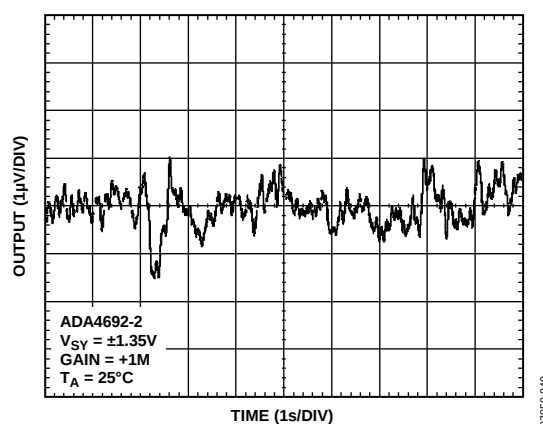


Figure 40. 0.1 Hz to 10 Hz Noise

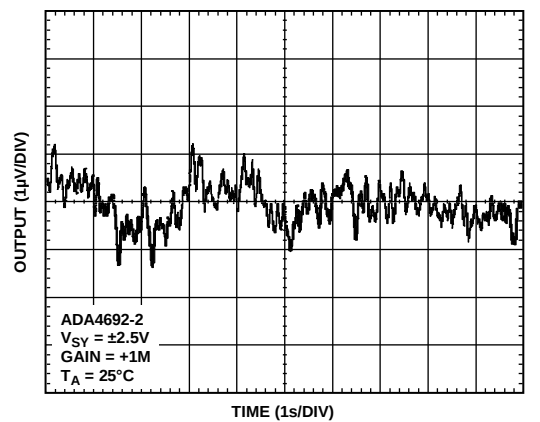


Figure 43. 0.1 Hz to 10 Hz Noise

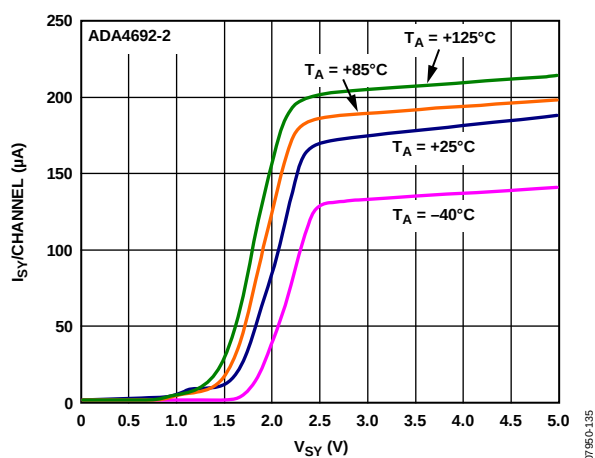


Figure 41. Supply Current per Amplifier vs. Supply Voltage

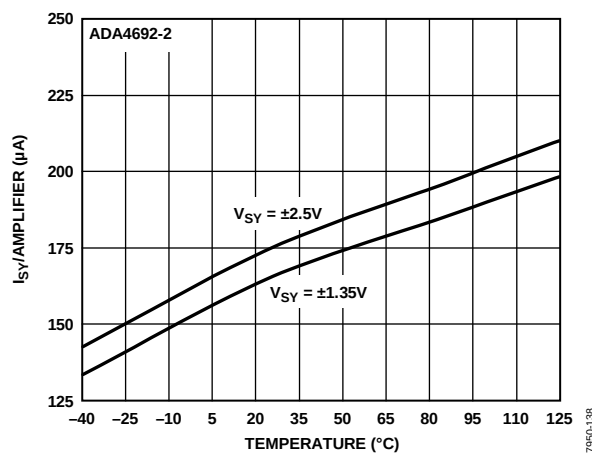


Figure 44. Supply Current per Channel vs. Temperature

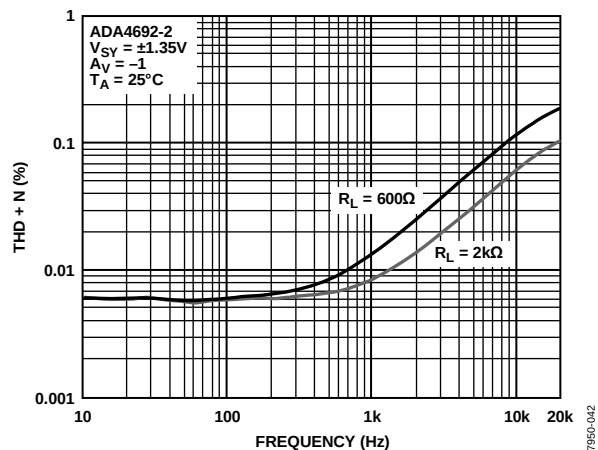


Figure 45. THD + Noise vs. Frequency

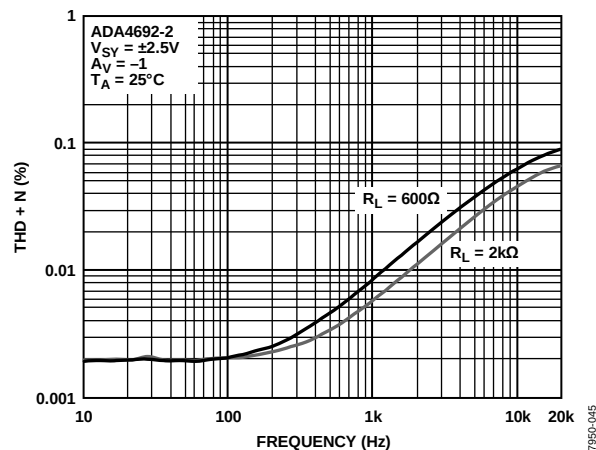


Figure 48. THD + Noise vs. Frequency

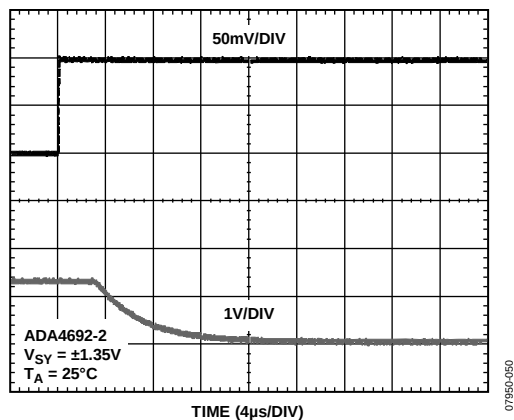


Figure 46. Positive Overload Recovery

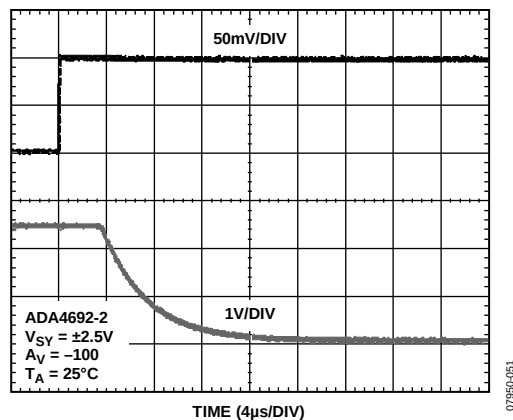


Figure 49. Positive Overload Recovery

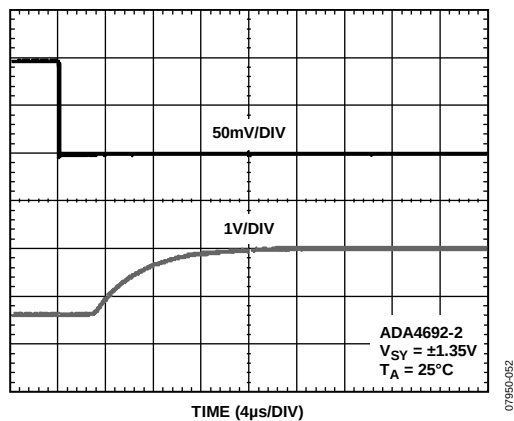


Figure 47. Negative Overload Recovery

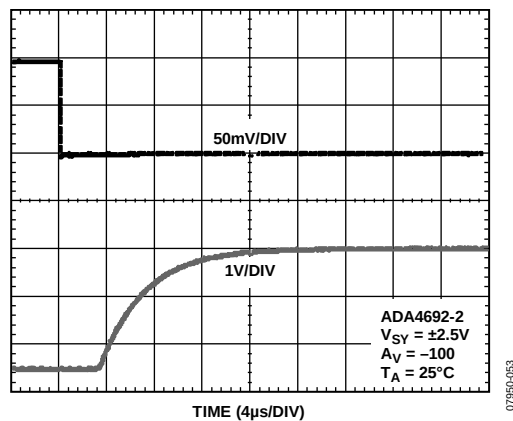


Figure 50. Negative Overload Recovery

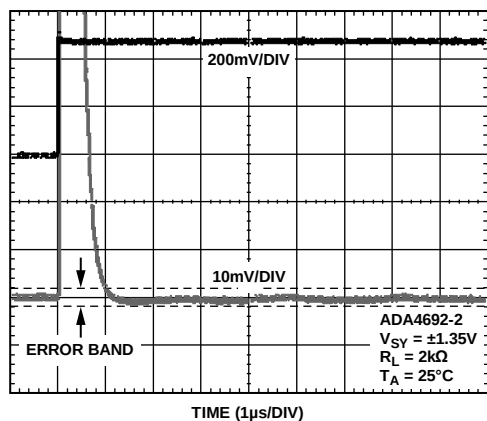


Figure 51. Positive Settling Time to 0.1%

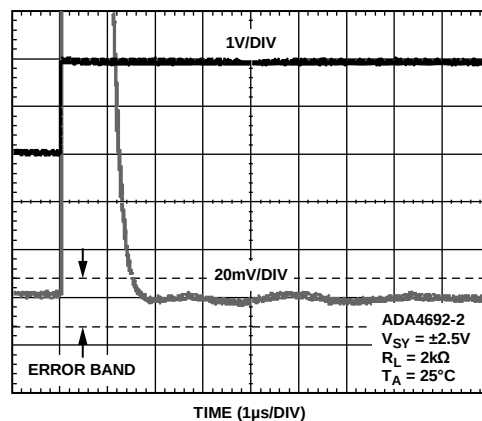


Figure 54. Positive Settling Time to 0.1%

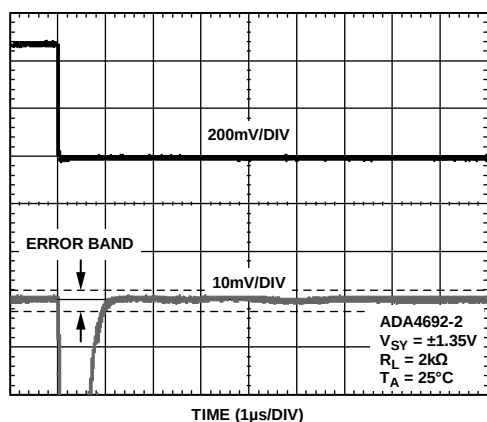


Figure 52. Negative Settling Time to 0.1%

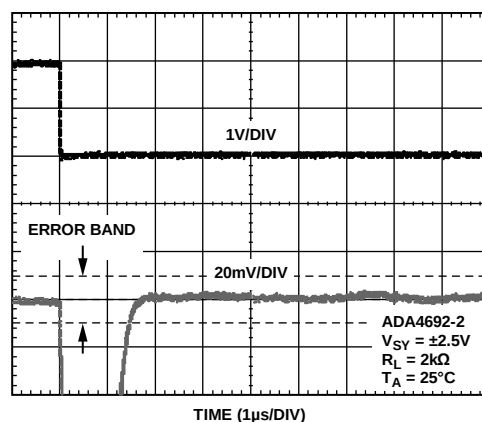


Figure 55. Negative Settling Time to 0.1%

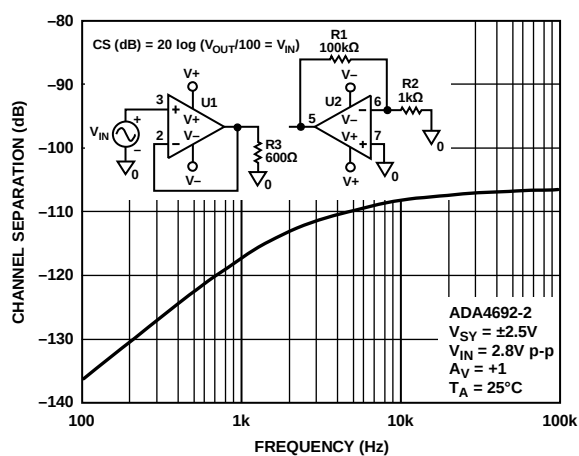


Figure 53. Channel Separation (CS) vs. Frequency

## SHUTDOWN OPERATION

### INPUT PIN CHARACTERISTICS

The ADA4691-2 has a classic CMOS logic inverter input for each shutdown pin, as shown in Figure 56.

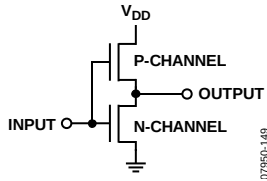


Figure 56. CMOS Inverter

With slowly changing inputs, the top transistor and bottom transistor may be slightly on at the same time, increasing the supply current. This can be avoided by driving the input with a digital logic output having fast rise and fall times. Figure 57 through Figure 59 show the supply current for both sections switching simultaneously with rise times of 1  $\mu$ s, 10  $\mu$ s, and 1 ms. Clearly, the rise and fall times should be faster than 10  $\mu$ s. Using an RC time constant to enable/disable shutdown is not recommended.

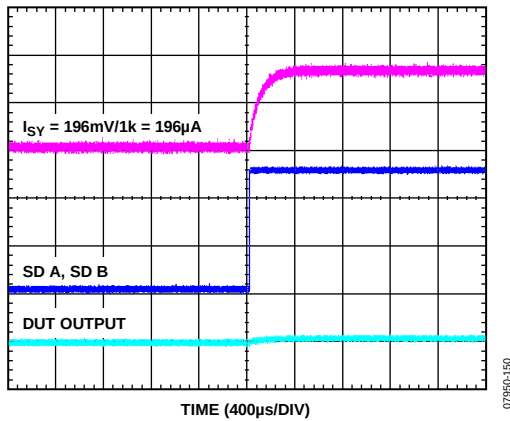


Figure 57. Shutdown Pin Rise Time = 1  $\mu$ s

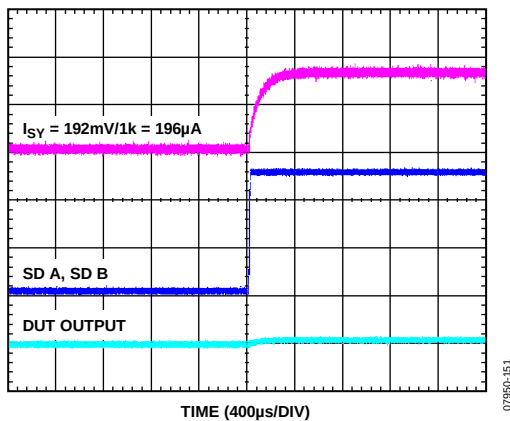


Figure 58. Shutdown Pin Rise Time = 10  $\mu$ s

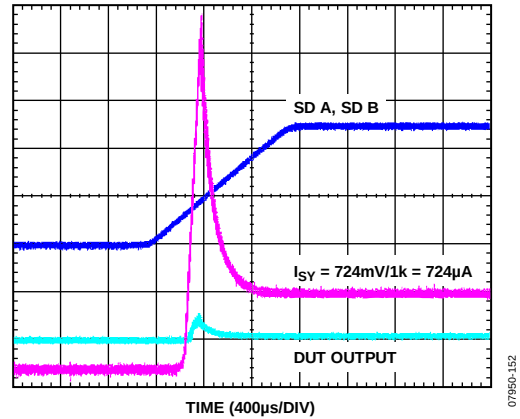


Figure 59. Shutdown Pin Rise Time = 1 ms

### INPUT THRESHOLD

The input threshold is approximately 1.2 V above the V- pin when operating on ground and 5 V and 0.9 V when operating on 2.7 V (see Figure 60 and Figure 61). The threshold is relatively stable over temperature. For operation on split supplies, the logic swing may have to be level shifted.

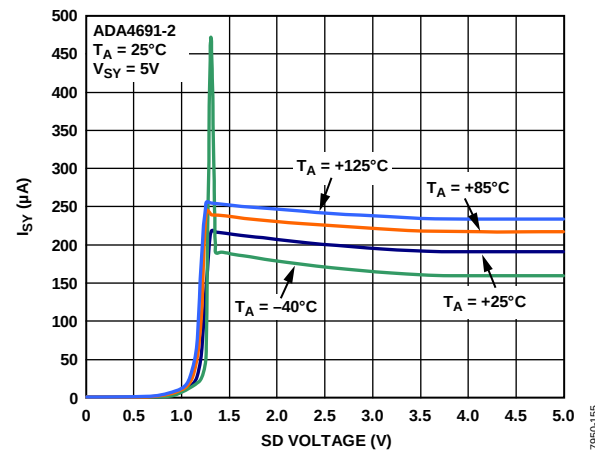


Figure 60. Supply Current vs. Temperature,  $V_{SY} = 5$  V

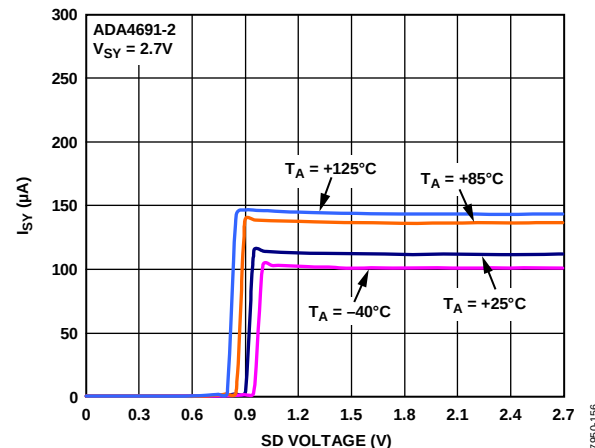
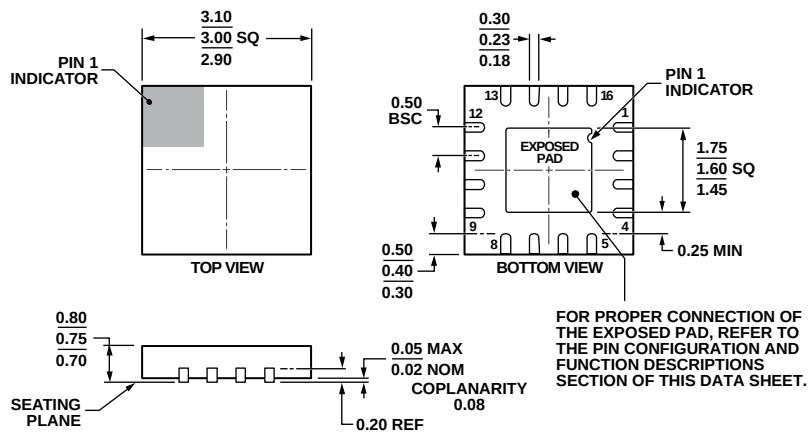


Figure 61. Supply Current vs. Temperature,  $V_{SY} = 2.7$  V



## OUTLINE DIMENSIONS



COMPLIANT TO JEDEC STANDARDS MO-220-WEED-6.

Figure 62. 16-Lead Lead Frame Chip Scale Package [LFCSP\_WQ]  
3 mm × 3 mm Body, Very Very Thin Quad  
(CP-16-22)  
Dimensions shown in millimeters

08-16-2010-E

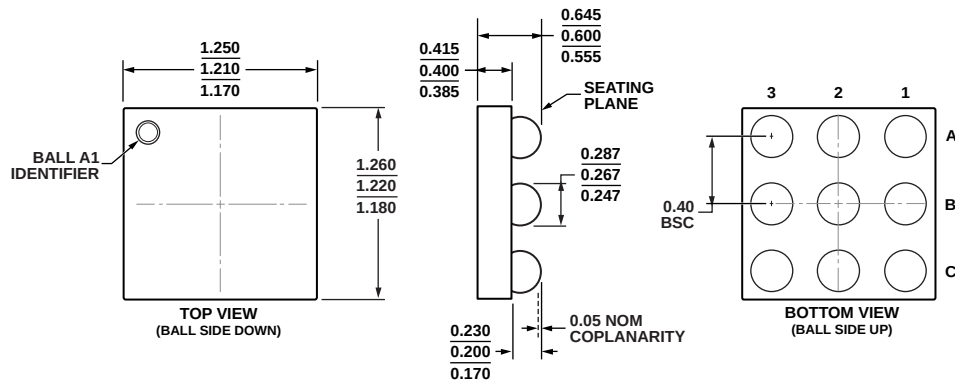


Figure 63. 9-Ball Wafer Level Chip Scale Package [WLCSP]  
(CB-9-3)  
Dimensions shown in millimeters

091709-A

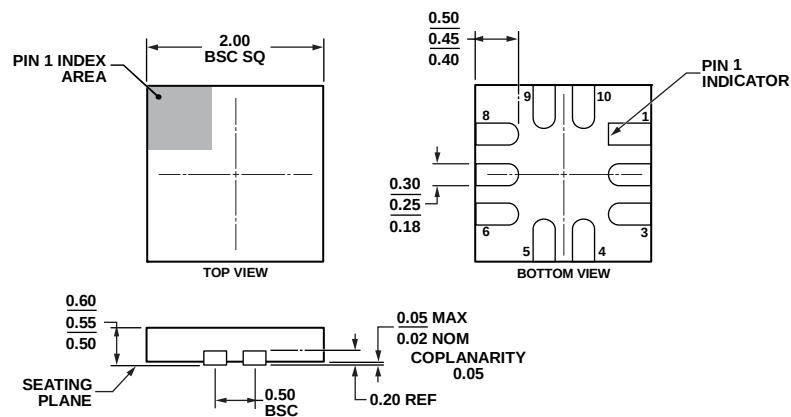


Figure 64. 10-Lead Lead Frame Chip Scale Package [LFCSP\_UQ]  
2 mm × 2 mm Body, Ultra Thin Quad  
(CP-10-11)  
Dimensions shown in millimeters

081308-D

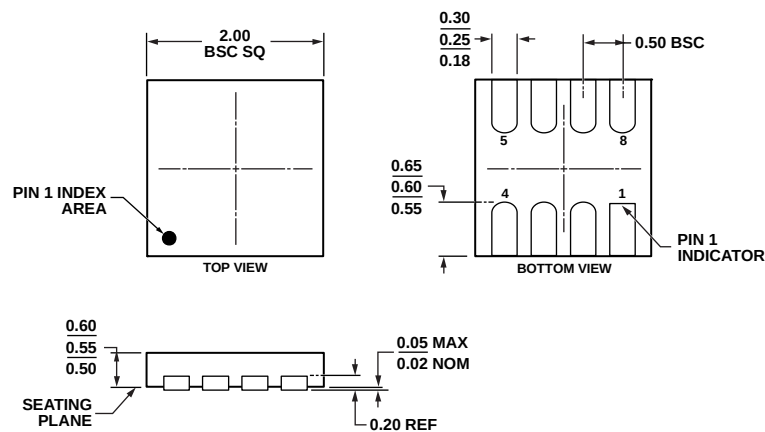
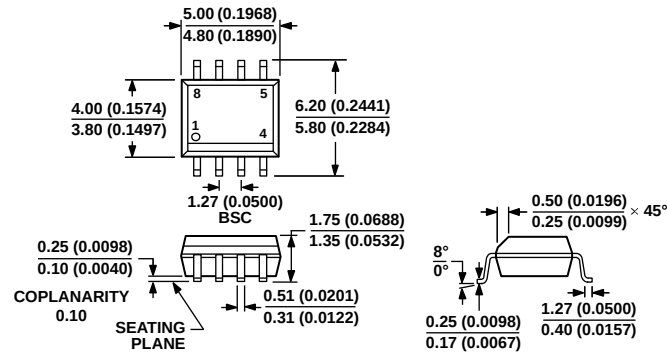


Figure 65. 8-Lead Lead Frame Chip Scale Package [LFCSP\_UD]  
2 mm × 2 mm Body, Ultra Thin, Dual Lead  
(CP-8-6)  
Dimensions shown in millimeters

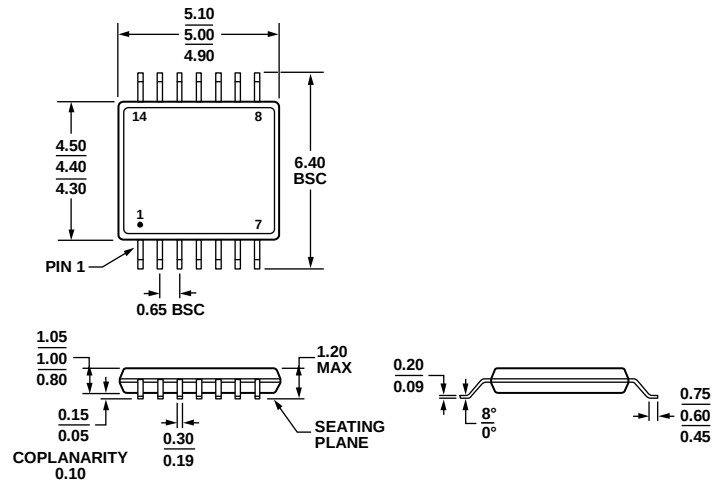
062406-A



COMPLIANT TO JEDEC STANDARDS MS-012-AA  
CONTROLLING DIMENSIONS ARE IN MILLIMETERS; INCH DIMENSIONS (IN PARENTHESES) ARE ROUNDED-OFF MILLIMETER EQUIVALENTS FOR REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN.

Figure 66. 8-Lead Standard Small Outline Package [SOIC\_N]  
Narrow Body  
(R-8)

Dimensions shown in millimeters and (inches)



COMPLIANT TO JEDEC STANDARDS MO-153-AB-1

Figure 67. 14-Lead Thin Shrink Small Outline Package [TSSOP]  
(RU-14)

Dimensions shown in millimeters

# ADA4691-2/ADA4691-4/ADA4692-2/ADA4692-4

## ORDERING GUIDE

| Model <sup>1</sup> | Temperature Range | Package Description | Package Option | Branding |
|--------------------|-------------------|---------------------|----------------|----------|
| ADA4691-2ACBZ-R7   | –40°C to +125°C   | 9-Ball WLCSP        | CB-9-3         | A2C      |
| ADA4691-2ACBZ-RL   | –40°C to +125°C   | 9-Ball WLCSP        | CB-9-3         | A2C      |
| ADA4691-2ACPZ-R7   | –40°C to +125°C   | 10-Lead LFCSP_UQ    | CP-10-11       | A2       |
| ADA4691-2ACPZ-RL   | –40°C to +125°C   | 10-Lead LFCSP_UQ    | CP-10-11       | A2       |
| ADA4691-4ACPZ-R2   | –40°C to +125°C   | 16-Lead LFCSP_WQ    | CP-16-22       | A2P      |
| ADA4691-4ACPZ-R7   | –40°C to +125°C   | 16-Lead LFCSP_WQ    | CP-16-22       | A2P      |
| ADA4691-4ACPZ-RL   | –40°C to +125°C   | 16-Lead LFCSP_WQ    | CP-16-22       | A2P      |
| ADA4692-2ACPZ-R7   | –40°C to +125°C   | 8-Lead LFCSP_UD     | CP-8-6         | A3       |
| ADA4692-2ACPZ-RL   | –40°C to +125°C   | 8-Lead LFCSP_UD     | CP-8-6         | A3       |
| ADA4692-2ARZ       | –40°C to +125°C   | 8-Lead SOIC_N       | R-8            |          |
| ADA4692-2ARZ-R7    | –40°C to +125°C   | 8-Lead SOIC_N       | R-8            |          |
| ADA4692-2ARZ-RL    | –40°C to +125°C   | 8-Lead SOIC_N       | R-8            |          |
| ADA4692-4ARUZ      | –40°C to +125°C   | 14-Lead TSSOP       | RU-14          |          |
| ADA4692-4ARUZ-RL   | –40°C to +125°C   | 14-Lead TSSOP       | RU-14          |          |

<sup>1</sup> Z = RoHS Compliant Part.