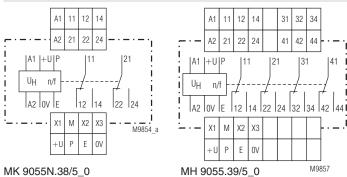
Monitoring Technique

VARIMETER Speed Monitor MK 9055N/5_ _, MH 9055/5_ _





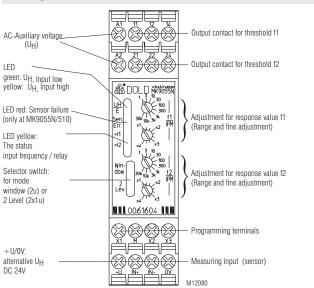
Circuit Diagrams



Connection Terminal

Terminal designation	Signalbeschreibung
A1+, A1	+ / L
A2	- / N
IN+, IN-, P, E	Measuring input
X1, X2, X3	Programming terminals
Μ	Ref. point programming terminals
UA	Analogue output voltage
IA	Analogue output current
+U / 0V	Sensor supply and alternative external auxiliary voltage DC 24 V
11, 12, 14; 21, 22, 24; 31, 32, 34; 41, 42, 44	Speed error-Indicator relay (4 changeover contacts)

Setting



Your Advantage

- Protection of persons, machines and products
- · Easy setting
- Universal input, for configuration of different sensors
- (PNP, NPN, 2-wire, contact, voltage)
- With fast reaction at low speed

Features:

- According to IEC/EN 60 255-1
- Monitoring of 2 frequency levels (e.g. underspeed / standstill and overspeed)
- Separate relay outputs for under- and overfrequency (1 or 2 c/o contacts each)
- As alternative window operating mode (monitoring of a speed range)
 Response value for over- and underspeed / frequency separately
- adjustable in 10 ranges 1 ... 120.000 IPM or 0,15 ... 20.000 Hz • Most fast reaction time also at low speed by time period measurement
- of the input frequency • As option with input for NAMUR-sensors with sensor and
- wire protection against interruption and short circuit Programmable via termminals:
- Start up time delay 0 ... 50 s or controllable
- Alarm delay time of 0 or 0.5 s
- With manual reset or auto reset
- LED-indication for auxiliary voltage, measuring input and output relay; additional LED for indication of wire- / sensor failure at NAMUR-input
- Auxiliary voltages AC 230 V and DC 24 V in one unit
- MH 9055 with wide input range for auxiliary voltage AC/DC 24 ... 60 V or AC/DC 110 ... 230 V (only 2 x 1 C/O)
- As option with analogue output, proportionally to speed
 2 possible contacts
- MK 9055N/5_ 2 x 1 changeover contacs
 MH 9055/5_ 2 x 2 hangeover contacs or wide range aux. voltage
 2 possible compact designs
- MK 9055N/5__: Width 22,5 mm MH 9055/5__: Width 45 mm

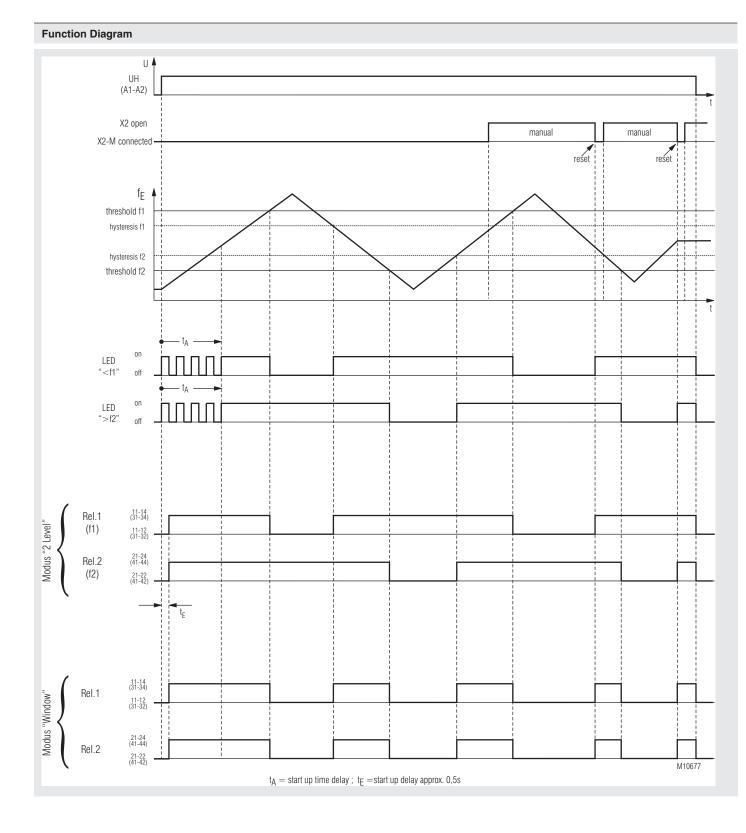
Approvals and Markings



Applications

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- Speed monitoring on rotating machine parts
- Monitoring of cyclic movements
- General monitoring of pulse sequences (transportation, conveyors, production systems),
- Monitoring of pulse frequency (e.g. flow sensors, anemometers)



Function

The auxiliary supply is connected to terminals A1-A2. An operation with alternatively DC 24 V is possible via terminals +U / 0V.

Different sensors can be connected to the measuring input that detects the speed pulses.

The input frequency is compared to the setting value over- and underfrequency (response value f1 or f2 = fine tunig x range).

As the device measures the periods duration the fastest frequency measurement is possible.

If the input frequency is under the threshold f1 (2 upper setting elements on the front) minus hysteresis and over the the threshold f2 (2 lower setting elements on the front) plus hysteresis, both output relays are energized and the Yellow LEDs "<f1" and ">f2" are on.

If the input frequency rises over the threshold f1, in 2-level mode relay 1 de-energizes (contact 11-12 closes); in window mode also relay 2 de-energizes (contact 21-22 closes) the yellow LED "<f1" goes off (alarm state).

Only when the input frequency returns under threshold f1 minus hysteresis the relay (in window mode both relays) energize again and the the yellow LED"<f1" lights up.

If the input frequency goes under the threshold f2, in 2-level mode relay 2 de-energizes (contact 21-22 closes); in window mode also relay 1 de-energizes (contact 11-12 closes) the yellow LED "<f2" goes off (alarm state).

Only when the input frequency returns over threshold f2 plus hysteresis the relay (in window mode both relays) energize again and the the yellow LED"<f2" lights up.

If manual reset is activated (terminal X2 unconnected) the relevant output relays remain in alarm state when the frequency is back in good state and the LED stays off. Reset of the alarm state is the possible by bridging X2-M or by disconnection of the auxiliary supply.

If a start up delay is adjusted, after connection of the auxiliary supply the start up delay elapses. During this time the frequency is not monitored. the yellow LEDs "<f1" and >f2" flash and the output relays are in good state (energized).

During start up delay an alarm signal can be avoided e.g. during the starting period of a motor.

With the sliding switch on the front either 2-level mode or window mode is selected.

"2 level mode": 2 x 1 c/o contact; the output relays switch separately at the corresponding thresholds for f1 and f2. "Window mode": 2 c/o contacts; the output relays switch

simultaneously on threshold f1 and f2 (where f1 > f2), i.e. the relays both de-energise either going over f1 or going under f2.

The variant /510 (NAMUR sensor input) includes broken wire and short circuit monitoring of the sensor and connection wire. A red LED indicates this failure and the output relays switch off.

Indicators Upper LED "UH/E": Auxiliary supply is present, - green: measuring input is Low Auxiliary supply is present, - vellow: measuring input is High - lintermittent red/green flashing if U and impuls sequence present Red LED "Sen.Err": (only at NAMUR input) on, when broken wire or interruption at sensor ciruit detected Lower LED "<f1" (yellow):- on, when inout frequency lower than f1 (relay 1 energized in 2 level mode) Lower LED ">f2" (yellow):- on, when input frequency higher than f2 (relay

wer LED ">f2" (yellow):- on, when input frequency higher than f2 (relay 2 energized in 2 level mode)

LEDs "<f1" and ">f2" flash during start up delay

Notes

Adjustment of threshold f1 and f2 / energized on trip for output relays

Normally the frequency threshold f1 is used for overfrequency and the frequency threshold f2 for underfrequency. The hysteresis works accordingly. Both output relays when adjusted as above work in de-energized on trip mode. in 2 level mode the monitoring and the control of the output relays on both frequency settings f1 and f2 work completely independent. so that f1 can be set higher then f2 when manual reset is not selected. Therefore if F2 is used for overfrequency monitoring the output relay will operate in energized on trip mode as relay 2 (21-22-24) always energises when threshold f2 plus hysteresis is exceeded. Equally the threshold f1 minus hysteresis is used for relay 1 (11-12-14). In windows mode with manual reset the frequency threshold f1 must be always adjusted higher than f2 otherwise the output relays will not energize.

Universal measuring input

The universal input of the speed monitor (terminals +U, P, E, 0V) can handle a large variety of sensors (inductive or capacitve proximity sensors, ultra sonic, halleffect, optical sensors, light barriers, reed contacts etc.). The input is suitable for all sensors according to IEC / EN 60947-5-2 (VDE 0660 part 208).

Depending on the sensor that is used (3-wire PNP or NPN, 2-wire, contact) the connection to the input terminals could be different (see Connection Examples).

As the speed monitor is suitable for a very high maximum frequency, RCelements need to be installed to suppress bouncing of contact sensors (see Connection Examples). It is possible to use standard RC-elements suitable for contact protection or RF interference protection.

NAMUR input

The Variant $M_{9055N/510}$ is optimzed for the connection of NAMUR sensors according to IEC / EN 60947-5-6 (VDE 0660 Teil 212; former EN 50227 / DIN 19234). These 2-wire-sensors are connected to terminals IN+ / IN-(see application example).

Namur sensors have a defined current in ON as well as in OFF state. This allows to detect short circuits and broken wire on sensor and connection wires with this variant. Together with the upper green/yellow LED the type of failure is indicated:

Red LED "Sen..Err" ON and upper LED "UH/E" lights up green: Broken wire at input circuit Red LED "Sen..Err" ON and upper LED "UH/E" lights up yellow: Short circuit at input circuit

Instead of a NAMUR sensor also a contact sensor with correspondent resistor circuit can be used (see Connection Examples). The suggested resistors are necessary to avoid broken wire or short circuit detection alarm. If the resistors are connected directly on the sensor side, the wiring still is monitored. Because of contact bouncing of mechanical contacts a capacitor has to be connected on the measuring input terminals.

Sensor supply, 24V DC auxiliary supply as alternative

The input circuit (+U, P, E, 0V) is galvanic separated to the auxiliary supply A1, A2 (eg. AC 230V). By connecting AC 230V auxiliary voltage on terminals A1-A2 the unit provides a voltage of approx. 24 V max 20mA to supply external sensors. If the auxiliary supply is DC 24V or sensors with higher power consumption are used, the DC 24V auxiliary supply is connected to terminals +U / 0V. The sensors are also supplied from this source. (In this case there is no galvanic separation between auxiliary supply and measuring input).

Monitoring indicator of sensor input

The upper 2-coloure LED shows the connected supply voltage and the electrical state of the measuring input: Green: input E ist on LOW level Yellow: input E ion HIGH level Depending on the type of sensor (PNP, NPN, 2-wire, NO or NC contact) the actual state (active or inactive) is indicated. Green / yellow: input pulses from sensor present

Several speed monitors on one sensor

Parallel operation of several speed monitors on one sensor is possible the universal input e.g. to monitor several speed levels. The corresponding terminals are all connected in parallel.

Programming terminals (M-X1-X2-X3):

Attention! The terminals M-X1-X2-X3 have no galvanic separation to the measuring circuit (+U / P / E / 0V) e.g. auxiliary voltage DC 24 V

Notes

- M: Common connection (Ground) of the programming terminals (identically with 0V
- X1: Start up delay with range 0...50 s by bridging X1 with M using a resistor or potentiometer (see Technical Data). If no start up delay is required X1-M has to be bridged
- X2: Manual reset with NO contact push button on X2-M, auto reset with terminals X2-M bridged.
- X3: With open terminal: alarm delay = 0.5 s, bridged with M no time delay.

Start up delay

A start up delay (t_A , 0 ... 50 s) is adjusted by connecting terminal X1 with M via a resistor 0... 500 kOhm (details see technical data) and it is initiated when the power supply is connected. During this time the frequency is not monitored and both output relays are energised.

If the connection X1-M is interrupted (resistance > 500 kOhm), the start up delay is permanent, this allows to disable the monitoring by an external contact until a system reaches the operational state. Closing the external contact will initiate the start up delay determined by a connected resistor. If no start up delay is required X1-M needs to be bridged.

The X1-M connection is necessary to enable the monitoring of the frequency.

During elapse of the sart up delay the yellow LEDs <f1 and >f2 flash with a 2 Hz frequency. to adjust a certain time in seconds the number of flashes can be counted as setting aid. The number of flashes divided by 2 gives the delay time in seconds.

Manual reset

To store the alarm states for over or underfrequency, the X2 terminal needs to be unconnected. The alarm storing has effect on the relays and corresponding LEDs By bridging X2-M or disconnecting the power supply the alarm state is reset.

Variants with Analogue Output Indicating the Actual Speed / Frequency

With this variant the programming terminal X3 is replaced by terminal UA or IA, that provides an analogue signal proportional to the speed with reference to terminal 0V. This signal is either 0 ... 10 V or 0 ... 20 mA or 4 ... 20 mA. As the X3 terminal is not available, these variants do not have an alarm delay.

With the variant /517 (NAMUR sensor input with analogue output 4 ... 20 mA) the analogue output also indicates a sensor or wiring failure by switching the output to 0 mA.

The analogue output has no galvanic separation to measuring input and the alternative auxiliary supply on terminals +U/0V.

Technical Data

Frequency Measuring Input

Universal Input (+U / P / E 0V)

for PNP-, NPN-, 2-wire sensors, contacts and voltages, connection see application examples;

suitable for all proximity sensors according to IEC / EN 60947-5-2 (VDE 0660 part 208)

built in power supply approx. DC 24 V / max. 20 mA on terminals +U / 0V; Alternatively external auxiliary voltage supply DC 24 V via terminals +U / 0V

Max, residual current

at 2-wire sensors:	2 mA (OFF state)
Max. voltage drops	
at 2-wire sensors:	8 V (ON state)
Voltage control	
Input resistance:	Approx. 17 k Ω
Low-capability:	≤ 8 V
High-capability:	≥11 V

NAMUR Input (Variant /510) IN+ / IN-

 for NAMUR sensors according to IEC/EN 60947-5-6 (VDE 0660 part 212)

 No-load voltage:
 Approx. 8.2 V

 Input resistance:
 Approx. 1 kΩ

 Short circuit current:
 Approx. 8 mA

response value	
Low:	Typ. 1.55 mA
High:	Typ. 1.75 mA
Broken wire threshold:	≤ 0.15 mA
short circuit threshold:	≥6 mA

Alternatively external auxiliary voltage supply DC 24 V via terminals +U / 0V

Common Data for Inputs

v	Response value (f1 / f2) 10 ranges each: 1 120.000 IPM										
nal	range	1	2	3	4	5	6	7	8	9	10
ith or	Imp. /	1	3	10	30	100	300	1.000	3.000	10.000	30.000
ve	min	to	to	to	to	to	to	to	to	to	to
		4	12	40	120	400	1.200	4.000	12.000	40.000	120.000

	oder 0,15 20.000 Hz									
range	1	2	3	4	5	6	7	8	9	10
	0.15	0,5	1,5	5	15	50	150	500	1.500	5.000
Hz	to	to	to	to	to	to	to	to	to	to
	0.6	2	6	20	60	200	600	2.000	6.000	20.000

1.5 kHz

5 kHz

25 kHz

Fine adjustment: Max. input frequency

(Impuls : Pause = 1 : 1) Range 1 ... 4: Range 5 ... 7: Range 8 ... 10: **Min. pulse- and breaktime** Range 1 ... 4: Range 5 ... 7: Range 8 ... 10:

Stability of the setting threshold at variation of auxiliary voltage and temperature: Hysteresis: Reaction time of Frequency monitoring:

Response delay: with terminal X3 open: with X3-M bridged: Infinite 1:4 each range

350 μs 100 μs 20 μs the "higher" range of the f1 and f2 determines the above values.

2 % Fixed, approx. 5% at f1 and f2

(Alarm delay set to 0) Duration of 1 cycle (inverse value of adjusted frequency) + 10 ms (at over frequency: inverse value of signal frequency + 10 ms)

0,5 s No response delay

Technical Data			Technical Data	
Start up delay:	Adjustable von 0 5 resitor/potentiometer		General Data	
	terminals X1-M:		Nominal operating mode: Temperature range	conti
$R/k\Omega$: 0 15 22 3 h k <td< td=""><td></td><td>50 220 470 ∞</td><td>Operation:</td><td>- 20</td></td<>		50 220 470 ∞	Operation:	- 20
t _v /s: 0 0.3 0.7 1.	.3 2.3 5 9 1	5 25 50 ∞	Storage:	- 20
Time between connection of auxiliary supply and ready to mesure	Approx. 0,5 s (with s	tart up delay is 0)	Altitude: Clearance and creepage dis rated impulse voltage / pollution degree:	< 2,0 stance
Auxiliary Voltage (A1-A2; bz	w. +U / 0V)		Contact to measuring input: Contact to auxiliary circuit:	4 kV 4 kV
Auxiliary voltage U _{H:}	AC 115, 230, 400 V (via terminals +U / 0	V)	Contact to Contact: Auxiliary circuit A1-A2 to measuring input:	4 kV 4 kV 4 kV
	(Terminals +U / 0V h separation to measu		Programming terminals M-X1-X2-X3:	withc
	AC/DC 24 60, 110 MH-version possible		Auxiliary voltage DC 24 V (an +U / 0V):	withc
Voltage range AC:	0.8 1.1 U		Analogue output, optional (UA / IA):	witho
DC:	0.85 1.2 U _H		EMC	
AC/DC:	0.75 1.2 U _H		Electrostatic discharge:	8 kV
Frequency range	45 440 Hz		HF-irradiation 80 MHz 1 GHz:	12 V
AC: Nominal consumption:	45 440 HZ		1 GHz 2.7 GHz:	10 V
AC:	approx. 4 VA		Fast transients: Surge voltage	2 kV
DC:	approx. 2 W		between	
Contact Output (11-12-14, 21-2	2-24 + 31-32-34, 41-42-44	4 bei MH 9055.39/5)	wires for power supply:	1 kV
. .	,		HF-wire guided Interference suppression:	10 V Limit
Contacts : MK 9055N.38/5:	2 x 1 changeover co		Degree of protection: Housing:	IP 40
MH 9055.39/5:1 for over and underfrequency alarm each 2 x 2 changeover contacta 2 for over and underfrequency alarm each			Terminals: Housing:	IP 20 thern
Thermal curren I _{th} : Switching capacity to AC 15	4 A		Vibration resistance:	acc. Ampl frequ
NO contacts: NC contacts:	3 A / AC 230 V 1 A / AC 230 V	IEC/EN 60 947-5-1 IEC/EN 60 947-5-1	Climate resistance: Terminal designation: Wire connection:	20 / (EN 5
to DC 13 NO contacts:	1 A / DC 24 V	IEC/EN 60 947-5-1	wire connection:	1 x 4 2 x 2
NC contacts:	1 A / DC 24 V	IEC/EN 60 947-5-1		1 x 2
Electrcal life				DIN
to AC 15 at 1 A, AC 230 V: short circuit strength	1,5 x 10⁵ switch.cycl	. IEC/EN 60 947-5-1		2 x 1 DIN 4
max. fuse rating:	4 A gG / gL	IEC/EN 60 947-5-1	Wire fixing:	Plus-
Mechanicl life:	\geq 30 x 10 ⁶ switching	cycles	Fining towns	termi
Analogue volt. output (varian	t /5_5, terminal "UA" aç	gainst "0V")	Fixing torque: Mounting: Weight:	0.8 N DIN-
Nominal output voltage:	0 10 V, linear prop	ortional to the	MK 9055N.38/5 ,	
	speed / frequency, w separation to measure		MH 9055.38/5: MH 9055.39/5:	Appr Appr
Load: Scale:	DC 24 V-supply max. 10 mA 0 V at 0 IPM / Hz		Dimensions	
evulo.	5 V at setting end of	scale value of	Width x height x depth:	
	speed / frequency 10 V at input frequer		MK 9055N/5: MH 9055/5:	22.5 45
Accuracy:	scale value 3 %			
Analogue current output (va	riant /5_6, or 5_7; termi	nal "IA" against "0V")		
Output:	0 20 mA bzw. 4	20 mA. linear		
Max. burden: Scale:	proportional to the series without galvanic sepainput and DC 24 V-st 500 Ω 0 mA e.g. 4 mA at 10 mA e.g. 12 mA at scale value 20 mA at input frequ	peed / frequency, aration to measuring upply 0 IPM / Hz setting end of		
	scale value			
Fault signal at NAMUR input:	at output 4 20 mA	(variant /017)		
namon input.	on sensor failure cur			
Accuracy:	3 %			

3 %

Accuracy:

continuous operation

IEC 60 664-1

IEC 60 664-1

IEC 60 664-1

IEC 60 664-1

IEC/EN 61 000-4-2

IEC/EN 61 000-4-3

IEC/EN 61 000-4-3 IEC/EN 61 000-4-4

IEC/EN 61 000-4-5

IEC/EN 61 000-4-6

EN 55 011

IEC/EN 60 529

IEC/EN 60 529

IEC/EN 60 068-1

IEC/EN 60 715

without galv. separat. to measuring input

without galv. separat. to measuring input

without galv. separat. to measuring input

- 20 ... + 60 °C - 20 ... + 60 °C < 2,000 m

4 kV / 2

4 kV / 2 4 kV / 2

4 kV / 2

8 kV (air)

12 V / m

10 V / m

IP 40

IP 20

Limit value class B

acc. to UL subject 94 Amplitude 0.35 mm

20/060/04

EN 50 005 1 x 4 mm² solid or 2 x 2.5 mm² solid or

0.8 Nm DIN-rail

Approx. 210 g Approx. 360 g

22.5 x 90 x 97 mm 45 x 90 x 97 mm

thermoplastic with VO behaviour

frequency 10 ... 55 Hz IEC/EN 60 068-2-6

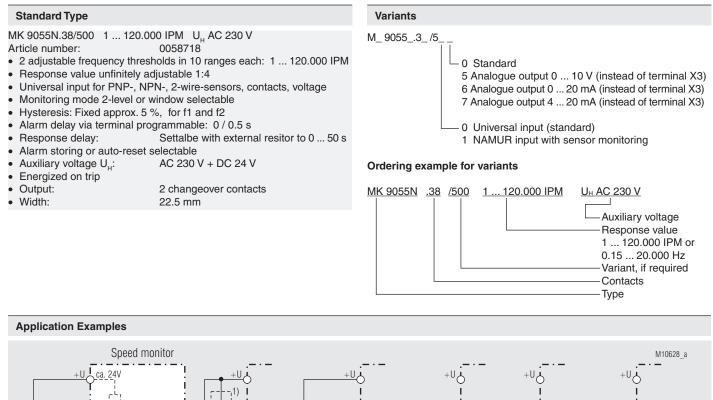
1 x 2.5 mm² stranded wire with sleeve

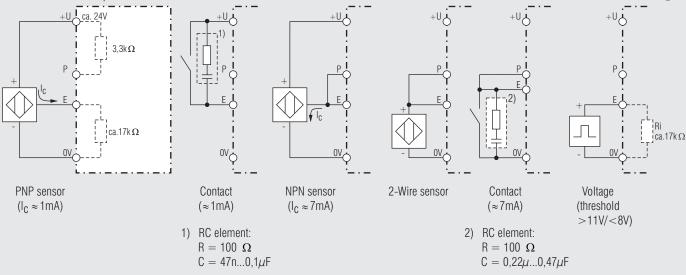
2 x 1.5 mm² stranded wire with sleeve

Plus-minus terminal screws M3,5 box terminals with wire protection

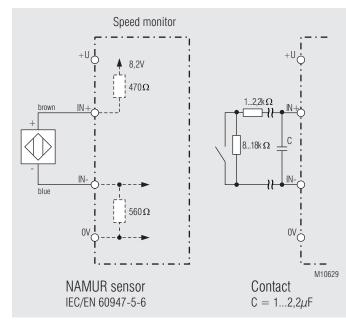
DIN 46 228-1/-2/-3/-4 oder

DIN 46 228-1/-2/-3/





Universal input



NAMUR input only at M_ 9055.3_/51_

Initiators (proximity sensors), inductive

Туре	NA 5001.01.10 pnp NA 5001.01.20 npn	NA 5002.01.34 pnp/npn	NA 5005.01.34 pnp/npn	NA 5010.01.10 pnp NA 5010.01.20 npn			
Dimensions	M8x1 SW13 M7266	49 60 65 M12 x 1 SW 17 M7267	45 60 68 M18 x 1 SW 24	49 60 M30 x 1,5 SW 36 M7269			
Enclosure	Metal	Metal	Metal	Metal			
Switching distance S _n	1 mm	2 mm	5 mm	10 mm			
Switching frequency	5 000 Hz	1 000 Hz	300 Hz	200 Hz			
Hysteresis	2 10 %						
Repeat accuracy	5 %						
Voltage range		10 30 V					
Residual ripple		< 10	1%				
Continuous current	≤ 200 mA	≤ 100 mA	≤ 100 mA	≤ 400 mA			
Output	.10 pnp NO	.34	.34	.10 pnp NO			
	.20 npn NO	pnp NO + npn NO	pnp NO + npn NO	.20 npn NO			
Indication of output state		LED					
Ambient temperature		- 25 70°C					
Temperature influence	10 %						
Degree of protection		IP 67					
Connection wire		2 r	n				
Fixing torque	4 Nm	15 Nm	40 Nm	100 Nm			
Weight	45 g	70 g	120 g	270 g			

Connection Table MK9055N.12/50x, MH9055.12/50x

Туре	Wire	Terminal on MK 9055N / MH 9055
	brown +	+ U
NA 5001.01.10	blue -	0 V
	black NO	E
	brown +	+ U
NA 5002.01.34	blanc +	+ U
NA 5005.01.34	blue -	0 V
	black NO	E
	brown +	+ U
NA 5010.01.10	blue -	0 V
	black NO	E

Connection Table MK9055N.12/50x, MH9055.12/50x

Туре	Wire	Terminal on MK 9055N / MH 9055
	brown +	+ U
NA 5001.01.20	blue -	0 V
	black NO	P, E
	brown +	+ U
NA 5002.01.34	blanc NO	P, E
NA 5005.01.34	blue -	0 V
	black -	0 V
	brown +	+ U
NA 5010.01.20	blue -	0 V
	black NO	P, E

E. DOLD & SÖHNE KG • D-78114 Furtwangen • Postfach 1251 • Telefon 0 77 23 / 654-0 • Telefax 0 77 23 / 654-356

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