

Comp-AC

User's Manual
for type ACS 100
frequency converters
from 0.12 to 2.2 kW



ACS 100 Frequency Converter

User's Manual

3BFE 64307622 R0125
EN
Effective: 8.3.2000

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Safety



Warning! Only a competent electrician may install the ACS 100.



Warning! Dangerous voltages are present when mains supply is connected. Wait at least 5 minutes after disconnecting the supply before removing the cover. Measure the voltage at DC terminals (U_{C+} , U_{C-}) before servicing the unit (see G).



Warning! Even when the motor is stopped there are dangerous voltages present at Power Circuit terminals U1, V1, W1 (L,N) and U2, V2, W2 and U_{C+} , U_{C-} .



Warning! Even when the ACS 100 is powered down, there may be dangerous external voltages at relay terminals RO1, RO2, RO3.



Warning! The ACS 100 is not a field repairable unit. Never attempt to repair a broken unit; contact the supplier for replacement of the unit.



Warning! The ACS 100 will start up automatically after an input voltage interruption if the external run command is on.



Warning! When the control terminals of two or more ACS100 / 140 / 400 units are connected in parallel, the auxiliary voltage for these control connections must be taken from a single source which can either be one of the units or an external supply.



Warning! Altering the parameter settings or device configurations will affect the function and performance of the ACS 100. Check that these changes do not cause any risk to persons or property.



Warning! The heat sink may reach a high temperature (see S).

Note! For more technical information, contact the supplier.

Table of Contents

Safety	i
Installation	1
Reference Sections	2
Environmental Limits	2
Dimensions (mm)	2
Installing the ACS 100	3
Removing the Cover.....	6
Attaching a Warning Sticker	6
Cable Connections	6
Terminal Interface	7
Type Designation Label and Code Key	8
Floating Network	8
Motor	8
Control Terminals	9
Configuration Switch	10
Connection Examples	11
Replacing the Cover.....	11
Power On	12
Protection Features.....	12
Motor Overload Protection	13
Loadability of ACS 100.....	13
Type Series and Technical Data	14
Product Conformity.....	17
Environmental Information	17
Accessories	18
Programming	19
Control Panel	19
Control Modes	19
Output Display	20
Menu Structure.....	20
Setting Parameter Value	20
Menu Functions.....	21
Diagnostic Displays	21
Resetting the Drive.....	22
ACS 100 Parameter Table	23
Group 01: Actual Values and Status	25
Group 02: Motor Values and Limits.....	25
Group 03: Drive Control	26
Group 04: Input/Output.....	27
Group 05: Supervision.....	28

Diagnostics	31
General	31
Alarm and Fault displays	31
Fault Resetting	31
ACS 100 EMC Instructions.....	35

Installation

Study this manual carefully before proceeding. Failure to observe the warnings and instructions given may cause a malfunction or personal hazard.

- 1 CHECK the environment. See **A**
- 2 INSTALL the ACS 100. See **B, C**
- 3 REMOVE the cover. See **D**
- 4 ATTACH a warning sticker in the language of your choice. See **E**
- 5 IDENTIFY power and control terminals. See **F, G, K**
- 6 CHECK voltage supply. See **H, I**
- 7 CHECK the motor. See **J**
- 8 CHECK configuration switch S1. See **L**
- 9 CONNECT power terminals. See **F, G**
- 10 CONNECT control wires. See **G, K, M**
- 11 REPLACE the cover. See **N**
- 12 TURN the power on. See **O**

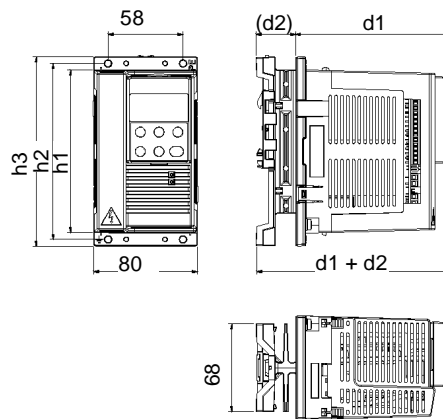
Reference Sections

A Environmental Limits

- Ambient operating temperature 0 - 40 °C (0 - 30 °C if $f_{sw} = 16$ kHz)
- Max. ambient temperature 50 °C if P_N and I_2 derated to 80 % and $f_{sw} = 4$ kHz
- Installation altitude 0 - 1000 m if P_N and I_2 100 %
- Installation altitude 0 - 2000 m if P_N and I_2 derated 1 % every 100 m above 1000 m.
- Relative humidity less than 95 % (non-condensing)
- Storage temperature -40 °C - 70 °C
- Transport temperature -40 °C - 70 °C


The ACS 100 should be installed in clean and dry air, free from dripping water, corrosive materials and electrically conductive dust (pollution degree 2). The installation room must be locked or tool-openable.

B Dimensions (mm)



Frame Size IP 20	200 V Series						Weight (kg)	
	h1	h2	h3	d1	(d2)	d1+d2	1~	3~
A	126	136	146	117	32	149	0.9	0.8
B	126	136	146	117	69	186	1.2	1.1
C	198	208	218	117	52	169	1.6	1.5
D	225	235	245	124	52	176	1.9	1.8
H	126	136	146	119	0	119	0.8	-

C Installing the ACS 100

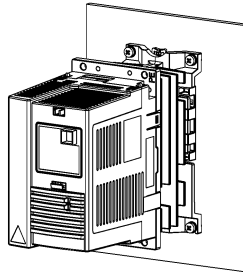
 **Warning!** Before installing the ACS 100 ensure that the mains supply to the installation is off.

Standard Series (Frame sizes A, B, C and D)

Install the ACS 100 vertically. Leave 25 mm free space above and below the unit. Ensure that there is sufficient cool air in the cabinet to compensate for the power losses (power and control circuits) listed at the end of section **S**, "Technical Data".

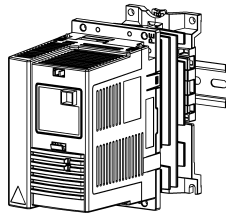
Wall mounting

Use M4 screws



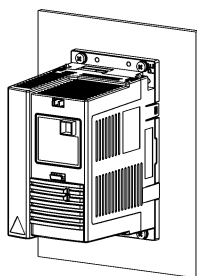
DIN rail (35 mm)

Press the lever on top of the unit while installing on / removing from DIN rail.



Flange mounting

The ACS 100 can be installed so that the heat sink is in an air duct. The power circuit losses will then be dissipated outside leaving only the control circuit losses to be dissipated inside (see **S**).



Heatsinkless series (Frame size H)

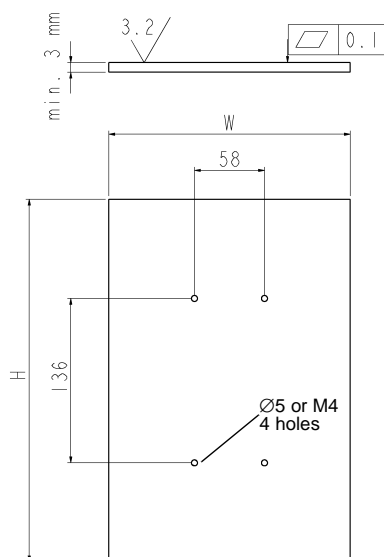


Note! The frame size H **does not include the heatsink**. The heatsinkless ACS 100 is intended for applications where an external heatsink is available. Ensure that the area of installation fulfils the heat dissipation requirements.

Mounting Surface Requirements

Install the heatsinkless ACS 100 on an uncoated, clean metallic surface that fulfils the following requirements:

- A minimum thickness of 3 mm.
- The surface must be stiff and flat. (max. flatness error 0.1 and max. roughness R_a 3.2 μm)



Heat Dissipation Requirements

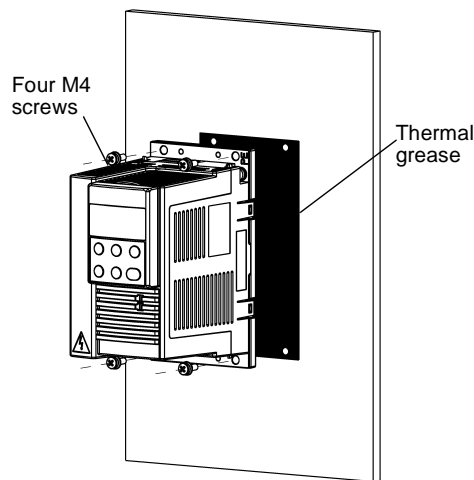
Ensure that the mounting surface is capable of conducting power losses into the environment. The maximum temperature of the mounting plate may not exceed 80 °C under any circumstances.

The table below gives the power losses and minimum surface area requirements, when a 3 mm steel plate, capable of dissipating heat from both sides, is used as a heatsink (max. ambient temperature 40 °C). The 3 mm steel plate is only one example, any kind of external heatsink can be used if it meets the mounting surface and heat dissipation requirements.

Converter Type	Power Loss (W)	Minimum Area H x W (mm x mm)
ACS 101-H18-1	7	150 x 150
ACS 101-H25-1	10	180 x 180
ACS 101-H37-1	12	200 x 200
ACS 101-H75-1	13	210 x 210
ACS 101-1H1-1	19	250 x 250
ACS 101-1H6-1	27	300 x 300

Mechanical Installation

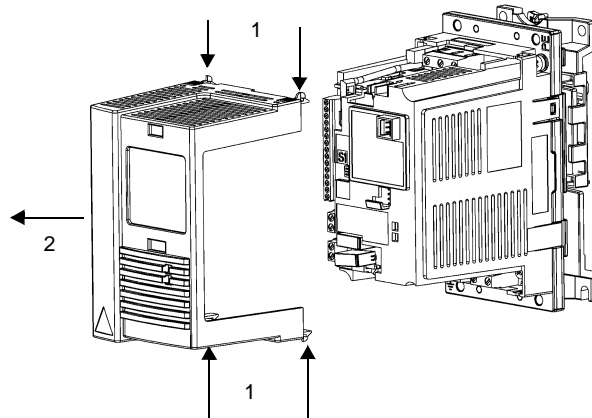
- Clean the mounting surface.
- Apply thermal grease between the ACS 100 and the mounting surface.
- Use M4 screws, mounting torque 1-1.5 Nm.



After installation, verify the thermal design by monitoring the temperature (parameter 104) of the ACS 100. The thermal design is successful if the ACS 100 temperature does not exceed 85 °C under full load and maximum ambient temperature.

D Removing the Cover


- 1 Press the four snap-on buttons on the top and bottom corners of the unit simultaneously.
- 2 Remove the cover.



E Attaching a Warning Sticker

The packing box includes warning stickers in different languages. Attach a warning sticker in the language of your choice to the place on the inside plastic skeleton as indicated, in section G, 'Terminal Interface'.

F Cable Connections

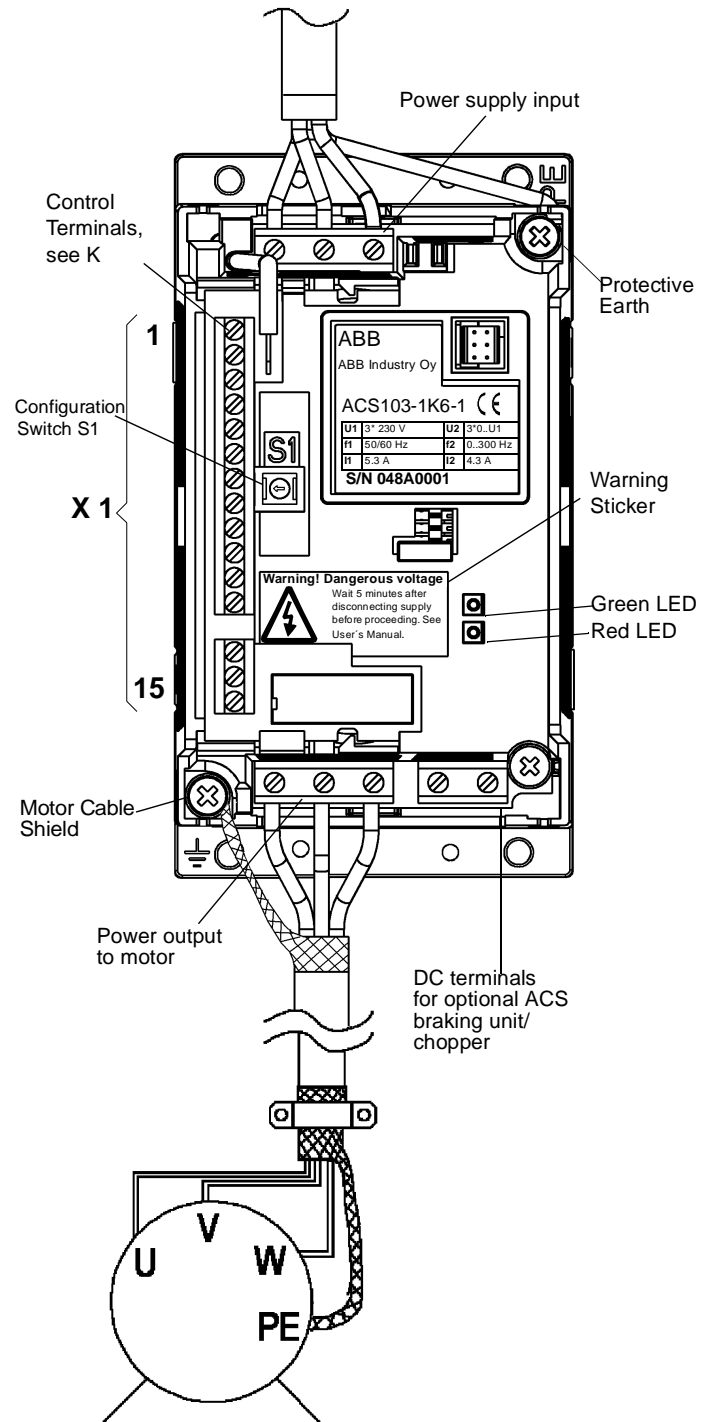
Terminal	Description	Note
L, N	1~ power supply input	In figure below (see G), a 3~ unit is shown.
U1, V1, W1	3~ power supply input	Do not use in 1~ supply!
PE	Protective Earth	Min. 4 mm ² Cu wire.
U2, V2, W2	Power output to motor	Max. cable length depends on the unit type (see S).
Uc+, Uc-	DC bus voltage 325 V	For optional ACS braking unit/chopper
	Motor cable shield	

Follow local rules for cable cross-sections. Use shielded motor cable. Route the motor cable away from control wires and the power supply cable to avoid electromagnetic interference.



Note! See EMC instructions on "ACS 100 EMC Instructions" on page 35.

G Terminal Interface



H Type Designation Label and Code Key

Supply:

ACS 101 = 1 ~

ACS 103 = 3 ~

Power:

1K6 = 1.6 kVA standard series (frames A, B, C and D)

1H6 = 1.6 kVA heatsinkless series (frame H)

ABB ABB Industry Oy			
ACS103-1K6-1			
U1	3* 230V	U2	3*0..U1
f1	50/60 Hz	f2	0..300 Hz
I1	5.3 A	I2	4.3 A
S/N 048A0001			

Serial number:

S/N 048A0001

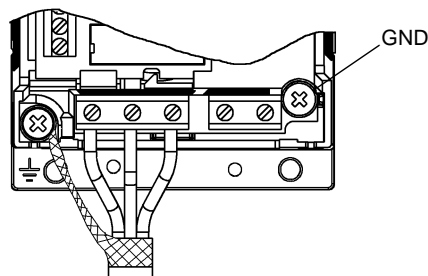
0= Year 2000

48 = Week 48

A0001=Internal number

I Floating Network

If the supply network is floating (IT network) remove the grounding screw (GND). Failure to do so may cause danger or damage the unit.



In floating networks do not use RFI filter. The mains becomes connected to earth through the filter capacitors. In floating networks this may cause danger or damage the unit.

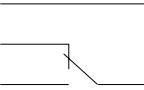
Make sure that no excessive emission is propagated to neighbouring low voltage networks. In some cases, the natural suppression in transformers and cables is sufficient. If in doubt, a supply transformer with static screening between the primary and secondary windings can be used.

J Motor

Check that the motor is compatible. The motor must be a three-phase induction motor, with U_N from 200 to 240 V and f_N either 50 Hz or 60 Hz. If the motor values differ from these, the group 02 parameter values must be changed.

The motor nominal current, I_N , must be less than or equal to the nominal output current of the ACS 100, I_2 (See **H** and **S**).

K Control Terminals

X1	Identification	Description
1	SCR	Terminal for signal cable screen. (Connected internally to frame earth.)
2	AI	Analogue input 0-10 V \Leftrightarrow 0- f_{nom} output frequency. $R_i = 190\text{ k}\Omega$ (0-10 V signal) / $500\text{ }\Omega$ (0-20 mA signal). Resolution 0.1 % accuracy $\pm 1\text{ %}$.
3	AGND	Analogue input circuit common. (Connected internally to frame earth through $1\text{ M}\Omega$.)
4	10 V	10 V reference voltage output for analogue input potentiometer, accuracy $\pm 2\text{ %}$, 10 mA.
5	AI	Analogue input AI can be configured to accept 0- 20 mA signal by shorting terminals 5 and 6. Then $R_i = 500\text{ }\Omega$.
6	AGND	Terminals for DI return wires.
7	AGND	
8	12 V	Aux. voltage output 12 V DC. $I_{max} = 100\text{ mA}$ (reference to AGND). Short circuit protected.
9	DCOM	Digital input common. To activate a digital input, there must be +12 V (or -12 V) between that input and DCOM. The 12 V may be provided by the ACS 100 (X1:8) as in the connection examples (see M) or from an external 12-24 V source of either polarity.
DI Configuration		<div> ABB Standard $(f_{nom} = 50\text{ Hz})$ $S1 = \{0;1;2;3;4\}$. See L </div> <div> 3-wire $(f_{nom} = 60\text{ Hz})$ $S1 = \{5;6;7;8;9\}$. See L </div>
10	DI 1	Start. Activate to start. Motor will ramp up to frequency reference. Disconnect to stop. Motor will coast to stop.
11	DI 2	Reverse. Activate to reverse rotation direction.
12	DI 3	Jog. Activate to set output frequency to constantspeed default 5 Hz, see parameter 406.
13	RO 1	 <div> Fault relay output Fault: RO 1 and RO 2 connected. 12 V-250 V AC/ 30 V DC 10 mA - 2 A </div>
14	RO 2	
15	RO 3	

DI configuration can be modified with parameter 405 or, if the control panel is not available, with configuration switch S1 (see **L**).

Digital input impedance $1.5\text{ k}\Omega$.

Use multi-strand $0.5\text{-}1.5\text{ mm}^2$ wire.

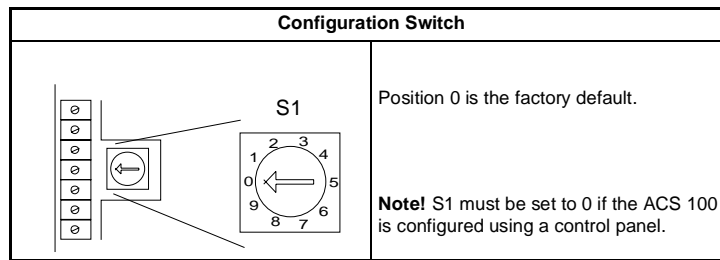
Note! For fail safe reasons the fault relay signals a "fault", when the ACS 100 is powered down.

L Configuration Switch

The ACS 100 can be configured by using a configuration switch or a control panel. **When the control panel is used, S1 must be set to 0.**

The position of the configuration switch S1 determines:

- the nominal frequency f_{nom} (set to motor f_N)
- the acceleration and deceleration ramp time
- the I/O configuration of digital inputs (See **M**)



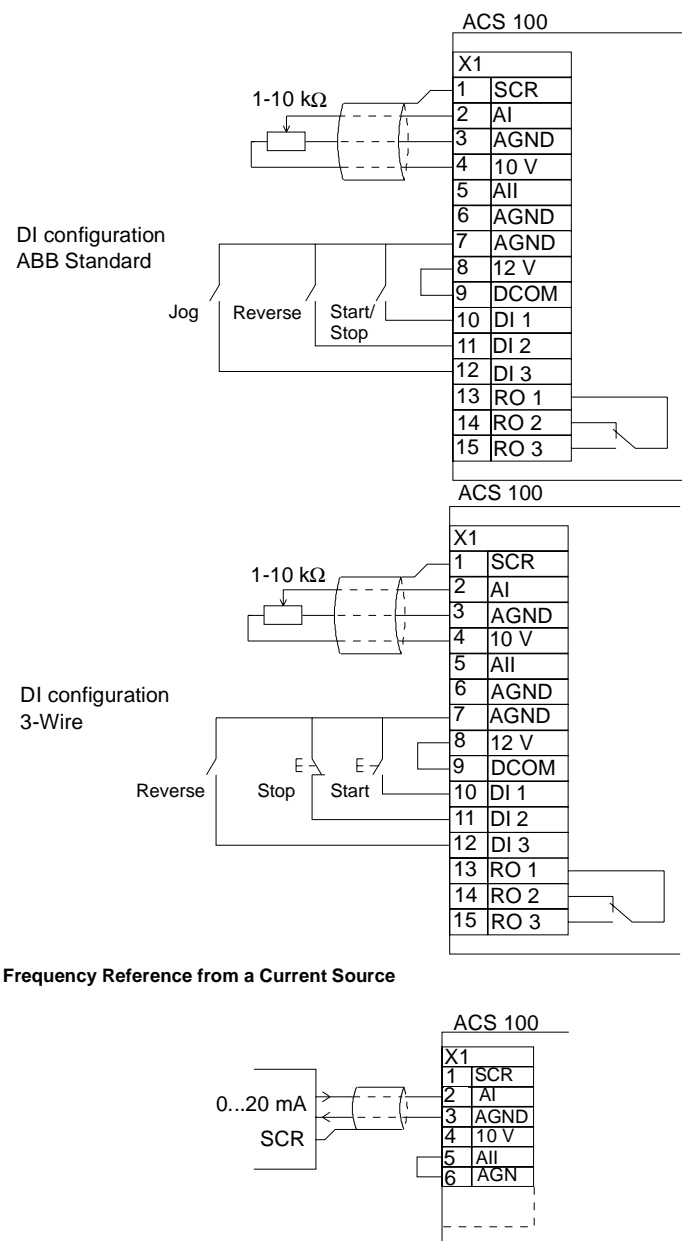
When setting the position of S1, first ascertain the motor nominal frequency f_N and then select the desired ramp time.

The configuration of digital inputs (DI) is dependent on the nominal frequency f_{nom} .

f_{nom}	Ramp Time 0 - f_{nom}	S1-position	DI Configuration
50 Hz	5 s	0	ABB standard
	1 s	1	
	10 s	2	
	30 s	3	
	60 s	4	
60 Hz	1 s	5	3-wire
	5 s	6	
	10 s	7	
	30 s	8	
	60 s	9	

Note! The ACS 100 reads the position of the configuration switch during power up. Never set S1 when the ACS 100 is powered on.

M Connection Examples



N Replacing the Cover

Do not turn the power on before replacing the cover back on.

O Power On

When power is supplied to the ACS 100, the green LED comes on.

P Protection Features

The ACS 100 has a number of protective features:

- Overcurrent
- Overvoltage
- Undervoltage
- Overtemperature
- Output earth fault
- Output short circuit
- Input phase loss (3~)
- Power loss ride through (500 ms)
- I/O terminal short circuit protection
- Long-term overcurrent limit trip 110 %
- Short-term current limit 150 %
- Motor overload protection (see Q)

The ACS 100 has the following LED alarm and fault indicators (for location of LED alarm indicators, see section G).

If the ACS 100-PAN control panel is connected, see “Diagnostics” on page 31.

Red LED: off Green LED: blinking	
ABNORMAL CONDITION: <ul style="list-style-type: none"> • ACS 100 cannot fully follow control commands. • Blinking lasts 15 seconds. 	POSSIBLE CAUSES: <ul style="list-style-type: none"> • Acceleration or deceleration ramp is too fast in relation to load torque requirement. • A short voltage interruption.

Red LED: on Green LED: on	
ACTION: <ul style="list-style-type: none"> • Give a stop signal to reset fault. • Give a start signal to restart the drive. NOTE: If the drive fails to start, check that the input voltage is within the tolerance range, (200...240 V \pm 10 %).	POSSIBLE CAUSES: <ul style="list-style-type: none"> • Transient overcurrent • Over-/undervoltage • Overtemperature CHECK: <ul style="list-style-type: none"> • the supply line for phase loss or disturbances. • the drive for mechanical problems that might cause overcurrent. • that heat sink is clean.

Red LED: blinking Green LED: on	
ACTION: <ul style="list-style-type: none"> • Turn the power off. • Wait for the LEDs to turn off. • Turn the power back on. Caution! This action may start the drive.	POSSIBLE CAUSE: <ul style="list-style-type: none"> • Output earth fault • Short circuit CHECK: <ul style="list-style-type: none"> • the isolations in the motor circuit.

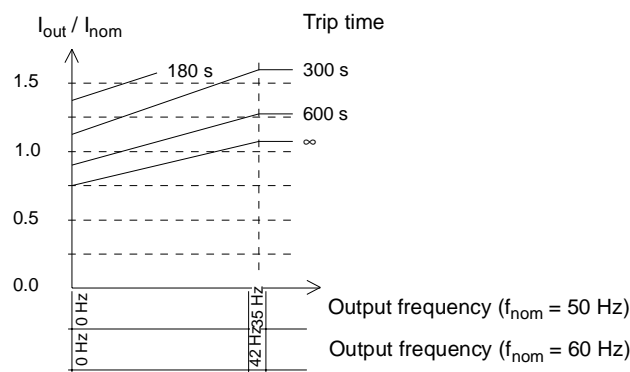
Note! Whenever the ACS 100 detects a fault condition, the fault relay activates. The motor will coast to stop and the ACS 100 will wait to be reset. If the fault still persists and no external cause has been identified, contact your ACS 100 supplier.

Q Motor Overload Protection

If the motor current I_{out} exceeds the nominal current I_{nom} of the motor (parameter 203) for a prolonged period of time, the ACS 100 automatically protects the motor from overheating by tripping.

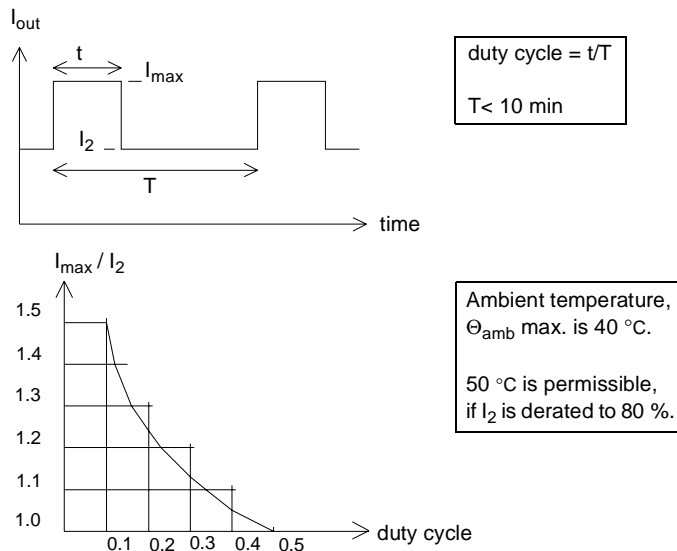
Trip time depends on the extent of the overload (I_{out} / I_{nom}), the output frequency and nominal motor frequency f_{nom} . Times given apply to a "cold start".

ACS 100 provides overload protection in accordance with the National Electric Code (US). The default setting of motor thermal protection is **ON**. For more information, see parameter 502 on page 28.



R Loadability of ACS 100

In the event of an output overload, the ACS 100 will trip.



S Type Series and Technical Data

Standard series						
Nominal motor P _N	kW	0.12	0.18	0.25	0.37	0.55
1~ Input	ACS101-	K18-1	K25-1	K37-1	K75-1	1K1-1
3~ Input	ACS103-	-	-	-	K75-1	1K1-1
Frame size		A				
Nominal Ratings (See H, P)	Unit					
Input voltage U ₁	V	200 V-240 V ±10 % 50/60 Hz (ACS 101: 1~, ACS 103: 3~)				
Continuous output current I ₂ (4 kHz)	A	1.0	1.4	1.7	2.2	3.0
Continuous output current I ₂ (8 kHz)	A	0.9	1.3	1.5	2.0	2.7
Continuous output current I ₂ (16 kHz)	A	0.8	1.1	1.3	1.7	2.3
Max. output current I _{2 max} (4 kHz)	A	1.5	2.1	2.6	3.3	4.5
Max. output current I _{2 max} (8 kHz)	A	1.4	2.0	2.3	3.0	4.1
Max. output current I _{2 max} (16 kHz)	A	1.1	1.5	1.9	2.4	3.3
Output voltage U ₂	V	0 - U ₁ 3~				
Input current I ₁ 1~	A	2.7	4.4	5.4	6.9	9.0
Input current I ₁ 3~	A	-	-	-	3.2	4.2
Switching frequency	kHz	4 (Standard) 8 (Low noise *) 16 (Silent **)				
Protection limits	(See P)					
Overcurrent (peak)	A	3.2	4.5	5.5	7.1	9.7
Overvoltage: Trip limit	V DC	420 (corresponds to 295 V input)				
Undervoltage: Trip limit	V DC	200 (corresponds to 142 V input)				
Overtemperature	°C	90 (heat sink)				
Max. wire sizes						
Max. motor cable length	m	50	50	50	75	75
Power terminals	mm ²	4 single core / Torque 0.8 Nm				
Control terminals	mm ²	0.5 - 1.5 (AWG22...AWG16) / Torque 0.4 Nm				
Line fuse 1~ ACS101- ***	A	6	6	10	10	10
Line fuse 3~ ACS103- ***	A	-	-	-	6	6
Power losses						
Power circuit	W	7	10	12	13	19
Control circuit	W	8	10	12	14	16

* Derate ambient temperature to 30 °C or derate P_N and I_2 to 90 % (see I_2 (8 kHz)).

** Derate ambient temperature to 30 °C and derate P_N and I_2 to 75 % (see I_2 (16 kHz)).

*** Fuse type: UL class CC or T. For non-UL installations IEC269 gG.

Use 60 °C rated power cable (75 °C if T_{amb} above 45 °C).

Standard series					
Nominal motor P _N	kW	0.75	1.1	1.5	2.2
1~ Input	ACS101-	1K6-1	2K1-1	2K7-1	4K1-1
3~ Input	ACS103-	1K6-1	2K1-1	2K7-1	4K1-1
Frame size		B	C		D
Nominal Ratings (See H, P)	Unit				
Input voltage U ₁	V	200 V-240 V ±10 % 50/60 Hz (ACS 101: 1~, ACS 103: 3~)			
Continuous output current I ₂ (4 kHz)	A	4.3	5.9	7.0	9.0
Continuous output current I ₂ (8 kHz)	A	3.9	5.3	6.3	8.1
Continuous output current I ₂ (16 kHz)	A	3.2	4.4	5.3	6.8
Max. output current I _{2 max} (4 kHz)	A	6.5	8.9	10.5	13.5
Max. output current I _{2 max} (8 kHz)	A	5.9	8.0	9.5	12.2
Max. output current I _{2 max} (16 kHz)	A	4.7	6.5	7.7	9.9
Output voltage U ₂	V	0 - U ₁ 3~			
Input current I ₁ 1~	A	10.8	14.8	18.2	22.0
Input current I ₁ 3~	A	5.3	7.2	8.9	12.0
Switching frequency	kHz	4 (Standard) 8 (Low noise *) 16 (Silent **)			
Protection limits	(See P)				
Overcurrent (peak)	A	13.8	19.0	23.5	34.5
Overvoltage: Trip limit	V DC	420 (corresponds to 295 V input)			
Undervoltage: Trip limit	V DC	200 (corresponds to 142 V input)			
Overtemperature	°C	90 (heat sink)	95 (heat sink)		
Max. wire sizes					
Max. motor cable length	m	75	75	75	75
Power terminals	mm ²	4 single core / Torque 0.8 Nm			
Control terminals	mm ²	0.5 - 1.5 (AWG22...AWG16) / Torque 0.4 Nm			
Line fuse 1~ ACS101- ***	A	16	16	20	25
Line fuse 3~ ACS103- ***	A	6	10	10	16
Power losses					
Power circuit	W	27	39	48	70
Control circuit	W	17	18	19	20

* Derate ambient temperature to 30 °C or derate P_N and I_2 to 90 % (see I_2 (8 kHz)).

** Derate ambient temperature to 30 °C and derate P_N and I_2 to 75 % (see I_2 (16 kHz)).

*** Fuse type: UL class CC or T. For non-UL installations IEC269 gG.

Use 60 °C rated power cable (75 °C if T_{amb} above 45 °C).

Heatsinkless series							
Nominal motor P _N	kW	0.12	0.18	0.25	0.37	0.55	0.75
1~ Input	ACS101-	H18-1	H25-1	H37-1	H75-1	1H1-1	1H6-1
Frame size		H					
Nominal ratings (See H, P)	Unit						
Input voltage U ₁	V	200V - 240V ±10 % 50/60 Hz (ACS 101:1~)					
Continuous output current I ₂ (4 kHz)	A	1.0	1.4	1.7	2.2	3.0	4.3
Continuous output current I ₂ (8 kHz)	A	0.9	1.3	1.5	2.0	2.7	3.9
Continuous output current I ₂ (16 kHz)	A	0.8	1.1	1.3	1.7	2.3	3.2
Max. output current I _{2 max} (4 kHz)	A	1.5	2.1	2.6	3.3	4.5	6.5
Max. output current I _{2 max} (8 kHz)	A	1.4	2.0	2.3	3.0	4.1	5.9
Max. output current I _{2 max} (16 kHz)	A	1.1	1.5	1.9	2.4	3.3	4.7
Output voltage U ₂	V	0 - U ₁ 3~					
Input current I ₁ 1~	A	2.7	4.4	5.4	6.9	9.0	10.8
Switching frequency	kHz	4 (Standard) 8 (Low noise *) 16 (Silent **)					
Protection limits	(See P)						
Overcurrent (peak)	A	3.2	4.5	5.5	7.1	9.7	13.8
Overvoltage: Trip limit	V DC	420 (corresponds to 295 V input)					
Undervoltage: Trip limit	V DC	200 (corresponds to 142 V input)					
Overtemperature	°C	90 (heat sink)					
Max. wire sizes							
Max. motor cable length	m	50	50	50	75	75	75
Power terminals	mm ²	4 single core / torque 0.8 Nm					
Control terminals	mm ²	0.5 - 1.5 (AWG22...AWG16) / torque 0.4 Nm					
Line fuse 1~ *** ACS101-	A	6	6	10	10	10	16
Power losses							
Power circuit	W	7	10	12	13	19	27
Control circuit	W	8	10	12	14	16	17

* Derate ambient temperature to 30 °C or derate P_N and I_2 to 90 % (see I_2 (8 kHz)).

** Derate ambient temperature to 30 °C and derate P_N and I_2 to 75 % (see I_2 (16 kHz)).

*** Fuse type: UL class CC or T. For non-UL installations IEC269 gG.

Use 60 °C rated power cable (75 °C if T_{amb} above 45 °C).

T Product Conformity

CE Marking

The ACS 100 complies with the requirements of the European

- Low Voltage Directive 73/23/EEC with amendments
- EMC Directive 89/336/EEC with amendments

Corresponding declarations and a list of main standards are available on request.



Note! See "ACS 100 EMC Instructions" on page 35

A frequency converter and a Complete Drive Module (CDM) or a Basic Drive Module (BDM), as defined in IEC 61800-2, is not considered as a safety related device mentioned in the Machinery Directive and related harmonised standards. The CDM/BDM/frequency converter can be considered as a part of safety device if the specific function of the CDM/BDM/frequency converter fulfils the requirements of the particular safety standard. The specific function of the CDM/BDM/frequency converter and the related safety standard is mentioned in the documentation of the equipment.

UL, ULc and C-Tick Markings

	Frame size	UL	ULc	C-Tick
ACS 100	A	pending	pending	pending
ACS 100	B	pending	pending	pending
ACS 100	C	pending	pending	pending
ACS 100	D	pending	pending	pending
ACS 100	H	pending	pending	pending

The ACS 100 is designed for use on a circuit capable of delivering no more than 65 kA.

U Environmental Information

A product to be disposed of contains valuable raw material that should be recycled, thus preserving energy and natural resources. Instructions for disposal are available from ABB sales and service companies.

V Accessories

PEC-98-0008

Panel Extension Cable kit for use with the ACS 100 / ACS 140 / ACS 400.

ACS 100/140-IFxx-1, ACS 100-FLT-

RFI input filters.

ACS-CHK-

Input/output chokes.

ACS-BRK-

Braking units.

ACS-BRC-

Braking choppers.

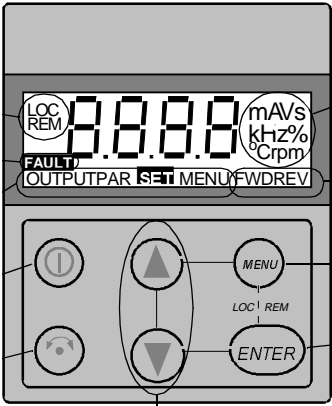
Programming

Control Panel

This section of the manual provides information on how to use the ACS 100-PAN control panel with an ACS 100 frequency converter.

The control panel can be connected to and detached from the converter at any time. The panel can be used to copy parameters to other ACS 100 with the same software revision (parameter 103).

When the control panel is powered up, the LCD display illuminates for one second. Immediately afterwards, the position of the configuration switch, S1, is displayed for one second, e.g. **CF 0**, when S1 = 0.



Control Modes

The very first time the drive is powered up, it is controlled from terminal X1 (remote control, **REM**). The ACS 100 is controlled from the control panel when the drive is in local control (**LOC**).

Switch to local control (**LOC**) by pressing and holding the MENU and ENTER buttons down simultaneously until first **Loc** or later **LCr** is displayed:

- If the buttons are released while **Loc** is displayed, the panel frequency reference is set to the current external reference and the drive is stopped.
- When **LCr** is displayed, the current run/stop status and the frequency reference are copied from the user I/O.

Start and stop the drive by pressing the START/STOP button.

Change the shaft direction by pressing the REVERSE button.

Switch back to remote control (**REM**) by pressing and holding the MENU and ENTER buttons down simultaneously until **rE** is displayed.

Shaft Direction

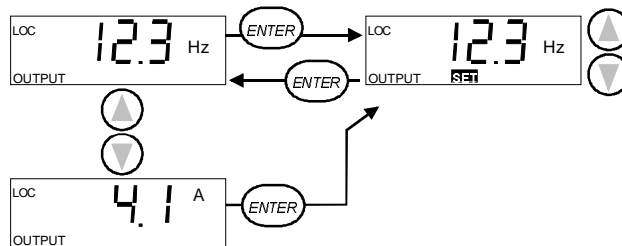
FWD / REV Visible	<ul style="list-style-type: none">• Shaft direction is forward / reverse• Drive is running and at set point
FWD / REV Blinking rapidly	Drive is accelerating / decelerating.
FWD / REV Blinking slowly	Drive is stopped.

Output Display

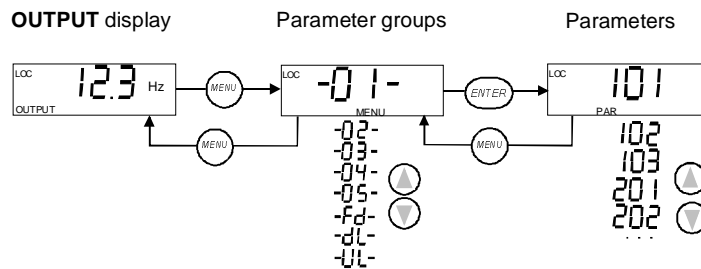
When the control panel is powered up, the panel displays the actual output frequency. Whenever the MENU button is pressed and held, the control panel resumes this **OUTPUT** display.

To toggle between output frequency and output current, press the UP or DOWN button.

To set the output frequency in local control mode (**LOC**), press ENTER. Pressing the UP/DOWN buttons changes the output immediately. Press ENTER again to return to **OUTPUT** display.



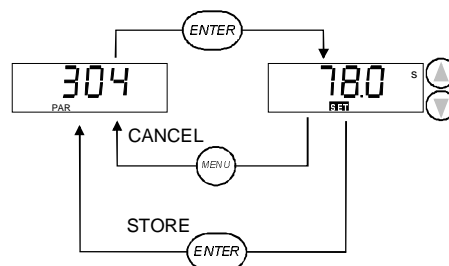
Menu Structure



Setting Parameter Value

Press ENTER to view the parameter value.

To set a new value, press and hold ENTER until **SET** is displayed.



Note! **SET** blinks, if the parameter value is altered. **SET** is not displayed, if the value cannot be altered.

Note! To view the parameter default value press UP/DOWN buttons simultaneously.

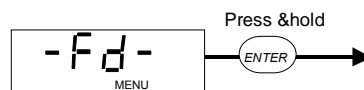
Menu Functions

Scroll the Parameter groups for the desired Menu Function. Press and hold ENTER until the display blinks to start the function.

Note! Factory default settings and parameter copying does not affect all parameters. The excluded parameters are: 201 (Nom Volt), 202 (Nom Freq), 203 (Nom Curr), 204 (Nom Speed), and 503 (Param Lock). See ACS 100 Parameter Table for a description of these parameters.

Note! Drive must be stopped and in local control. The configuration switch, S1, must be set to 0. Parameter 503 (Param Lock) must be set to 1.

Restore factory defaults



Parameter 503 (Param Lock) can also be set to 2.

Copy parameters from panel to drive (download)



Copy parameters from drive to panel (upload)

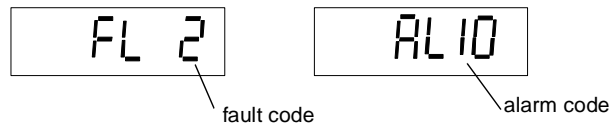


Diagnostic Displays

When the red LED of the ACS 100 is on or blinking, a fault is active. The relevant fault message flashes in the panel display.

When the green LED of the ACS 100 is blinking, an alarm is active. The relevant alarm message is shown in the panel display. Alarms 1-6 arise from button operation and green LED does not blink for them.

The alarm and fault messages disappear by pressing MENU, ENTER or the arrow buttons of the control panel. The message will reappear after a few seconds if the keypad is not touched and alarm or fault is still active



Refer to Diagnostics section for complete list of alarms and faults.

Resetting the Drive

When the red LED of the ACS 100 is on or blinking, there is an active fault.

To reset a fault when the red LED is on, press the START/STOP button.

Caution! When in remote control, this may start the drive.

To reset a fault when the red LED is blinking, turn the power off.

Caution! Turning the power on again may start the drive immediately.

The relevant fault code (see Diagnostics) flashes in the panel display until the fault is reset or the display is "cleared".

You can "clear" the display without resetting the fault by pressing any button.

The word FAULT will be visible in the display.

Note! If no other button is pressed within 15 seconds and the fault is still active, the fault code will be displayed again.

After a power failure, the drive will be in the same control mode (**LOC** or **REM**) as before the power failure.

ACS 100 Parameter Table

S = Value can be modified only when Configuration switch, S1 = 0.

N = Not changeable when start is active.

Code	Name	Min.	Max.	Resolution	Default	User	S	N
Group 01								
ACTUAL VALUES AND STATUS								
101	Ref Freq	0 Hz	300 Hz	0.1 Hz	-			
102	Last Fault	-	-	-	0			
103	Version	0.0.0.0	9.9.9.F	-	-			
104	Temp	0 °C	150 °C	0.1 °C	-			
Group 02								
MOTOR VALUES AND LIMITS								
201	Nom Volt	200 V	240 V	200, 208, 220, 230, 240 V	230 V			✓
202	Nom Freq	50 Hz	300 Hz	1 Hz	50 Hz		✓	✓
203	Nom Curr	0.5 x I ₂	1.5 x I ₂	0.1 A	I ₂			✓
204	Nom Speed	0 rpm	3600 rpm	1 rpm	1440 rpm			✓
205	Max Curr	0.5 x I ₂	1.5 x I ₂	0.1 A	1.5*I ₂			
206	Max Freq	0 Hz	300 Hz	1 Hz	50 Hz		✓	✓
207	Min Freq	0 Hz	300 Hz	1 Hz	0 Hz			
208	Dir Lock	1	2	-	1			
209	Motor Noise	0	2	-	0			✓
Group 03								
DRIVE CONTROL								
301	Stop	1	2	-	1			
302	Ramp	0	3	-	0			
303	Acc	0.1 s	1800 s	0.1 s; 1.0 s	5.0 s		✓	
304	Dec	0.1 s	1800 s	0.1 s; 1.0 s	5.0 s		✓	
305	U/f Ratio	1	2	-	1			✓
306	IR Comp	0 V	30 V	1 V	10 V			
307	DC Inj Time	0 s	250 s	0.1 s; 1.0 s	0.0 s			
308	UC _{max} Control	0	1	-	1			
Group 04:								
INPUT/ OUTPUT								
401	AI min	0 %	100 %	1 %	0 %			
402	AI max	0 %	100 %	1 %	100 %			
403	Ref min	0 Hz	300 Hz	1 Hz	0 Hz			
404	Ref max	0 Hz	300 Hz	1 Hz	50 Hz		✓	
405	DI Config	1	3	-	1		✓	✓
406	Const Speed	0 Hz	300 Hz	0.1 Hz	5 Hz			
Group 05:								
SUPERVISION								
501	AI Fault	0	1	-	0			
502	Freq Lim	0 Hz	300 Hz	1 Hz	35 Hz		✓	
503	Param Lock	0	2	-	1			
504	Start Inhibit	0	1	-	1			

Code	Name	Min.	Max.	Resolution	Default	User	S	N
505	Auto Reset	0 s	3 s	0.1 s	0 s			
506	Display Alarms	0	1	-	0			

Group 01: Actual Values and Status

Code	Description
101	Ref Freq Reference frequency.
102	Last Fault Fault memory. 0 = no fault in memory. Clear the fault memory by pressing the UP/DOWN buttons simultaneously in parameter SET mode.
103	Version Software version number.
104	Temp Displays the temperature of the ACS 100 heatsink in degrees centigrade.

Group 02: Motor Values and Limits

Code	Description
201	Nom Volt (U_{nom}) Nominal motor voltage from motor rating plate. Nom Volt sets the maximum output voltage supplied to motor by ACS 100. Nom Freq sets the frequency at which output voltage is equal to the Nom Volt. The ACS 100 cannot supply the motor with a voltage greater than the mains voltage. See figure 3.
202	Nom Freq (f_{nom}) Nominal motor frequency from motor rating plate (field weakening point). See Figure 3.
203	Nom Curr (I_{nom}) Nominal motor current from the motor rating plate. Note! This parameter is used only when motor thermal protection function is used. Refer to parameter 502 (Freq Lim). See Figure 5.
204	Nom Speed Nominal motor speed from motor rating plate.
205	Max Curr Maximum output current the ACS 100 will supply to motor.
206	Max Freq (f_{max}) Maximum frequency the ACS 100 will supply to motor.
207	Min Freq (f_{min}) Minimum frequency the ACS 100 will supply to motor. Note! Keep $f_{min} < f_{max}$.
<p><i>Figure 1 Usage of f_{min} and f_{max} to limit output frequency.</i></p> <p>The graph plots Output frequency on the y-axis against f_{ref} on the x-axis. The frequency starts at a constant value f_{min} for f_{ref} values from 0 up to a point marked f_{min} on the x-axis. From this point, the frequency increases linearly until it reaches f_{max} at a point marked f_{max} on the x-axis. For f_{ref} values greater than f_{max}, the frequency remains constant at f_{max}.</p>	
208	Dir Lock Direction lock Reverse can be disabled. 1 = FWD / REV 2 = FWD only
209	Motor Noise Motor noise control. 0 = standard (switching frequency 4 kHz) 1 = low noise (switching frequency 8 kHz) 2 = silent (switching frequency 16 kHz) Note! When the low noise (8 kHz) setting is used, the maximum loadability of the ACS 100 is I_2 at 30 °C ambient temperature or $0.9 \cdot I_2$ at 40 °C. When the silent (16 kHz) setting is used, the maximum loadability is $0.75 \cdot I_2$ at 30 °C ambient temperature.

Group 03: Drive Control

Code	Description	
301	Stop Stop mode. 1 = Coast 2 = Ramp See also parameter 307 (DC Inj. Time).	
302	Ramp Ramp shape. 0 = Linear 1 = Fast S curve 2 = Medium S curve 3 = Slow S curve	<i>Figure 2</i>
303	Acc Acceleration time from zero to maximum frequency ($0 - f_{\max}$).	
304	Dec Deceleration time from maximum frequency to zero ($f_{\max} - 0$).	
305	U/f Ratio U/f below weakening point. 1 = Linear (curves A and C) 2 = Square (curves B and D) Linear is preferred for constant torque applications and Square for centrifugal pump and fan applications.	<i>Figure 3</i>
306	IR Comp Amount of IR compensation, i.e. extra voltage applied to motor on frequency range $0 - f_{\text{nom}}$. Note! IR compensation should be kept as low as possible.	
307	DC Inj Time DC injection time after modulation has stopped. If stop mode is Coast, ACS 100 uses DC Braking. If stop mode is Ramp, ACS 100 uses DC Hold after ramp.	
308	UC_{max} Overvoltage regulator control. Should be 0, if braking chopper is connected. 0 = No overvoltage control 1 = Overvoltage control enabled	

Group 04: Input/Output

Code	Description																															
401	AI min Analogue input scaling. 0 % equals 0 mA (or 0 V) and 100 % equals 20 mA (or 10 V) at input.	<p>Figure 4a</p>																														
402	AI max Analogue input scaling. 0 % equals 0 mA (or 0 V) and 100 % equals 20 mA (or 10 V) at input. Note! Keep AI min<AI max																															
403	Ref min Reference value for analogue input scaling.	<p>Figure 4b</p>																														
404	Ref max Reference value for analogue input scaling.																															
405	DI Config Digital input configuration. 1 = ABB Standard 2 = 3-wire 3 = Alternate Note! After modifications, turn the power off and then on again to validate changes.	<p>Table 1 DI configurations.</p> <table><tr><th rowspan="2">ABB Standard</th><th colspan="2">Function</th></tr><tr><th>activated</th><th>deactivated</th></tr><tr><td>DI 1</td><td>start</td><td>stop</td></tr><tr><td>DI 2</td><td>reverse</td><td>forward</td></tr><tr><td>DI 3</td><td>parameter 406 (Const speed) is f_{ref}</td><td>analogue input is f_{ref}</td></tr></table>	ABB Standard	Function		activated	deactivated	DI 1	start	stop	DI 2	reverse	forward	DI 3	parameter 406 (Const speed) is f_{ref}	analogue input is f_{ref}																
ABB Standard	Function																															
	activated	deactivated																														
DI 1	start	stop																														
DI 2	reverse	forward																														
DI 3	parameter 406 (Const speed) is f_{ref}	analogue input is f_{ref}																														
406	Const speed Constant speed. Can be actuated from digital input. See Table 1.	<table><tr><th colspan="3">3-Wire</th><th>Function</th></tr><tr><td>DI 1</td><td colspan="2">Momentary activation with DI2 activated: start</td><td></td></tr><tr><td>DI 2</td><td colspan="2">Momentary deactivation: stop</td><td></td></tr><tr><td>DI 3</td><td colspan="2">When activated: reverse direction When deactivated: forward direction</td><td></td></tr></table> <table><tr><th rowspan="2">Alternate</th><th colspan="2">Function</th></tr><tr><th>activated</th><th>deactivated</th></tr><tr><td>DI 1</td><td>start forward</td><td>stop, if DI2 is also deactivated</td></tr><tr><td>DI 2</td><td>start reverse</td><td>stop, if DI1 is also deactivated</td></tr><tr><td>DI 3</td><td>parameter 406 (Const speed) is f_{ref}</td><td>analogue input is f_{ref}</td></tr></table> <p>Note! When Alternate is selected, the drive stops, if DI1 and DI2 are activated at the same time.</p>	3-Wire			Function	DI 1	Momentary activation with DI2 activated: start			DI 2	Momentary deactivation: stop			DI 3	When activated: reverse direction When deactivated: forward direction			Alternate	Function		activated	deactivated	DI 1	start forward	stop, if DI2 is also deactivated	DI 2	start reverse	stop, if DI1 is also deactivated	DI 3	parameter 406 (Const speed) is f_{ref}	analogue input is f_{ref}
3-Wire			Function																													
DI 1	Momentary activation with DI2 activated: start																															
DI 2	Momentary deactivation: stop																															
DI 3	When activated: reverse direction When deactivated: forward direction																															
Alternate	Function																															
	activated	deactivated																														
DI 1	start forward	stop, if DI2 is also deactivated																														
DI 2	start reverse	stop, if DI1 is also deactivated																														
DI 3	parameter 406 (Const speed) is f_{ref}	analogue input is f_{ref}																														

Group 05: Supervision

Code	Description
501	AI Fault Analogue input supervision. 0 = not in use 1 = If analogue input is below the level given by parameter 401 (AI min), a fault indication is displayed and the ACS 100 coasts to stop.
502	Freq Lim (f_{lim}) Frequency limit for thermal protection. Together with parameter 203 (Nom Curr) determines the continuous safe operation area for the motor. 0 Hz = Thermal protection disabled. <div style="display: flex; align-items: center;"> <div style="flex: 1;"> <p><i>Figure 5</i></p> </div> <div style="flex: 1; padding-left: 10px;"> <p>Trip time</p> <p>60 s</p> <p>90 s</p> <p>180 s</p> <p>300 s</p> <p>∞</p> </div> </div>
503	Param Lock Parameter lock. 0 = STAR/STOP and REVERSE buttons and parameter modification disabled. Parameter value viewing is allowed. 1 = Not locked. 2 = Modified values not stored in permanent memory.
504	Start Inhibit Start inhibit control. Start inhibit means that a pending start command is ignored when: <ul style="list-style-type: none"> • fault is reset, or • mode change from local to remote takes place. 0 = Off Start inhibit control disabled. Drive will start after fault is reset or mode is changed while there is a pending start command. 1 = On Start inhibit control is enabled. Drive will not start after fault is reset or mode is changed. In order to start the drive again, give start command anew.
505	Auto Reset The automatic reset system can be used for resetting undervoltage faults automatically. Auto reset sets the number of allowed auto resets (5) within a certain time (30 s). 0 s = Disable If a value greater than 0 s is selected, the undervoltage fault is reset automatically after the delay set by this parameter. If 0 s is selected, the fault is not reset automatically. <div style="text-align: center; margin: 10px 0;"> <p>x = Automatic reset</p> </div> <p><i>Figure 6 Operation of automatic reset function. The number of trials is constant 5 and the trial time is constant 30 s. By moment 'Now' three faults has occurred making the next fault fourth, the system is reset automatically because the number of trials is less than 5.</i></p>

506	Display Alarms Controls the visibility of some of the alarms, see "Diagnostics" on page 31. 0 = No Some of the alarms are suppressed. 1 = Yes All of the alarms are enabled.
-----	--

Diagnostics

General

This chapter describes the various diagnostic displays of the control panel and lists the most common causes for the particular display. If the fault cannot be resolved by the given instructions, contact an ABB service representative.

Caution! Do not attempt any measurement, parts replacement or other service procedures not described in this manual. Such actions will void guarantee, endanger correct operation, and increase downtime and expense.

Alarm and Fault displays

The seven-segment display unit of control panel indicates alarms and faults using codes "ALxx" or "FLxx", where xx is the corresponding alarm or fault code.

Alarms 1-6 arise from button operation. Green LED blinks for AL10-16, meaning that the ACS 100 cannot fully follow the control commands. The faults are indicated by red LED.

The alarm and fault messages disappear by pressing MENU, ENTER or the arrow buttons of the control panel. The message will reappear after a few seconds if the keypad is not touched and the alarm or fault is still active.

Last fault code is stored into parameter 102. This fault memory can be cleared from the control panel by pressing UP and DOWN buttons simultaneously in parameter set mode.

Fault Resetting

Faults that are indicated by a red blinking LED are reset by turning the power off for a while. Other faults (indicated by red static LED) can be reset either from the control panel, by digital input or serial communication, or switching the supply voltage off for a while. When the fault has been removed, the motor can be started.

The ACS 100 can be configured to automatically reset certain faults. Refer to parameter 505 AUTO RESET.

Warning! If an external source for start command is selected and is still active, the ACS 100 may start immediately after fault reset.

Warning! All electrical installation and maintenance work described in this chapter should only be undertaken by a qualified electrician. The Safety Instructions on the first pages of this manual must be followed.

Table 2 Alarms

Code	Description
CF 0 - CF 9	Position of configuration switch S1. Certain parameters can be modified only when S1 = 0.
AL 1	Parameter upload/download failed.
AL 2	Operation not allowed while start is active.
AL 3	Operation not allowed in remote or local control.
AL 4	REVERSE button disabled. Parameter 208 (Dir Lock) is active.
AL 5	Panel START button disabled. DI configuration is 3-wire and DI2 is open.
AL 6	Operation not allowed. Parameter 503 (Param Lock) is active.
AL10*	Overcurrent controller active.
AL11*	Overvoltage controller active.
AL12*	Undervoltage controller active.
AL13	Reserved. Contact supplier.
AL14	Reverse command attempted in remote control (REM), while parameter 208 (Dir Lock) is active.
AL15 - AL16	Reserved. Contact supplier.

Note! Alarms (*) will be shown only if parameter 506 is set to 1 (Yes).

Table 3 Faults

Code	Description
FL 1	Overcurrent: <ul style="list-style-type: none"> Possible mechanical problem. Acc and/or Dec times may be too small.
FL 2	DC overvoltage: <ul style="list-style-type: none"> Input voltage too high. Dec time may be too small.
FL 3	ACS 100 overtemperature: <ul style="list-style-type: none"> Ambient temperature too high. Severe overload.
FL 4 *	Fault current: output earth fault or short circuit.
FL 5	Output overload.
FL 6	DC undervoltage.
FL 7	Analogue input fault. (See parameter 501.)
FL 8	Motor overtemperature. (See parameter 502.)
FL 9	Panel disconnected from drive in local control. Note! If FL 9 is active when the power is turned off, the ACS 100 will start in remote control (REM) when the power is turned back on.
FL10	Parameters inconsistent. Check that AI min (f_{min}) is not greater than AI max (f_{max}).
FL11 *	DC bus ripple too large. Check supply.
FL12	Reserved. Contact supplier.
FL13 - FL14*	Hardware error. Contact supplier.
FL15*	Analogue input out of range. Check AI level.
FL16-FL19*	Hardware error. Contact supplier.
Full display blinking	Serial link failure. Bad connection between the control panel and the ACS 100.

Note! Faults (*) with red blinking LED are reset by turning the power off and on. Other faults are reset by pressing the START/STOP button.

ACS 100 EMC Instructions

Mandatory Installation Instruction According to the EMC Directive for type ACS 100 frequency converters

Follow the instructions given in the ACS 100 User's Manual and the instructions delivered with different accessories.

CE Marking

A CE mark is attached to ACS 100 frequency converters to verify that the unit follows the provisions of the European Low Voltage and EMC Directives (Directive 73/23/EEC, as amended by 93/68/EEC and Directive 89/336/EEC, as amended by 93/68/EEC).

The EMC Directive defines the requirements for immunity and emissions of electrical equipment used in European Economic Area. The EMC product standard EN 61800-3 covers the requirements stated for frequency converters. ACS 100 frequency converters comply with the requirements stated in EN 61800-3 for Second Environment and First Environment.

Product standard EN 61800-3 (Adjustable speed electrical power drive systems - Part 3: EMC product standard including specific test methods) defines **First Environment** as environment that includes domestic premises. It also includes establishments directly connected without intermediate transformers to a low voltage power supply network which supplies buildings used for domestic purposes. **Second Environment** includes establishments other than those directly connected to a low voltage power supply network which supplies buildings used for domestic purposes. With ACS 100, no RFI filter is needed in Second Environment.

C-Tick Marking (pending)

A C-tick mark is attached to 1-phase ACS 100 frequency converters to verify that the unit follows the provisions of the Australian Statutory Rules No 294, 1996, Radiocommunication (Compliance Labelling - Incidental Emissions) Notice and the Radiocommunication Act, 1989, and the Radiocommunication Regulations, 1993, of New Zealand.

The statutory rules defines the essential requirements for emissions of electrical equipment used in Australia and New Zealand. The standard AS/NZS 2064, 1997, Limits and methods of measurement of electronic disturbance characteristics of industrial, scientific and medical (ISM) radiofrequency equipment, covers the detailed requirements for a frequency converter.

The frequency converter ACS 100 complies with the AS/NZS 2064, 1997, limits for class A equipment. Class A equipment is suitable for use in all establishments other than domestic and those directly connected to a low voltage network which supplies buildings used for domestic purposes. The compliance is valid with the following provisions:

- The frequency converter is equipped with RFI-filter.
- The motor and control cables are chosen as specified in this manual for use in public low-voltage network.
- The installation rules of this manual are followed.

Cabling Instructions

Keep individual unscreened wires between the cable clamps and the screw terminals as short as possible. Route control cables away from power cables.

Mains Cable

A three conductor cable (single phase and neutral with protective earth) or four conductor cable (three phase with protective earth) are recommended for the mains cabling. Shielding is not necessary. Dimension the cables and fuses in accordance with the input current. Always pay attention to local legislation when sizing the cables and fuses.

The mains input connectors are at the top of the converter unit. Mains cable routing must be done so that the distance from the sides of the converter is at least 20 cm to avoid excessive radiation to the mains cable. In the case of screened cable twist the cable screen wires together into a bundle not longer than five times its width and connect to the PE terminal of the converter. (Or PE terminal of input filter, if present.)

Motor Cable

The motor cable must be a symmetrical three conductor cable with a concentric PE conductor or a four conductor cable with a concentric shield. Minimum requirement for the motor cable screen is presented in Figure 7.

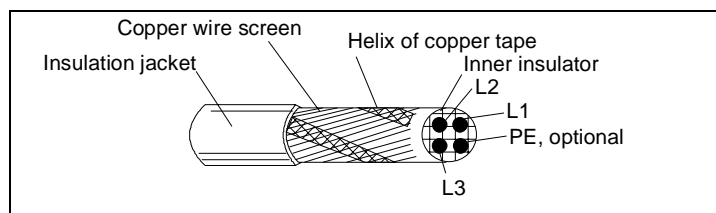


Figure 7 Minimum requirement for motor cable screen (e.g. MCMK, NK Cables).

The general rule for cable screen effectiveness is: the better and tighter the screen of the cable, the lower the radiated emission level. Example of an effective construction is presented in Figure 8.

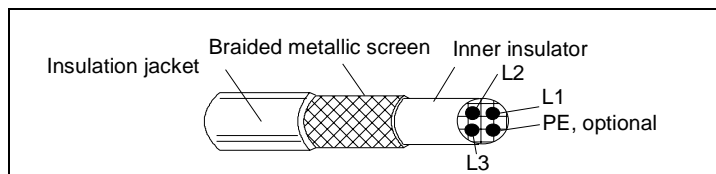


Figure 8 Effective motor cable screen (e.g. Ölflex-Servo-FD 780 CP, Lappkabel or MCMK, NK Cables).

Twist the cable screen wires together into a bundle not longer than five times its width and connect to the bottom left-hand corner of the converter heatsink (terminal marked \perp).

At the motor end the motor cable screen must be earthed 360 degrees with an EMC cable gland (e.g. ZEMREX SCG Screened cable glands) or the screen wires must be twisted together into a bundle not longer than five times its width and connected to the PE terminal of the motor.

Control Cables

Control cables must be multi-core cables with a braided copper wire screen.

The screen must be twisted together into a bundle not longer than five times its width and connected to terminal X1:1.

Route the control cables as far away as possible from the mains and motor cables (at least 20 cm). Where control cables must cross power cables make sure they are at an angle as near 90 degrees as possible. Also the cable routing must be done so that the distance from the sides of the converter is at least 20 cm to avoid excessive radiation to the cable.

A double shielded twisted pair cable is recommended for the analogue signals. Employ one individually shielded pair for each signal. Do not use common return for different analogue signals.

A double shielded cable is the best alternative for low voltage digital signals but single shielded twisted multipair cable is also usable (see Figure 9).

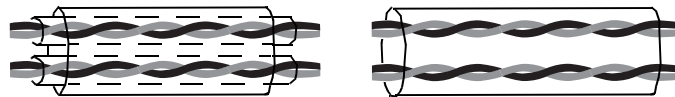


Figure 9 A double shielded twisted pair cable on the left and a single shielded twisted multipair cable on the right.

The analogue and digital input signals should be run in separate, screened cables.

Relay-controlled signals, providing their voltage does not exceed 48 V, can be run in the same cables as digital input signals. It is recommended that the relay-controlled signals be run as twisted pairs.

Never mix 24 VDC and 115/230 VAC signals in the same cable.

Note! When the overriding control equipment and the ACS 100 are installed inside the same cabinet, these recommendations might be overly cautious. If the customer plans to test the entire installation, there is an opportunity to save some costs by relaxing these recommendations, for example by using unshielded cable for the digital inputs. But the customer must verify this.

Control Panel Cable

If the control panel is connected to the converter with a cable, use only the cable provided with the option package ACS100-EXT or PEC-98-0008. Follow the instructions delivered with the option package.

Route the control panel cable as far away as possible from the mains and motor cables (at least 20 cm). Also the cable routing must be done so that the distance from the sides of the converter is at least 20 cm to avoid excessive radiation to the cable.

Additional Instructions to Comply with EN61800-3, First Environment, Restricted Distribution, and AS/ NZS 2064, 1997, Class A

Always use optional RFI filter as specified in Tables 4 and 5 and follow the instructions in the filter package for all cable screen connections.

The filters with regular cable lengths are shown in Table 4 and the filters with extra long cable lengths in Table 5.

The motor cable lengths have to be limited as specified in Tables 4 and 5. At the motor end, the cable screen must be earthed 360 degrees with an EMC cable gland (e.g. Zemrex SCG screened cable glands).

Table 4 Maximum motor cable lengths with input filter ACS100/140-IFAB-1 or -IFCD-1 and switching frequency 4 kHz, 8 kHz or 16 kHz.

Converter type	ACS100/140-IFAB-1		
	4 kHz	8 kHz	16 kHz
ACS 101-K18-1 ACS 101-H18-1	30 m	20 m	10 m
ACS 101-K25-1 ACS 101-H25-1	30 m	20 m	10 m
ACS 101-K37-1 ACS 101-H37-1	30 m	20 m	10 m
ACS 101-K75-1 ACS 101-H75-1	30 m	20 m	10 m
ACS 101-1K1-1 ACS 101-1H1-1	30 m	20 m	10 m
ACS 101-1K6-1 ACS 101-1H6-1	30 m	20 m	10 m
Converter type	ACS100/140-IFCD-1		
	4 kHz	8 kHz	16 kHz
ACS 101-2K1-1	30 m	20 m	10 m
ACS 101-2K7-1	30 m	20 m	10 m
ACS 101-4K1-1	30 m	20 m	10 m

Table 5 Maximum motor cable lengths with input filter ACS100-FLT-C or ACS 140- FLT-C and switching frequency 4 kHz or 8 kHz.

Converter Type	ACS100-FLT-C	
	4 kHz	8 kHz*
ACS 101-K75-1	100 m	100 m
ACS 101-1K1-1	100 m	100 m
ACS 101-1K6-1	100 m	100 m
ACS 101-2K-1	100 m	100 m
ACS 101-2K7-1	100 m	100 m
ACS 101-4K1-1	100 m	100 m
Converter Type	ACS140-FLT-C	
ACS 103-xKx-1**	100 m	100 m

* Effective motor cable screen is required, according to Figure 8.

**ACS 103-4K1-1: maximum continuous load 70 % of nominal.

For ACS 101-4K1-1 and ACS 103-4K1-1, a cable shown in Figure 8 is required.

Always use output choke ACS-CHK-B, if motor cable length exceeds 50 m.

With input filter ACS100-FLT-C always use output choke ACS-CHK-A.

Chokes ACS-CHK-A and ACS-CHK-B are supplied in the same package with the input filter ACS100-FLT-C.

With input filters ACS100-FLT-C or ACS140-FLT-C conducted emission complies with the limits for unrestricted distribution class in First Environment as specified in EN 61800-3 (EN 50081-1) provided that the motor cable has effective screen (see Figure 8) and maximum length is 30 m.

Additional Instructions to Comply with EN61800-3, First Environment, Unrestricted Distribution

Always use optional RFI filter ACS100-FLT-D or ACS100-FLT-E and follow the instructions in the filter package for all cable screen connections.

The motor cable lengths have to be limited as specified in Table 6 and the cable must have effective screen according to Figure 8. At the motor end, the cable screen must be earthed 360 degrees with an EMC cable gland (e.g. Zemrex SCG screened cable glands).

Table 6 Maximum motor cable lengths with input filter ACS100-FLT-D, -E or ACS140-FLT-D and switching frequency 4 kHz.

Converter type	ACS100-FLT-D	ACS100-FLT-E
	4 kHz	4 kHz
ACS 101-K75-1	5 m	-
ACS 101-1K1-1	5 m	-
ACS 101-1K6-1	5 m	-
ACS 101-2K1-1	-	5 m
ACS 101-2K7-1	-	5 m
ACS 101-4K1-1	-	5 m

Two chokes ACS-CHK-A or ACS-CHK-C are supplied in the filter package. The motor cable including the shield must be fed through the hole in the choke. Also all control cables and the control panel cable, if present, must be fed through another choke. The cable lengths between the converter and the chokes must be at maximum 50 cm.

For types ACS 101-2K1-1, ACS 101-2K7-1 and ACS 101-4K1-1 the control panel, if present, must be mounted on the converter front cover.

Line Current Harmonics

The product standard EN 61800-3 refers to IEC 61000-3-2 which specifies limits for harmonic current emissions for equipment connected to low voltage public supply network.

The ACS 100 is a professional equipment to be used in trades, professions, or industries and which is not intended for sale to the general public. The supply authorities shall be notified as authorisation may be required before connection.

The current harmonic levels under rated load conditions are available on request.

Distribution Networks Isolated from Earth

Input filters cannot be used in floating supply networks, or high impedance earthed industrial distribution networks.

Make sure that no excessive emission is propagated to neighbouring low voltage networks. In some cases, the natural suppression in transformers and cables is sufficient. If in doubt, a supply transformer with static screening between the primary and secondary windings can be used.



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